

# Operating Instructions

Radar sensor for continuous level  
measurement of liquids

## NCR-25

4 ... 20 mA/HART - four-wire



Document ID: 36504



***BINMASTER***®

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**Safety instructions for Ex areas**



Take note of the Ex specific safety instructions for Ex applications.  
These instructions are attached as documents to each instrument  
with Ex approval and are part of the operating instructions manual.

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# 1 About this document

## 1.1 Function

This operating instructions manual provides all the information you need for mounting, connection and setup as well as important instructions for maintenance and fault rectification. Please read this information before putting the instrument into operation and keep this manual accessible in the immediate vicinity of the device.

## 1.2 Target group

This operating instructions manual is directed to trained specialist personnel. The contents of this manual should be made available to these personnel and put into practice by them.

## 1.3 Symbols used



### Information, tip, note

This symbol indicates helpful additional information.



**Caution:** If this warning is ignored, faults or malfunctions can result.



**Warning:** If this warning is ignored, injury to persons and/or serious damage to the instrument can result.



**Danger:** If this warning is ignored, serious injury to persons and/or destruction of the instrument can result.



### Ex applications

This symbol indicates special instructions for Ex applications.



### List

The dot set in front indicates a list with no implied sequence.



### Action

This arrow indicates a single action.



### Sequence of actions

Numbers set in front indicate successive steps in a procedure.



### Battery disposal

This symbol indicates special information about the disposal of batteries and accumulators.

## 2 For your safety

### 2.1 Authorised personnel

All operations described in this operating instructions manual must be carried out only by trained specialist personnel authorised by the plant operator.

During work on and with the device the required personal protective equipment must always be worn.

### 2.2 Appropriate use

VEGAPULS 62 is a sensor for continuous level measurement.

You can find detailed information about the area of application in chapter "*Product description*".

Operational reliability is ensured only if the instrument is properly used according to the specifications in the operating instructions manual as well as possible supplementary instructions.

### 2.3 Warning about incorrect use

Inappropriate or incorrect use of the instrument can give rise to application-specific hazards, e.g. vessel overfill or damage to system components through incorrect mounting or adjustment. Also the protective characteristics of the instrument can be influenced.

### 2.4 General safety instructions

This is a state-of-the-art instrument complying with all prevailing regulations and directives. The instrument must only be operated in a technically flawless and reliable condition. The operator is responsible for the trouble-free operation of the instrument.

During the entire duration of use, the user is obliged to determine the compliance of the necessary occupational safety measures with the current valid rules and regulations and also take note of new regulations.

The safety instructions in this operating instructions manual, the national installation standards as well as the valid safety regulations and accident prevention rules must be observed by the user.

For safety and warranty reasons, any invasive work on the device beyond that described in the operating instructions manual may be carried out only by personnel authorised by the manufacturer. Arbitrary conversions or modifications are explicitly forbidden.

The safety approval markings and safety tips on the device must also be observed.

Depending on the instrument version, the emitting frequencies are in the C, K or W band range. The low emission power is far below the internationally approved limit values. When used correctly, the device poses no danger to health.

## 2.5 EU conformity

The device fulfils the legal requirements of the applicable EU directives. By affixing the CE marking, we confirm the conformity of the instrument with these directives.

You can find the EU conformity declaration on our website under [www.vega.com/downloads](http://www.vega.com/downloads).

### Electromagnetic compatibility

Instruments in four-wire or Ex-d-ia version are designed for use in an industrial environment. Nevertheless, electromagnetic interference from electrical conductors and radiated emissions must be taken into account, as is usual with class A instruments according to EN 61326-1. If the instrument is used in a different environment, the electromagnetic compatibility to other instruments must be ensured by suitable measures.

## 2.6 NAMUR recommendations

NAMUR is the automation technology user association in the process industry in Germany. The published NAMUR recommendations are accepted as the standard in field instrumentation.

The device fulfils the requirements of the following NAMUR recommendations:

- NE 21 – Electromagnetic compatibility of equipment
- NE 43 – Signal level for fault information from measuring transducers
- NE 53 – Compatibility of field devices and display/adjustment components
- NE 107 – Self-monitoring and diagnosis of field devices

For further information see [www.namur.de](http://www.namur.de).

## 2.7 Radio license for Europe

The instrument was tested according to the latest issue of the following harmonized standards:

- EN 302372 - Tank Level Probing Radar

It is hence approved for use inside closed vessels in countries of the EU.

Use is also approved in EFTA countries, provided the respective standards have been implemented.

For operation inside of closed vessels, the following conditions must be fulfilled:

- The instrument must be permanently mounted on a closed vessel made of metal, reinforced concrete, or comparable attenuating materials
- Flanges, process fittings and mounting accessories must ensure the microwave impermeability of the vessel and not let the radar signal escape to the outside

- If necessary, existing viewing windows in the vessel must be coated with a microwave impermeable material (e.g. electrically conductive coating)
- Manholes and flanges on the vessel must be closed and sealed to avoid penetration of the radar signal
- The instrument should be preferably mounted on top of the vessel with antenna orientation downward
- The instrument must only be installed and maintained by appropriately qualified staff

## 2.8 Radio license for USA

This approval is only valid for USA. Hence the following text is only available in the English language.

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- This device may not cause interference, and
- This device must accept any interference, including interference that may cause undesired operation of the device

This device is approved for unrestricted use only inside closed, stationary vessels made of metal, concrete and reinforced fiberglass.

For operation outside of closed vessels, the following conditions must be fulfilled:

- This device shall be installed and maintained to ensure a vertically downward orientation of the transmit antenna's main beam. Furthermore, the use of any mechanism that does not allow the main beam of the transmitter to be mounted vertically downward is prohibited.
- Operation of the instrument with horn antennas  $\varnothing$  40 mm and  $\varnothing$  48 mm is only permitted within closed vessels.
- Operation of the instrument with parabolic antenna ( $\varnothing$  245 mm) in conjunction with the electronics with increased sensitivity (PS60HS) is only permitted within closed vessels.
- This device shall be installed only at fixed locations. The LPR device shall not operate while being moved or while inside a moving container.
- Hand-held applications are prohibited.
- Marketing to residential consumers is prohibited.

Changes or modifications not expressly approved by the manufacturer could void the user's authority to operate this equipment.

## 2.9 Radio license for Canada

This approval is only valid for Canada. Hence the following texts are only available in the English/French language.

This device complies with Industry Canada's license-exempt RSS standards. Operation is subject to the following conditions:

- This device may not cause interference, and
- This device must accept any interference, including interference that may cause undesired operation of the device

This device has been approved for both closed containers and open-air environments with the following limitations:

- Closed Containers: For installations utilizing a tilt during installation: This device is limited to installation in a completely enclosed container made of metal, concrete or reinforced fiberglass to prevent RF emissions, which can otherwise interfere with aeronautical navigation, the maximum approved tilt angle is 10°.
- Open Air Environment: For operation outside of closed vessels, the following condition must be fulfilled: This device shall be installed and maintained to ensure a vertically downward orientation of the transmit antenna's main beam. Furthermore, the use of any mechanism that does not allow the main beam of the transmitter to be mounted vertically downward is prohibited.
- Operation of the instrument with horn antennas  $\varnothing$  40 mm and  $\varnothing$  48 mm is only permitted within closed vessels.
- Operation of the instrument with parabolic antenna ( $\varnothing$  245 mm) in conjunction with the electronics with increased sensitivity (PS60HS) is only permitted within closed vessels.

The installation of the LPR/TLPR device shall be done by trained installers, in strict compliance with the manufacture's instructions.

This device shall be installed only at fixed locations. The LPR device shall not operate while being moved or while inside a moving container.

Hand-held applications are prohibited.

Marketing to residential consumers is prohibited.

The use of this device is on a "no-interference, no-protection" basis. That is, the user shall accept operations of high-powered radar in the same frequency band which may interfere with or damage this device.

However, devices found to interfere with primary licensing operations will be required to be removed at the user's expense.

The installer/user of this device shall ensure that it is at least 10 km from the Dominion Astrophysical Radio Observatory (DRAO) near Penticton, British Columbia. The coordinates of the DRAO are latitude 49°19'15" N and longitude 119°37'12"W. For devices not meeting this 10 km separation (e.g., those in the Okanagan Valley, British Columbia), the installer/user must coordinate with, and obtain the written concurrence of, the Director of the DRAO before the equipment can be installed or operated. The Director of the DRAO may be contacted at 250-497-2300 (tel.) or 250-497-2355 (fax). (Alternatively, the Manager, Regulatory Standards, Industry Canada, may be contacted.)

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux conditions suivantes:

- L'appareil ne doit pas produire de brouillage; et
- L'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.



Cet appareil est homologué pour une utilisation dans les cuves fermées et les environnements ouverts avec les restrictions suivantes :

- Cuves fermées : Pour les installations impliquant une inclinaison lors de l'installation : cet appareil ne doit être installé que dans une cuve totalement fermée en en métal, en béton ou en matière plastique renforcée de fibres de verre, pour empêcher les émissions RF susceptibles d'interférer avec la navigation aéronautique. L'angle d'inclinaison maximum autorisé est de 10°.
- Environnement ouvert : Pour l'utilisation hors des cuves fermées, la condition suivante doit être remplie : L'appareil doit être installé et entretenu de manière à garantir une orientation verticale vers le bas du faisceau principal de l'antenne émettrice. De plus, l'utilisation de tout mécanisme ne permettant pas l'orientation verticale vers le bas du faisceau principal de l'émetteur est interdite
- Il est uniquement autorisé d'exploiter l'appareil avec les antennes cônes Ø 40 mm et Ø 48 mm dans des boîtiers fermés.
- Il est uniquement autorisé d'exploiter l'appareil avec une antenne parabolique (Ø 245 mm) en liaison avec l'électronique à sensibilité accrue (PS60HS) dans des boîtiers fermés.

L'installation d'un dispositif LPR ou TLPR doit être effectuée par des installateurs qualifiés, en pleine conformité avec les instructions du fabricant.

Cet appareil ne doit être installé qu'à des emplacements fixes. L'appareil LPR ne doit pas être utilisé pendant qu'il est en train d'être déplacé ou se trouve dans un conteneur en mouvement.

Les applications portables sont interdites.

La vente à des particuliers est interdite

Ce dispositif ne peut être exploité qu'en régime de non-brouillage et de non-protection, c'est-à-dire que l'utilisateur doit accepter que des radars de haute puissance de la même bande de fréquences puissent brouiller ce dispositif ou même l'endommager. D'autre part, les capteurs de niveau qui perturbent une exploitation autorisée par licence de fonctionnement principal doivent être enlevés aux frais de leur utilisateur.

La personne qui installe/utilise ce capteur de niveau doit s'assurer qu'il se trouve à au moins 10 km de l'Observatoire fédéral de radioastrophysique (OFR) de Penticton en Colombie-Britannique. Les coordonnées de l'OFR sont : latitude N 49° 19' 15", longitude O 119° 37' 12". La personne qui installe/utilise un dispositif ne pouvant respecter cette distance de 10km (p. ex. dans la vallée de l'Okanagan [Colombie-Britannique]) doit se concerter avec le directeur de l'OFR afin d'obtenir de sa part une autorisation écrite avant que l'équipement ne puisse être installé ou mis en marche. Le directeur de l'OFR peut être contacté au 250-497-2300 (tél.) ou au 250-497-2355 (fax). (Le Directeur des Normes réglementaires d'Industrie Canada peut également être contacté).

## 2.10 Environmental instructions

Protection of the environment is one of our most important duties. That is why we have introduced an environment management system

with the goal of continuously improving company environmental protection. The environment management system is certified according to DIN EN ISO 14001.

Please help us fulfil this obligation by observing the environmental instructions in this manual:

- Chapter "*Packaging, transport and storage*"
- Chapter "*Disposal*"

## 3 Product description

### 3.1 Configuration

#### Type label

The type label contains the most important data for identification and use of the instrument:

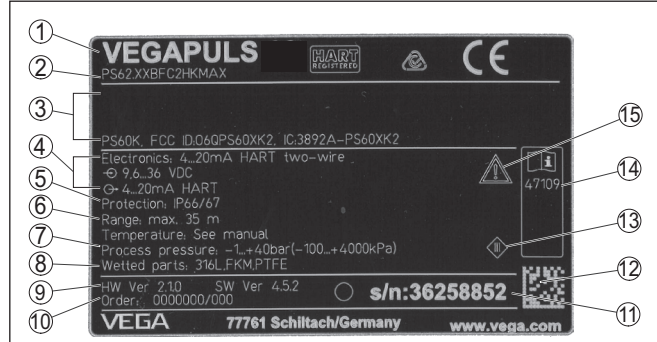


Fig. 1: Layout of the type label (example)

- 1 Instrument type
- 2 Product code
- 3 Approvals
- 4 Power supply and signal output, electronics
- 5 Protection rating
- 6 Measuring range
- 7 Process and ambient temperature, process pressure
- 8 Material, wetted parts
- 9 Hardware and software version
- 10 Order number
- 11 Serial number of the instrument
- 12 Data matrix code for smartphone app
- 13 Symbol of the device protection class
- 14 ID numbers, instrument documentation
- 15 Reminder to observe the instrument documentation

#### Serial number - Instrument search

The type label contains the serial number of the instrument. With it you can find the following instrument data on our homepage:

- Product code (HTML)
- Delivery date (HTML)
- Order-specific instrument features (HTML)
- Operating instructions and quick setup guide at the time of shipment (PDF)
- Order-specific sensor data for an electronics exchange (XML)
- Test certificate (PDF) - optional

Go to "[www.vega.com](http://www.vega.com)", "Instrument search (serial number)". Enter the serial number.

Alternatively, you can access the data via your smartphone:

- Download the smartphone app "VEGA Tools" from the "Apple App Store" or the "Google Play Store"
- Scan the Data Matrix code on the type label of the instrument or
- Enter the serial number manually in the app

**Scope of this operating instructions manual**

This operating instructions manual applies to the following instrument versions:

- Hardware from 2.1.0
- Software from 4.5.1

**Electronics versions**

The instrument is available in two different electronics versions. Each version can be identified via the product code on the type label as well as on the electronics.

- Standard electronics type PS60HK.-
- Electronics with increased sensitivity type PS60HS.-

**Scope of delivery**

The scope of delivery encompasses:

- Radar sensor
- Documentation
  - Quick setup guide VEGAPULS 62
  - Instructions for optional instrument features
  - Ex-specific "*Safety instructions*" (with Ex versions)
  - If necessary, further certificates
- DVD "*DTM Collection*", included therein
  - PACTware
  - DTM Collection
  - Instrument master files (GSD) for Profibus PA
  - FDT certificates

**Information:**

The optional instrument features are described in the operating instructions manual. The respective scope of delivery results from the order specification.

**Application area****3.2 Principle of operation**

The VEGAPULS 62 radar sensor can be used in a wide variety of applications for continuous level measurement of liquids. It is suitable for applications in storage vessels, reactors and process vessels, even under extremely difficult process conditions.

Dependent on the application range, different versions are used:

- Antenna
  - Small tanks and process vessels, measurement of virtually all products: **Horn antenna ø 40 mm**
  - Storage tanks and process vessels, measurement of products such as solvents, hydrocarbons and fuels under extremely difficult process conditions: **Horn antenna ø 48 ... 95 mm**
  - Products with low  $\epsilon_r$  value with large measuring distances: **Parabolic antenna**
- Electronics
  - Products with an  $\epsilon_r$  value  $\geq 1.8$ : **Standard electronics**
  - Products with an  $\epsilon_r$  value  $< 1.8$ ,  $\geq 1.5$ ; applications with very bad reflective properties: **Electronics with increased sensitivity**

The actual values that can be reached depend on the measurement conditions, the antenna system or the standpipe or bypass.

## Functional principle

The antenna of the radar sensor emits short radar pulses with a duration of approx. 1 ns. These pulses are reflected by the product and received by the antenna as echoes. The transit time of the radar pulses from emission to reception is proportional to the distance and hence to the level. The determined level is converted into an appropriate output signal and outputted as measured value.

## Packaging

### 3.3 Packaging, transport and storage

Your instrument was protected by packaging during transport. Its capacity to handle normal loads during transport is assured by a test based on ISO 4180.

The packaging of standard instruments consists of environment-friendly, recyclable cardboard. For special versions, PE foam or PE foil is also used. Dispose of the packaging material via specialised recycling companies.

## Transport

Transport must be carried out in due consideration of the notes on the transport packaging. Nonobservance of these instructions can cause damage to the device.

## Transport inspection

The delivery must be checked for completeness and possible transit damage immediately at receipt. Ascertained transit damage or concealed defects must be appropriately dealt with.

## Storage

Up to the time of installation, the packages must be left closed and stored according to the orientation and storage markings on the outside.

Unless otherwise indicated, the packages must be stored only under the following conditions:

- Not in the open
- Dry and dust free
- Not exposed to corrosive media
- Protected against solar radiation
- Avoiding mechanical shock and vibration

## Storage and transport temperature

- Storage and transport temperature see chapter "*Supplement - Technical data - Ambient conditions*"
- Relative humidity 20 ... 85 %

### 3.4 Accessories and replacement parts

## PLICSCOM

The display and adjustment module PLICSCOM is used for measured value indication, adjustment and diagnosis. It can be inserted into the sensor and removed at any time.

The integrated Bluetooth module (optional) enables wireless adjustment via standard adjustment devices:<sup>1)</sup>

- Smartphone/tablet (iOS or Android operating system)
- PC/notebook with Bluetooth USB adapter (Windows operating system)

You can find further information in the operating instructions "*Display and adjustment module PLICSCOM*" (Document-ID 27835).

**VEGACONNECT**

The interface adapter VEGACONNECT enables the connection of communication-capable instruments to the USB interface of a PC. For parameter adjustment of these instruments, the adjustment software PACTware with VEGA-DTM is required.

You can find further information in the operating instructions "*Interface adapter VEGACONNECT*" (Document-ID 32628).

**VEGADIS 81**

The VEGADIS 81 is an external display and adjustment unit for VEGA plics® sensors.

For sensors with double chamber housing the interface adapter "*VEGADIS adapter*" is also required for VEGADIS 81.

You can find further information in the operating instructions "*VEGADIS 81*" (Document-ID 43814).

**VEGADIS adapter**

The VEGADIS adapter is an accessory part for sensors with double chamber housings. It enables the connection of VEGADIS 81 to the sensor housing via an M12 x 1 plug.

You can find further information in the supplementary instructions "*VEGADIS adapter*" (Document-ID 45250).

**VEGADIS 82**

VEGADIS 82 is suitable for measured value indication and adjustment of sensors with HART protocol. It is looped into the 4 ... 20 mA/HART signal cable.

You can find further information in the operating instructions "*VEGADIS 82 4 ... 20 mA/HART*" (Document-ID 45300).

**PLICSMOBILE T61**

PLICSMOBILE T61 is an external GSM/GPRS radio unit for transmission of measured values and for remote parameter adjustment of plics® sensors. Adjustment is carried out via PACTware/DTM and the integrated USB connection.

You can find further information in the supplementary instructions "*PLICSMOBILE T61*" (Document-ID 37700).

**Protective cover**

The protective cover protects the sensor housing against soiling and intense heat from solar radiation.

You will find additional information in the supplementary instructions manual "*Protective cover*" (Document-ID 34296).

**Flanges**

Screwed flanges are available in different versions according to the following standards: DIN 2501, EN 1092-1, BS 10, ASME B 16.5, JIS B 2210-1984, GOST 12821-80.

You can find additional information in the supplementary instructions manual "*Flanges according to DIN-EN-ASME-JIS*".

**Electronics module**

Electronics module "VEGAPULS series 60" is a replacement part for radar sensors of VEGAPULS series 60. A different version is available for each type of signal output.

<sup>1)</sup> Bluetooth function with VEGADIS 82 can only be used at a later date.

You can find further information in the operating instructions "*Electronics module VEGAPULS series 60*" (Document-ID 36801).

**Supplementary electronics for 4 ... 20 mA/HART - four-wire**

The supplementary electronics is a replacement part for the following sensors with 4 ... 20 mA/HART - two-wire:

- VEGAPULS series 60
- VEGAFLEX 80 series
- VEGABAR series 80

You can find further information in the operating instructions "*Supplementary electronics for 4 ... 20 mA/HART - four-wire*" (Document-ID 42766).

**Antenna impedance cone**

The antenna impedance cone is a replacement part used for optimum transmission of microwaves and for sealing against the process.

You find further information in the operating instructions "*Antenna impedance cone VEGAPULS 62 and 68*" (Document-ID 31381).

## 4 Mounting

### 4.1 General instructions

#### Screwing in

On instruments with threaded process fitting, the hexagon must be tightened with a suitable wrench. For the proper wrench size see chapter "*Dimensions*".



#### Warning:

The housing must not be used to screw the instrument in! Applying tightening force can damage internal parts of the housing.

#### Protection against moisture

Protect your instrument against moisture ingress through the following measures:

- Use the recommended cable (see chapter "*Connecting to power supply*")
- Tighten the cable gland
- When mounting horizontally, turn the housing so that the cable gland points downward
- Loop the connection cable downward in front of the cable gland

This applies mainly to outdoor installations, in areas where high humidity is expected (e.g. through cleaning processes) and on cooled or heated vessels.

#### Suitability for the process conditions

Make sure before mounting that all parts of the instrument exposed to the process are suitable for the existing process conditions.

These are mainly:

- Active measuring component
- Process fitting
- Process seal

Process conditions in particular are:

- Process pressure
- Process temperature
- Chemical properties of the medium
- Abrasion and mechanical influences

You can find detailed information on the process conditions in chapter "*Technical data*" as well as on the type label.

#### Cable glands

##### Metric threads

In the case of instrument housings with metric thread, the cable glands are screwed in at the factory. They are sealed with plastic plugs as transport protection.

You have to remove these plugs before electrical connection.

##### NPT thread

In the case of instrument housings with self-sealing NPT threads, it is not possible to have the cable entries screwed in at the factory. The free openings for the cable glands are therefore covered with red dust protection caps as transport protection. The dust protection caps do not provide sufficient protection against moisture.



Prior to setup you have to replace these protective caps with approved cable glands or close the openings with suitable blind plugs.

## 4.2 Mounting preparations

The instrument is also available in versions with an antenna whose diameter is larger than the process fitting (thread, flange). In such cases the antenna must be disconnected from the process fitting before mounting.

### Horn antenna

Proceed as follows:

1. Loosen the hexagon socket screws (3) on the antenna socket with an Allen wrench (size 3)
2. Remove the antenna (4)



#### Note:

The plastic cone may not be pulled out of the antenna socket.

3. Insert the antenna from below into the vessel socket and secure it against falling off
4. Retighten the antenna with hexagon screws to the antenna socket; max. torque see chapter "*Technical data*"



#### Note:

The radar sensor with rinsing air connection or with antenna extension has a notch on the antenna socket for polarization. This notch must be aligned with the marking on the process fitting.

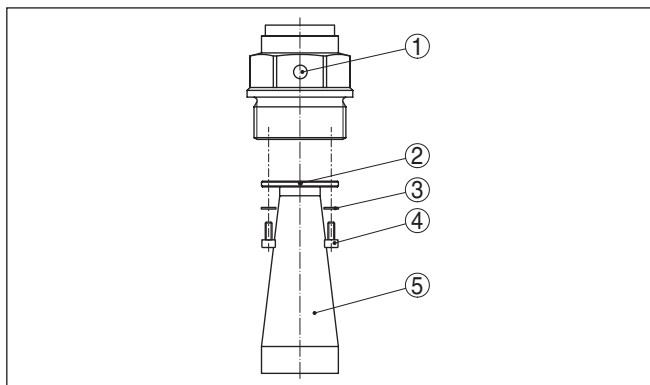


Fig. 2: Dismounting of the horn antenna

- 1 Marking on the process fitting
- 2 Marking at the antenna socket
- 3 Screw locking device
- 4 Hexagon socket screws
- 5 Antenna



#### Caution:

A secure hold of the antenna is only ensured with the untwist guard. The untwist guards inserted on site must hence be used again. Depending on temperature range and antenna material, these are

spring rings according to DIN 217 or wedge lock washers according to DIN 25 201.

### Parabolic antenna

Proceed as follows:

1. Clamp VEGAPULS 62 with the flange, e.g. in a bench vice
2. Hold the connection piece (1) with a wrench on the flat surfaces (width across flats 22 mm)
3. Loosen counter nut (3) completely with a wrench (width across flats 36 mm) in the direction of the antenna
4. Loosen compression nut (2) completely with a wrench (width across flats 41 mm) in the direction of the antenna
5. Remove the parabolic antenna (4) axially
6. Mount sensor flange on the adapter flange and fasten it tightly
7. Check if the O-ring seal is present on the connection piece and make sure it is not damaged.



#### Note:

A damaged O-ring seal must be replaced: FKM (SHS FPM 70C3 GLT), FFKM (Kalrez 6375)

8. Remount the parabolic antenna (4)
9. Fasten compression nut (2) with a wrench (width across flats 41), max. torque see chapter "Technical data"
10. Fasten counter nut (3) with a wrench (width across flats 36), max. torque see chapter "Technical data"



#### Note:

On the version with rinsing air connection, make sure that the holes in the antenna and in the process fitting coincide. This ensures a sufficient air flow (the air is led through the holes to the feed system. A rinsing of the whole parabolic antenna is not intended).

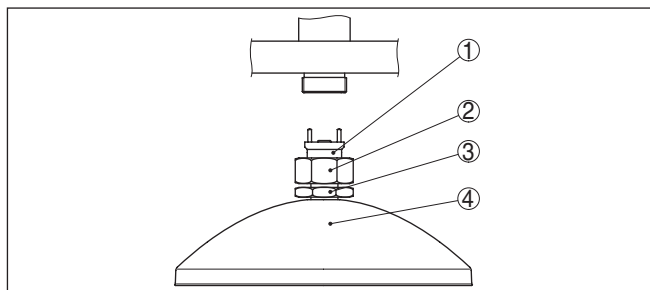


Fig. 3: Dismounting, parabolic antenna

- 1 Connection piece
- 2 Compression nut
- 3 Counter nut
- 4 Parabolic antenna

## Horn and parabolic antenna

## Polarisation

### 4.3 Mounting instructions

The illustrations with the following mounting instructions show a radar sensor with horn antenna. The mounting instructions apply analogously also to the version with parabolic antenna.

The emitted radar impulses of the radar sensor are electromagnetic waves. The polarisation is the direction of the electrical wave component. By turning the instrument in the connection flange or mounting boss, the polarisation can be used to reduce the effects of false echoes.

The position of the polarisation is marked on the process fitting of the instrument.

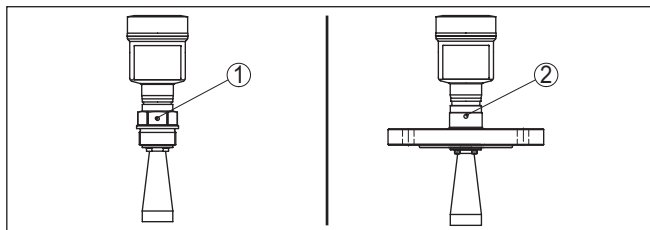


Fig. 4: Position of the polarisation

- 1 Marking with screwed version
- 2 Marking with flange version

## Installation position

When mounting the sensor, keep a distance of at least 200 mm (7.874 in) from the vessel wall. If the sensor is installed in the center of dished or round vessel tops, multiple echoes can arise. However, these can be suppressed by an appropriate adjustment (see chapter "Setup").

If you cannot maintain this distance, you should carry out a false signal suppression during setup. This applies particularly if buildup on the vessel wall is expected. In such cases, we recommend repeating the false signal suppression at a later date with existing buildup.

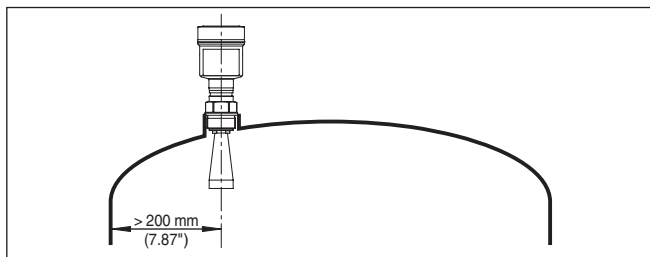


Fig. 5: Mounting of the radar sensor on round vessel tops

In vessels with conical bottom it can be advantageous to mount the sensor in the centre of the vessel, as measurement is then possible down to the bottom.

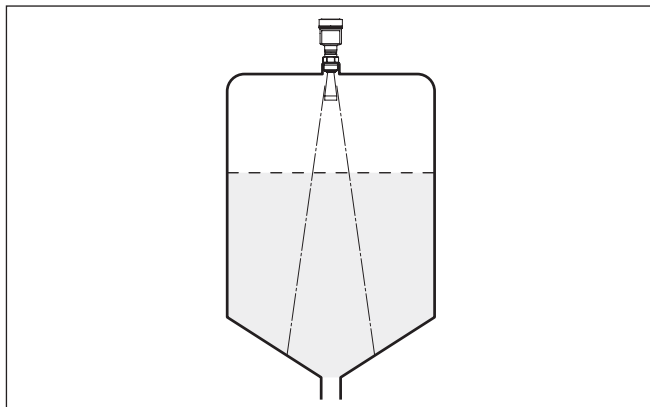


Fig. 6: Mounting of the radar sensor on vessels with conical bottom

### Inflowing medium

Do not mount the instruments in or above the filling stream. Make sure that you detect the product surface, not the inflowing product.

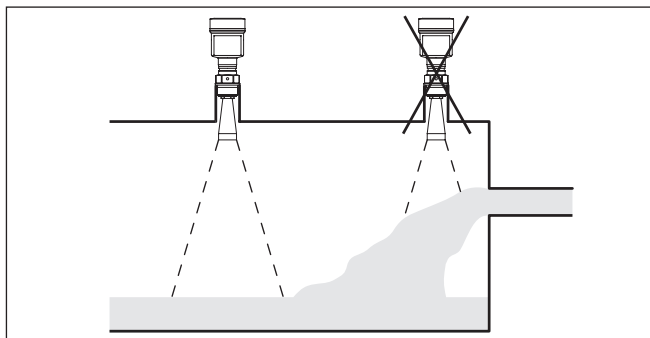


Fig. 7: Mounting of the radar sensor with inflowing medium

### Mounting socket

The socket piece should be dimensioned in such a way that the antenna end protrudes slightly out of the socket.

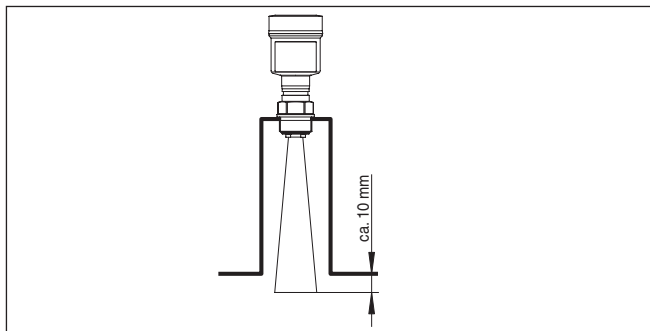


Fig. 8: Recommended socket mounting with horn antenna

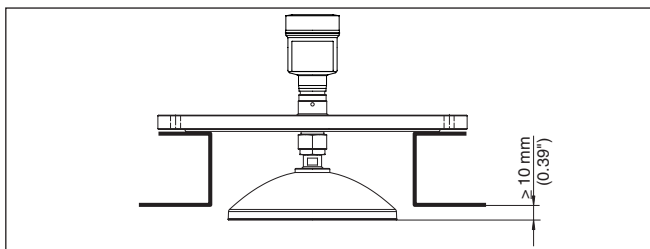


Fig. 9: Recommended socket mounting with parabolic antenna

When using a swivelling holder, keep in mind that the distance between antenna and socket gets smaller as the inclination of the sensor increases. Additional false reflections may be generated which can influence the measuring result at close range. Max. torque see chapter "Technical data"

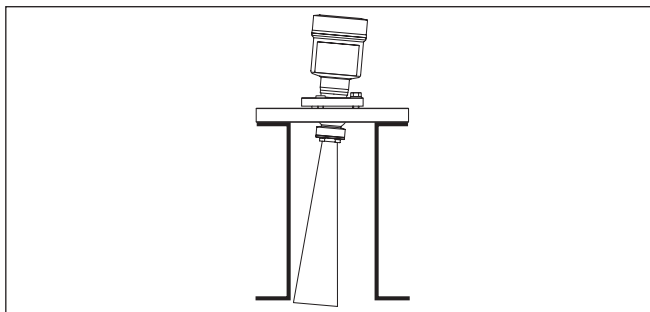


Fig. 10: Distance between antenna and socket with horn antenna

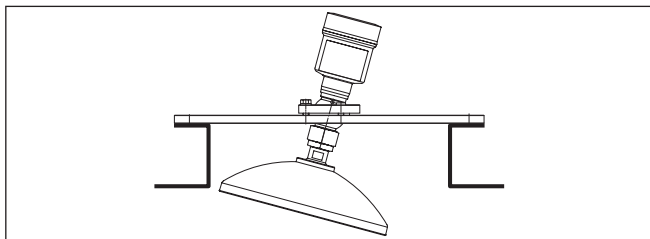


Fig. 11: Distance between antenna and socket with parabolic antenna

If the medium has good reflective properties, VEGAPULS 62 with horn antenna can also be mounted on a longer socket piece. Recommended values for socket heights are specified in the following illustration. You must carry out a false signal suppression afterwards.

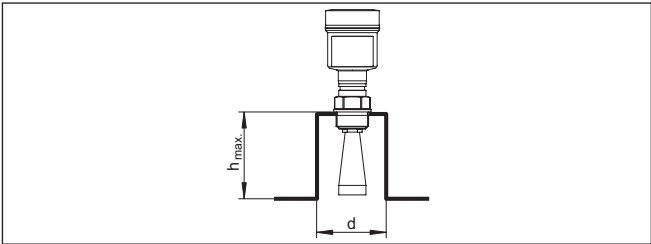


Fig. 12: Deviating socket dimensions

Socket diameter d	Socket length h	Recommended antenna diameter
40 mm	≤ 100 mm	40 mm
50 mm	≤ 150 mm	48 mm
80 mm	≤ 250 mm	75 mm
100 mm	≤ 500 mm	95 mm
150 mm	≤ 800 mm	95 mm

Socket diameter d	Socket length h	Recommended antenna diameter
1½"	≤ 3.9 in	1½"
2"	≤ 5.9 in	2"
3"	≤ 9.8 in	3"
4"	≤ 19.7 in	4"
6"	≤ 31.5 in	4"



**Tip:**

The instrument is also optionally available with an antenna extension. The antenna length can be selected (either ex works or later) to allow the antenna to protrude slightly out of the end of the mounting socket. Due to the antenna extension however, disturbing reflections are generated in the close-up range. This can lead to an increase in the required minimum distance, especially with poorly reflecting media such as plastic powder. In practice, a cleanly constructed mounting socket, if necessary with rounded edges, introduces fewer disturbing influences than an antenna extension.

**Sensor orientation**

In liquids, direct the sensor as perpendicular as possible to the product surface to achieve optimum measurement results.

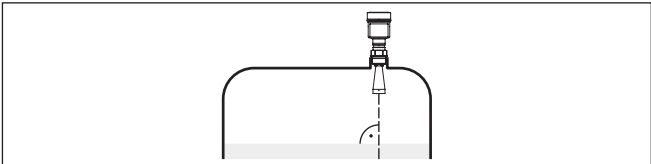


Fig. 13: Alignment in liquids

## Swivelling holder

Proceed as follows to align the sensor with the swivelling holder:

1. Loosen terminal screw of the swivelling holder with a fork spanner SW 13

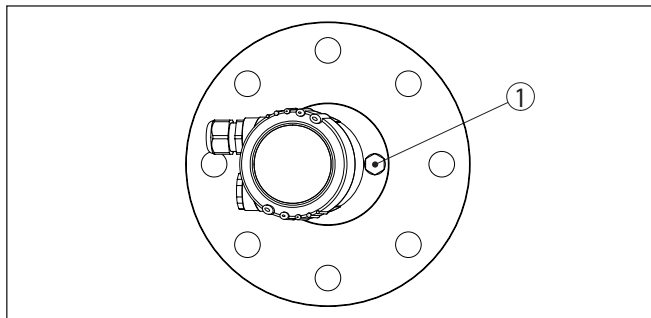


Fig. 14: VEGAPULS 62 with swivelling holder

1 Terminal screw



### Information:

The hexagon screws must not be loosened.

2. Align the sensor, check angle of inclination. Max. angle of inclination of the swivelling holder see chapter "Dimensions"
3. Re-tighten the terminal screw, max. torque see chapter "Technical data".

## Vessel installations

The mounting location of the radar sensor should be a place where no other equipment or fixtures cross the path of the radar signals.

Vessel installations, such as e.g. ladders, limit switches, heating spirals, struts, etc., can cause false echoes and impair the useful echo. Make sure when planning your measuring point that the radar sensor has a "clear view" to the measured product.

In case of existing vessel installations, a false signal suppression should be carried out during setup.

If large vessel installations such as struts or supports cause false echoes, these can be attenuated through supplementary measures. Small, inclined sheet metal baffles above the installations scatter the radar signals and prevent direct interfering reflections.

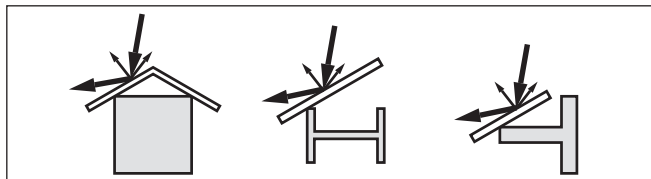


Fig. 15: Cover flat, large-area profiles with deflectors

## Agitators

If there are agitators in the vessel, a false signal suppression should be carried out with the agitators in motion. This ensures that the

interfering reflections from the agitators are saved with the blades in different positions.

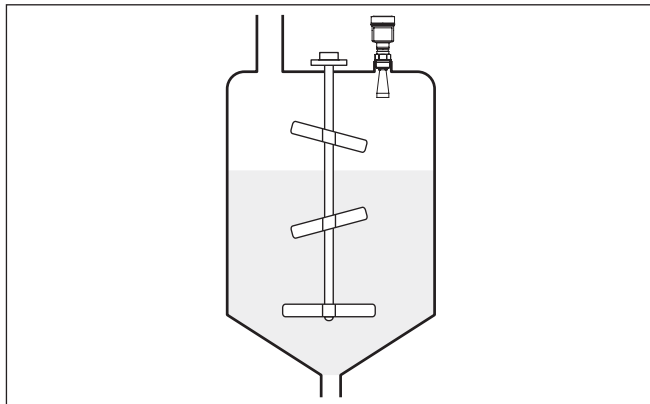


Fig. 16: Agitators

### Foam generation

Through the action of filling, stirring and other processes in the vessel, compact foam can form on the product surface, damping the emitted signals considerably.

If foams are causing measurement errors, the biggest possible radar antennas, the electronics with increased sensitivity or low frequency radar sensors (C band) should be used.

As an alternative, sensors with guided microwave can be used. These are unaffected by foam generation and are best suited for such applications.

### Mounting in the vessel insulation

Instruments for a temperature range up to 250 °C or up to 450 °C have a distance piece between process fitting and electronics housing. This distance piece is used for thermal decoupling of the electronics against high process temperatures.



#### Information:

The spacer may only be incorporated up to a maximum of 50 mm into the vessel insulation. Only then is a reliable temperature decoupling guaranteed.



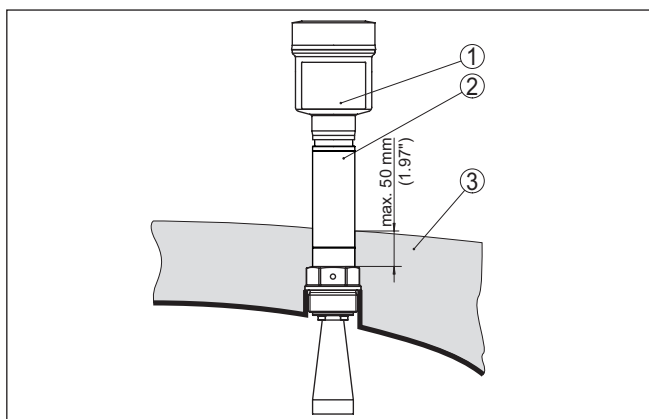


Fig. 17: Mounting the instrument on insulated vessels.

- 1 Electronics housing
- 2 Spacer
- 3 Vessel insulation

## 4.4 Measurement setup - Pipes

### Measurement in a surge pipe

By using a surge pipe in the vessel, the influence of vessel installations and turbulence can be excluded. Under these prerequisites, the measurement of products with low dielectric values ( $\epsilon_r$  value  $\leq 1.6$ ) is possible.

Note the following illustrations and instructions for measurement in a surge pipe.



#### Information:

Measurement in a surge pipe is not recommended for extremely adhesive products.

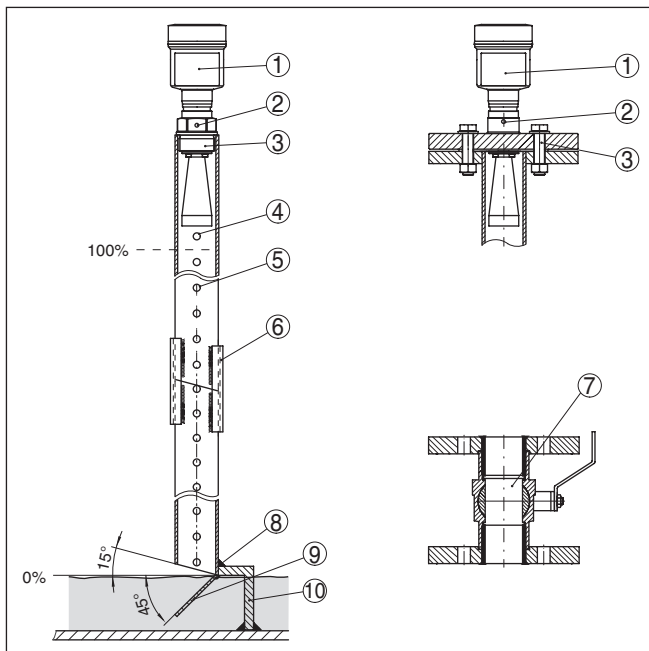
**Configuration surge pipe**

Fig. 18: Configuration surge pipe VEGAPULS 62

- 1 Radar sensor
- 2 Polarisation marking
- 3 Thread or flange on the instrument
- 4 Vent hole
- 5 Holes
- 6 Welding connection through U-profile
- 7 Ball valve with complete opening
- 8 Surge pipe end
- 9 Reflector sheet
- 10 Fastening of the surge pipe

## Surge pipe extension

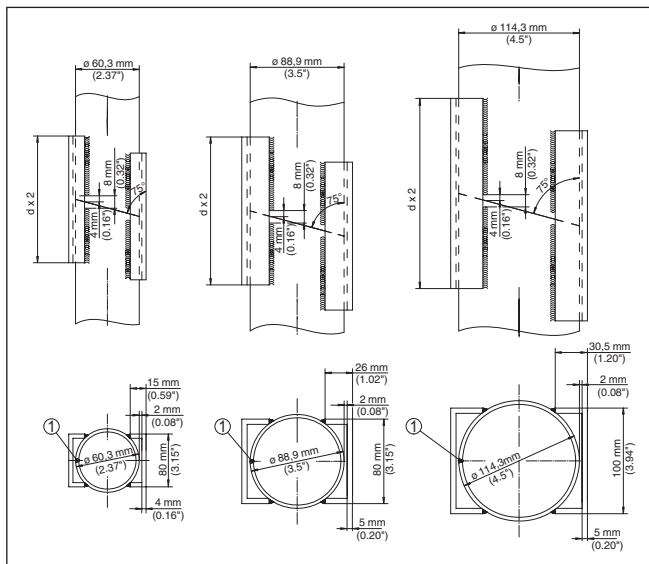


Fig. 19: Welding connection with surge pipe extension for different example diameters

1 Position of the welded joint with longitudinally welded pipes

## Instructions and requirements, surge pipe

### Instructions of orientation of the polarisation:

- Note marking of the polarisation on the sensor
- With threaded versions, the marking is on the hexagon, with flange versions between two flange holes
- The marking must be in one plane with the holes in the surge pipe

### Instructions for the measurement:

- The 100 % point must be below the upper vent hole and the antenna edge
- The 0 % point is the end of the surge pipe
- During parameter adjustment, select "Application standpipe" and enter the tube diameter to compensate for errors due to running time shift
- A false signal suppression with the installed sensor is recommended but not mandatory
- The measurement through a ball valve with unrestricted channel is possible

### Constructive requirements:

- Material metal, smooth inner surface
- Preferably pultruded or straight beaded stainless steel tube
- Welded joint should be straight and lie in one axis with the holes
- Flanges are welded to the tube according to the orientation of the polarisation

- When using a ball valves, align the transitions on the inside and fix accurately
- Gap size with junctions  $\leq 0.1$  mm
- Surge pipes must extend all the way down to the requested min. level, as measurement is only possible within the tube
- Diameter of holes  $\leq 5$  mm, any number OK, on one side or completely through
- The antenna diameter of the sensor should correspond to the inner diameter of the tube
- Diameter should be constant over the complete length

**Instructions for surge pipe extension:**

- The ends of the extension tubes must be bevelled and exactly aligned
- Welded connection via external U profiles according to illustration above. Length of the U profiles should be at least double the tube diameter
- Do not weld through the pipe wall. The surge pipe must remain smooth inside. Roughness and beads on the inside caused by unintentional penetration should be removed since they cause strong false echoes and encourage buildup
- An extension via welding neck flanges or pipe collars is not recommended.

**Measurement in the bypass tube**

An alternative to measurement in a surge pipe is measurement in a bypass tube outside of the vessel.

## Configuration bypass

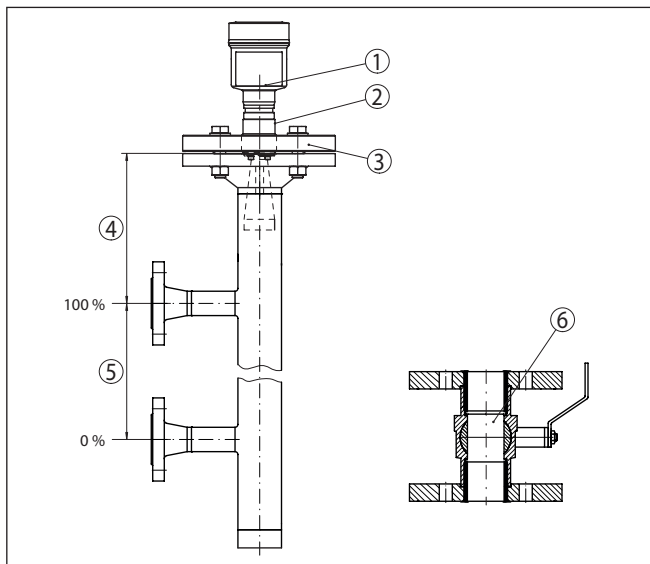


Fig. 20: Configuration bypass

- 1 Radar sensor
- 2 Polarisation marking
- 3 Instrument flange
- 4 Distance sensor reference plane to upper tube connection
- 5 Distance of the tube connections
- 6 Ball valve with complete opening

### Instructions and requirements, bypass

#### Instructions of orientation of the polarisation:

- Note marking of the polarisation on the sensor
- With threaded versions, the marking is on the hexagon, with flange versions between two flange holes
- The marking must be in one plane with the tube connections to the vessel

#### Instructions for the measurement:

- The 100 % point may not be above the upper tube connection to the vessel
- The 0 % point may not be below the lower tube connection to the vessel
- Min. distance, sensor reference plane to upper edge of upper tube connection > 300 mm
- During parameter adjustment, select "*Application standpipe*" and enter the tube diameter to compensate for errors due to running time shift
- A false signal suppression with the installed sensor is recommended but not mandatory
- The measurement through a ball valve with unrestricted channel is possible

### Constructional requirements on the bypass pipe:

- Material metal, smooth inner surface
- In case of an extremely rough tube inner surface, use an inserted tube (tube in tube) or a radar sensor with tube antenna
- Flanges are welded to the tube according to the orientation of the polarisation
- Gap size with junctions  $\leq 0.1$  mm, for example, when using a ball valve or intermediate flanges with single pipe sections
- The antenna diameter of the sensor should correspond to the inner diameter of the tube
- Diameter should be constant over the complete length

## 4.5 Measurement setup - Flow

### Flow measurement with rectangular overflow

The short examples give you introductory information on flow measurement. Detailed planning information is available from flume manufacturers and in special literature.

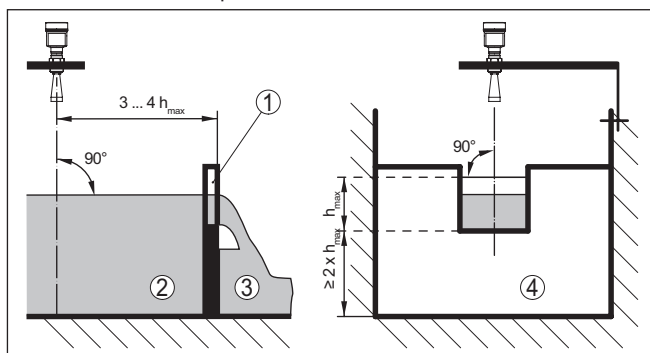


Fig. 21: Flow measurement with rectangular overflow:  $d_{\min}$  = min. distance of the sensor (see chapter "Technical data");  $h_{\max}$  = max. filling of the rectangular spillway

- 1 Overflow orifice (side view)
- 2 Headwater
- 3 Tailwater
- 4 Overflow orifice (view from tailwater)

In general, the following points must be observed:

- Install the sensor on the headwater side
- Installation in the centre of the flume and vertical to the liquid surface
- Distance to the overflow orifice
- Distance of orifice opening above ground
- Min. distance of the orifice opening to tailwater
- Min. distance of the sensor to max. storage level

## Flow measurement with Khafagi Venturi flume

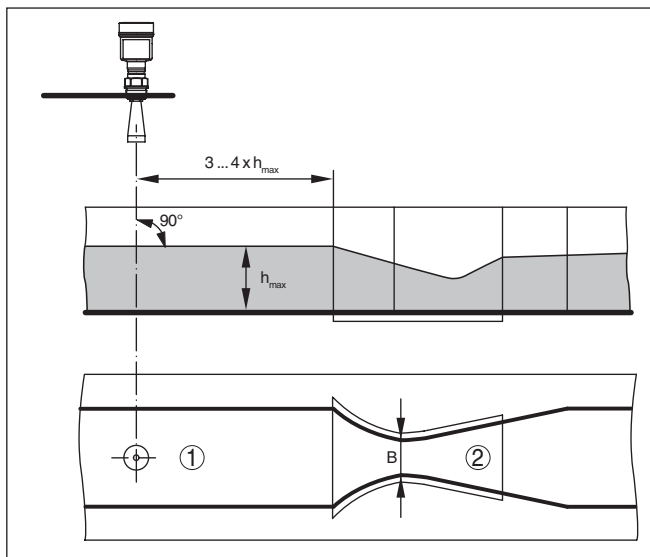


Fig. 22: Flow measurement with Khafagi-Venturi flume:  $h_{\text{max}}$  = max. filling of the flume;  $B$  = tightest constriction in the flume

- 1 Position sensor
- 2 Venturi flume

In general, the following points must be observed:

- Installation of the sensor at the inlet side
- Installation in the centre of the flume and vertical to the liquid surface
- Distance to the Venturi flume
- Min. distance of the sensor to max. storage level

## 5 Connecting to power supply

### 5.1 Preparing the connection

#### Safety instructions

Always keep in mind the following safety instructions:



#### Warning:

Connect only in the complete absence of line voltage.

- The electrical connection must only be carried out by trained personnel authorised by the plant operator.
- If overvoltage surges are expected, overvoltage arresters should be installed.



#### Note:

Install a separating facility for the instrument which is easy to access. The separating facility must be marked for the instrument (IEC/EN 61010).

#### Voltage supply via mains voltage

In this case, the instrument is designed in protection class I. To maintain this protection class, it is absolutely necessary that the ground conductor be connected to the internal ground terminal. Take note of the national installation regulations.

Supply voltage and current signal are carried on separate connection cables if reliable separation is required. The supply voltage range can differ depending on the instrument version.

The data for power supply are specified in chapter "*Technical data*".

#### Voltage supply via low voltage

In this case, the instrument is designed in protection class II. Generally connect the instrument to vessel ground (potential equalization) or with plastic vessels to the next ground potential. For this purpose, a ground terminal is located laterally on the instrument housing.

#### Connection cable

An approved, three-wire installation cable with PE conductor is required for voltage supply with mains voltage.

The 4 ... 20 mA current output is connected with standard two-wire cable without screen. If electromagnetic interference is expected which is above the test values of EN 61326-1 for industrial areas, screened cable should be used.

Use cable with round cross section for instruments with housing and cable gland. To ensure the seal effect of the cable gland (IP protection rating), find out which cable outer diameter the cable gland is suitable for.

Use a cable gland fitting the cable diameter.

#### Cable glands

##### Metric threads

In the case of instrument housings with metric thread, the cable glands are screwed in at the factory. They are sealed with plastic plugs as transport protection.

You have to remove these plugs before electrical connection.



### NPT thread

In the case of instrument housings with self-sealing NPT threads, it is not possible to have the cable entries screwed in at the factory. The free openings for the cable glands are therefore covered with red dust protection caps as transport protection.

Prior to setup you have to replace these protective caps with approved cable glands or close the openings with suitable blind plugs.

On plastic housings, the NPT cable gland or the Conduit steel tube must be screwed into the threaded insert without grease.

Max. torque for all housings, see chapter "*Technical data*".

### Cable screening and grounding

If screened cable is required, we recommend connecting the cable screen on both ends to ground potential. In the sensor, the screen must be connected directly to the internal ground terminal. The ground terminal on the outside of the housing must be connected to the ground potential (low impedance).



In Ex systems, the grounding is carried out according to the installation regulations.

In electroplating plants as well as plants for cathodic corrosion protection it must be taken into account that significant potential differences exist. This can lead to unacceptably high currents in the cable screen if it is grounded at both ends.



#### Information:

The metallic parts of the instrument (process fitting, sensor, concentric tube, etc.) are connected with the internal and external ground terminal on the housing. This connection exists either directly via the conductive metallic parts or, in case of instruments with external electronics, via the screen of the special connection cable.

You can find specifications on the potential connections inside the instrument in chapter "*Technical data*".

## 5.2 Connecting

### Connection technology

The voltage supply and signal output are connected via the spring-loaded terminals in the housing.

Connection to the display and adjustment module or to the interface adapter is carried out via contact pins in the housing.



#### Information:

The terminal block is pluggable and can be removed from the electronics. To do this, lift the terminal block with a small screwdriver and pull it out. When reinserting the terminal block, you should hear it snap in.

### Connection procedure

Proceed as follows:

1. Unscrew the housing lid
2. Loosen compression nut of the cable gland and remove blind plug

3. Remove approx. 10 cm (4 in) of the cable mantle (signal output), strip approx. 1 cm (0.4 in) insulation from the ends of the individual wires
4. Insert the cable into the sensor through the cable entry



Fig. 23: Connection steps 5 and 6

5. Insert the wire ends into the terminals according to the wiring plan



**Information:**

Solid cores as well as flexible cores with wire end sleeves are inserted directly into the terminal openings. In case of flexible cores without end sleeves, press the terminal from above with a small screwdriver, the terminal opening is then free. When the screwdriver is released, the terminal closes again.

6. Check the hold of the wires in the terminals by lightly pulling on them
7. Connect the screen to the internal ground terminal, connect the outer ground terminal to potential equalisation in case of power supply via low voltage
8. Connect the lead cable for power supply in the same way according to the wiring plan, in addition connect the ground conductor to the inner ground terminal when powered with mains voltage.
9. Tighten the compression nut of the cable glands. The seal ring must completely encircle the cables
10. Screw the housing lid back on

The electrical connection is finished.



**Information:**

The terminal blocks are pluggable and can be removed from the housing insert. To do this, lift the terminal block with a small screwdriver and pull it out. When inserting the terminal block again, you should hear it snap in.

### 5.3 Wiring plan, double chamber housing



The following illustrations apply to the non-Ex as well as to the Ex-d-ia version.

#### Electronics compartment

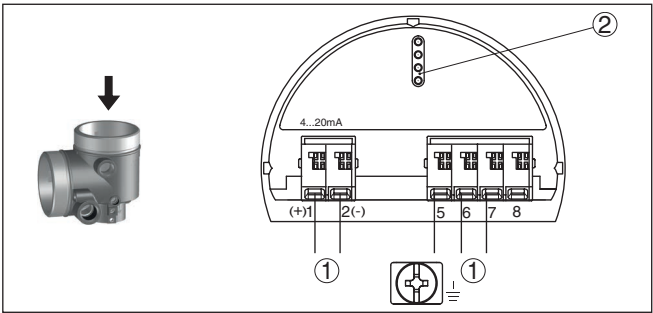


Fig. 24: Electronics compartment - double chamber housing

- 1 Internal connection to the terminal compartment
- 2 For display and adjustment module or interface adapter



#### Information:

The connection of an external display and adjustment unit is not possible with the Ex-d-ia version.

#### Connection compartment with mains voltage

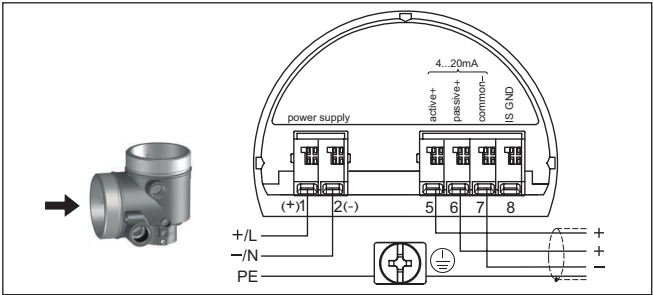


Fig. 25: Connection compartment with double chamber housing with mains voltage

Terminal	Function	Polarity
1	Voltage supply	+ / L
2	Voltage supply	- / N
5	4 ... 20 mA output (active)	+
6	4 ... 20 mA output (passive)	+
7	Mass - output	-
8	Function ground when installing according to CSA (Canadian Standards Association)	

**Connection compartment with low voltage**

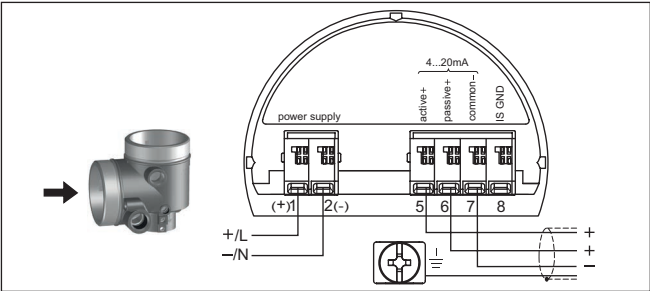


Fig. 26: Connection compartment with double chamber housing with low voltage

Terminal	Function	Polarity
1	Voltage supply	+/L
2	Voltage supply	-/N
5	4 ... 20 mA output (active)	+
6	4 ... 20 mA output (passive)	+
7	Mass - output	-
8	Function ground when installing according to CSA (Canadian Standards Association)	

**5.4 Double chamber housing with VEGADIS-Adapter**

The following illustrations apply to the non-Ex version.

**Electronics compartment**

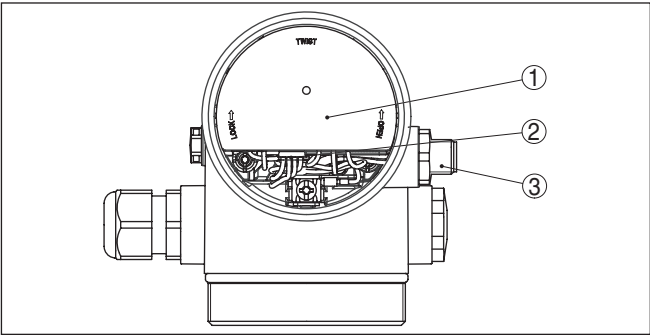


Fig. 27: View to the electronics compartment with VEGADIS adapter for connection of the external display and adjustment unit

- 1 VEGADIS adapter
- 2 Internal plug connection
- 3 Plug connector M12 x 1

36504-EN-170405

## Assignment of the plug connector

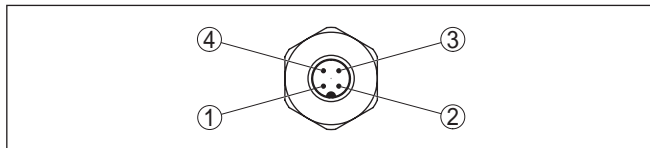


Fig. 28: View to the plug connector M12 x 1

- 1 Pin 1
- 2 Pin 2
- 3 Pin 3
- 4 Pin 4

Contact pin	Colour, connection cable in the sensor	Terminal, electronics module
Pin 1	Brown	5
Pin 2	White	6
Pin 3	Blue	7
Pin 4	Black	8

## 5.5 Switch-on phase

After connecting the instrument to power supply or after a voltage recurrence, the instrument carries out a self-check for approx. 30 s:

- Internal check of the electronics
- Indication of the instrument type, hardware and software version, measurement loop name on the display or PC
- Indication of the status message "*F 105 Determine measured value*" on the display or PC
- The output signal jumps to the set fault current

As soon as a plausible measured value is found, the corresponding current is outputted to the signal cable. The value corresponds to the actual level as well as the settings already carried out, e.g. factory setting.

## 6 Set up with the display and adjustment module

### 6.1 Insert display and adjustment module

The display and adjustment module can be inserted into the sensor and removed again at any time. You can choose any one of four different positions - each displaced by 90°. It is not necessary to interrupt the power supply.

Proceed as follows:

1. Unscrew the housing lid
2. Place the display and adjustment module on the electronics in the desired position and turn it to the right until it snaps in.
3. Screw housing lid with inspection window tightly back on

Disassembly is carried out in reverse order.

The display and adjustment module is powered by the sensor, an additional connection is not necessary.



*Fig. 29: Installing the display and adjustment module in the electronics compartment of the single chamber housing*

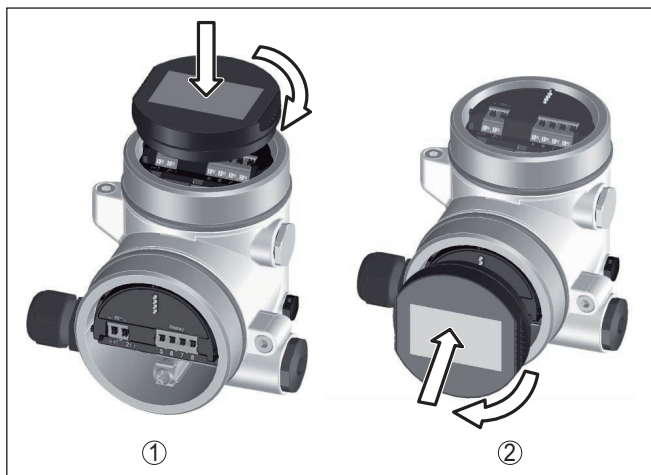


Fig. 30: Installing the display and adjustment module in the double chamber housing

- 1 In the electronics compartment
- 2 In the terminal compartment



#### Note:

If you intend to retrofit the instrument with a display and adjustment module for continuous measured value indication, a higher lid with an inspection glass is required.

## 6.2 Adjustment system

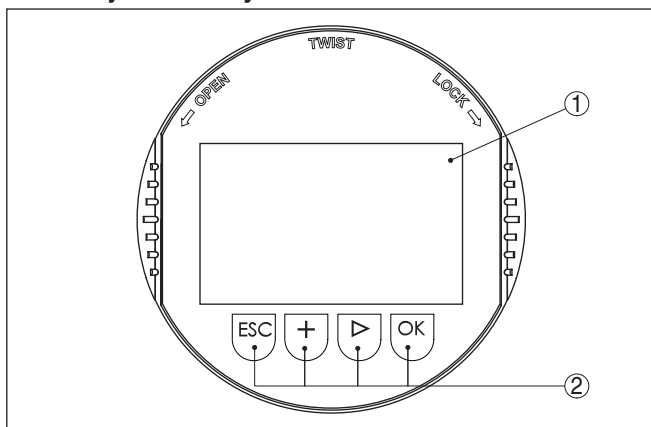


Fig. 31: Display and adjustment elements

- 1 LC display
- 2 Adjustment keys

### Key functions

- **[OK]** key:

- Move to the menu overview
  - Confirm selected menu
  - Edit parameter
  - Save value
- **[>]** key:
    - Change measured value presentation
    - Select list entry
    - Select menu items in the quick setup menu
    - Select editing position
  - **[+]** key:
    - Change value of the parameter
  - **[ESC]** key:
    - Interrupt input
    - Jump to next higher menu

### Operating system - Keys direct

The instrument is operated via the four keys of the display and adjustment module. The individual menu items are shown on the LC display. You can find the function of the individual keys in the previous illustration.

### Adjustment system - keys via magnetic pen

With the Bluetooth version of the display and adjustment module you can also adjust the instrument with the magnetic pen. The pen operates the four keys of the display and adjustment module right through the closed lid (with inspection window) of the sensor housing.

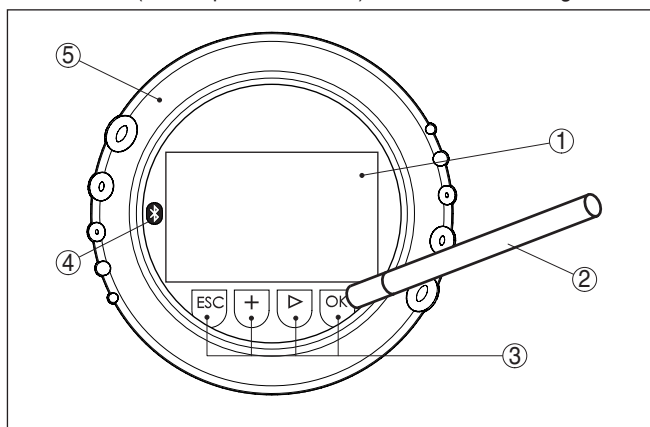


Fig. 32: Display and adjustment elements - with adjustment via magnetic pen

- 1 LC display
- 2 Magnetic pen
- 3 Adjustment keys
- 4 Bluetooth symbol
- 5 Lid with inspection window



## Time functions

When the **[+]** and **[->]** keys are pressed quickly, the edited value, or the cursor, changes one value or position at a time. If the key is pressed longer than 1 s, the value or position changes continuously.

When the **[OK]** and **[ESC]** keys are pressed simultaneously for more than 5 s, the display returns to the main menu. The menu language is then switched over to "English".

Approx. 60 minutes after the last pressing of a key, an automatic reset to measured value indication is triggered. Any values not confirmed with **[OK]** will not be saved.

## 6.3 Measured value indication - Selection of national language

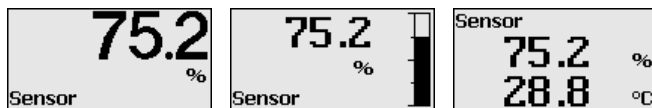
### Measured value indication

With the **[->]** key you move between three different indication modes.

In the first view, the selected measured value is displayed in large digits.

In the second view, the selected measured value and a corresponding bar graph presentation are displayed.

In the third view, the selected measured value as well as a second selectable value, e.g. the temperature of the electronics, are displayed.



During the initial setup of an instrument shipped with factory settings, use the **"OK"** key to get to the menu "National language".

### Selection of national language

This menu item is used to select the national language for further parameter adjustment. You can change the selection via the menu item "Setup - Display, Menu language".



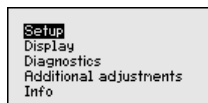
With the **"OK"** key you move to the main menu.

## 6.4 Parameter adjustment

The instrument is adapted to the application conditions via the parameter adjustment. The parameter adjustment is carried out with an adjustment menu.

### Main menu

The main menu is divided into five sections with the following functions:



**Setup:** Settings, e.g., for measurement loop name, medium, application, vessel, adjustment, signal output

**Display:** Settings, e.g., for language, measured value display, lighting

**Diagnosis:** Information, e.g. on instrument status, pointer, measurement certainty, simulation, echo curve

**Further settings:** Instrument unit, false signal suppression, linearisation curve, reset, date/time, reset, copy function

**Info:** Instrument name, hardware and software version, date of manufacture, instrument features



### Information:

In this operating instructions manual, the instrument-specific parameters in the menu sections "*Setup*", "*Diagnosis*" and "*Additional settings*" are described. The general parameters in these menu sections are described in the operating instructions manual "*Display and adjustment module*".

In the operating instructions manual "*Display and adjustment module*" you can also find the description of menu sections "*Display*" and "*Info*".

In the main menu item "*Setup*", the individual submenu items should be selected one after the other and provided with the correct parameters to ensure optimum adjustment of the measurement. The procedure is described in the following.

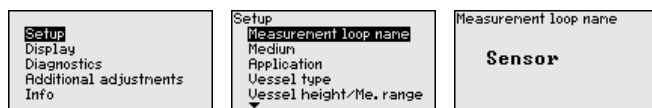
## Setup - Measurement loop name

In the menu item "*Sensor TAG*" you edit a twelve-digit measurement loop designation.

You can enter an unambiguous designation for the sensor, e.g. the measurement loop name or the tank or product designation. In digital systems and in the documentation of larger plants, a singular designation must be entered for exact identification of individual measuring points.

The available digits include:

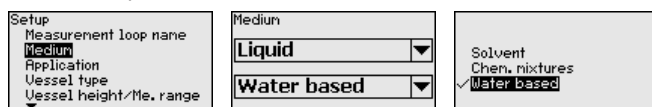
- Letters from A ... Z
- Numbers from 0 ... 9
- Special characters +, -, /, -

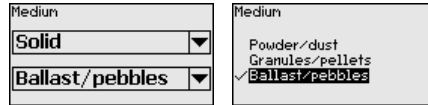


## Setup - Medium

Every medium has different reflective properties. With liquids, there are additional interfering factors such as turbulent product surface and foam generation. With bulk solids, the additional interfering factors are dust generation, angle of repose and secondary echoes from the vessel wall.

To adapt the sensor to these different measuring conditions, the selection "*Liquid*" or "*Bulk solid*" should be made in this menu item.





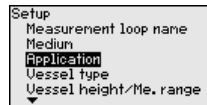
Through this selection, the sensor is optimally adapted to the product, and measurement certainty, particularly in products with poor reflective properties, is considerably increased.

Enter the requested parameters via the appropriate keys, save your settings with **[OK]** and jump to the next menu item with the **[ESC]** and the **[→]** key.

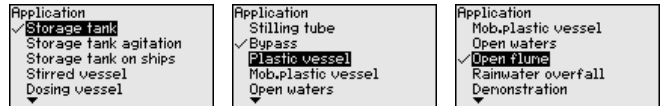
## Setup - Application

In addition to the medium, also the application, i.e. the measuring site, can influence the measurement.

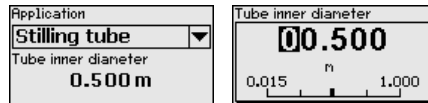
With this menu item, the sensor can be adapted to the applications. The adjustment possibilities depend on the selection "Liquid" or "Bulk solid" under "Medium".



The following options are available when "Liquid" is selected:



The selection "Standpipe" opens a new window in which the inner diameter of the applied standpipe is entered.



Following the characteristics of the applications and the metrological features of the sensor are described.



### Note:

Probably the operation of the instrument in these applications is subject to national restrictions in respect to the radio license (see chapter "For your safety"):

- Plastic tank
- Transportable plastic tank
- Open water (gauge measurement)
- Open flume (flow measurement)
- Rain water overfall (weir)

### Storage tank:

- Setup: large-volumed, upright cylindrical, spherical
- Medium speed: slow filling and emptying
- Process/measurement conditions:

- Condensation
- Smooth product surface
- High requirements on measurement accuracy
- Properties, sensor:
  - Low sensitivity to sporadic false echoes
  - Stable and reliable measured values through averaging
  - High accuracy
  - Short reaction time of the sensor not required

**Storage tank with product circulation:**

- Setup: large-volumed, upright cylindrical, spherical
- Medium speed: slow filling and emptying
- Installations: small, laterally mounted or large, top mounted stirrer
- Process/measurement conditions:
  - Relatively smooth product surface
  - High requirements on measurement accuracy
  - Condensation
  - Slight foam generation
  - Overfilling possible
- Properties, sensor:
  - Low sensitivity to sporadic false echoes
  - Stable and reliable measured values through averaging
  - High accuracy, because not set for max. speed
  - False signal suppression recommended

**Storage tank on ships (Cargo Tank):**

- Medium speed: slow filling and emptying
- Vessel:
  - Installations in the bottom section (bracers, heating spirals)
  - High sockets 200 ... 500 mm, also with large diameters
- Process/measurement conditions:
  - Condensation, buildup by movement
  - Max. requirement on measurement accuracy from 95 %
- Properties, sensor:
  - Low sensitivity to sporadic false echoes
  - Stable and reliable measured values through averaging
  - High accuracy
  - False signal suppression required

**Stirrer vessel (reactor):**

- Setup: all vessel sizes possible
- Medium speed:
  - Fast to slow filling possible
  - Vessel is filled and emptied very often
- Vessel:
  - Socket available
  - Large agitator blades of metal
  - Vortex breakers, heating spirals
- Process/measurement conditions:
  - Condensation, buildup by movement
  - Strong spout generation
  - Very agitated surface, foam generation
- Properties, sensor:

- Higher measurement speed through less averaging
- Sporadic false echoes are suppressed

**Dosing vessel:**

- Setup: all vessel sizes possible
- Medium speed:
  - Fast filling and emptying
  - Vessel is filled and emptied very often
- Vessel: tight installation situation
- Process/measurement conditions:
  - Condensation, buildup on the antenna
  - Foam generation
- Properties, sensor:
  - Measurement speed optimized by virtually no averaging
  - Sporadic false echoes are suppressed
  - False signal suppression recommended

**Standpipe:**

- Medium speed: very fast filling and emptying
- Vessel:
  - Vent hole
  - Joins like flanges, weld joints
  - Shifting of the running time in the tube
- Process/measurement conditions:
  - Condensation
  - Buildup
- Properties, sensor:
  - Measurement speed optimized through little averaging
  - Entering the tube inside diameter takes the running time shift into consideration
  - Echo detection sensitivity reduced

**Bypass:**

- Medium speed:
  - Fast up to slow filling with short up to long bypass tube possible
  - Often the level is hold via a control facility
- Vessel:
  - Lateral outlets and inlets
  - Joins like flanges, weld joints
  - Shifting of the running time in the tube
- Process/measurement conditions:
  - Condensation
  - Buildup
  - Separation of oil and water possible
  - Overfilling into the antenna possible
- Properties, sensor:
  - Measurement speed optimized through little averaging
  - Entering the tube inside diameter takes the running time shift into consideration
  - Echo detection sensitivity reduced
  - False signal suppression recommended

**Plastic tank:**

- Vessel:
  - Instrument fix mounted or built in
  - Measurement through the vessel top, if appropriate to the application
  - With empty vessel, the measurement can go through the bottom
- Process/measurement conditions:
  - Condensation on the plastic ceiling
  - In outdoor facilities, water and snow on vessel top possible
- Properties, sensor:
  - False signals outside the vessel are not taken into consideration
  - False signal suppression recommended

**Transportable plastic tank:**

- Vessel:
  - Material and thickness different
  - Measurement through the vessel top
- Process/measurement conditions:
  - Measured value jump with vessel change
- Properties, sensor:
  - Quick adaptation to changing reflection conditions due to vessel change
  - False signal suppression required

**Open water (gauge measurement):**

- Rate of level change: slow level change
- Process/measurement conditions:
  - Large distance from sensor to water surface
  - Extreme damping of output signal due to wave generation
  - Ice and condensation on the antenna possible
  - Spiders and insects build nests in the antennas
  - Floating material and animals sporadically appear on water surface
- Properties, sensor:
  - Stable and reliable measured values through frequent averaging
  - Insensitive in the close range

**Open flume (flow measurement):**

- Rate of level change: slow level change
- Process/measurement conditions:
  - Ice and condensation on the antenna possible
  - Spiders and insects build nests in the antennas
  - Smooth water surface
  - Exact measurement result required
  - Distance to the water surface normally relatively large
- Properties, sensor:
  - Stable and reliable measured values through frequent averaging
  - Insensitive in the close range

### Rain water overflow (weir):

- Rate of level change: slow level change
- Process/measurement conditions:
  - Ice and condensation on the antenna possible
  - Spiders and insects build nests in the antennas
  - Turbulent water surface
  - Sensor flooding possible
- Properties, sensor:
  - Stable and reliable measured values through frequent averaging
  - Insensitive in the close range

### Demonstration:

- Adjustment for all applications which are not typically level measurement
  - Instrument demonstration
  - Object recognition/monitoring (additional settings required)
- Properties, sensor:
  - Sensor accepts all measured value changes within the measuring range immediately
  - High sensitivity to interference, because virtually no averaging



### Caution:

If liquids with different dielectric constants separate in the vessel, for example through condensation, the radar sensor can detect under certain circumstances only the medium with the higher dielectric constant. Keep in mind that layer interfaces can cause faulty measurements.

If you want to measure the total height of both liquids reliably, please contact our service department or use an instrument specially designed for interface measurement.

## Setup - Vessel form

Apart from the medium and the application, the vessel form itself can influence the measurement. To adapt the sensor to these measuring conditions, this menu item offers different options for vessel bottom and ceiling for certain applications.

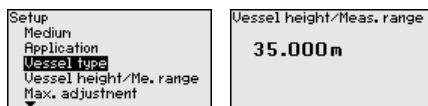
Setup Medium Application <b>Vessel type</b> Vessel height/Me. range Max. adjustment ▼	Vessel bottom ✓ <b>Straight</b> Conical Angular	Vessel top Straight ✓ <b>Dished boiler</b>
---	--	--

Enter the requested parameters via the appropriate keys, save your settings with **[OK]** and jump to the next menu item with the **[ESC]** and the **[→]** key.

## Setup - Vessel height, measuring range

Through this selection the operating range of the sensor is adapted to the vessel height, which considerably increases measurement certainty under different basic conditions.

The min. adjustment must be carried out independently of this.



Enter the requested parameters via the appropriate keys, save your settings with **[OK]** and jump to the next menu item with the **[ESC]** and the **[→]** key.

## Setup - Adjustment

Since the radar sensor is a distance measuring instrument, the distance from the sensor to the product surface is measured. To indicate the actual level, an allocation of the measured distance to the percentage height must be carried out.

To perform the adjustment, enter the distance with full and empty vessel, see the following example:

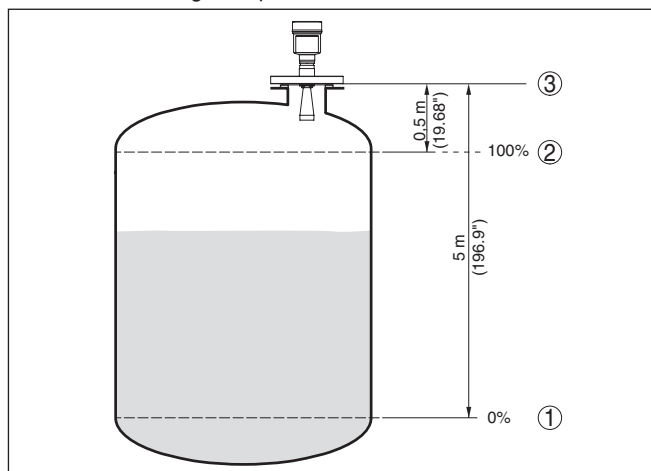


Fig. 33: Parameterisation example, Min./max. adjustment

- 1 Min. level = max. measuring distance
- 2 Max. level = min. measuring distance
- 3 Reference plane

If these values are not known, an adjustment with the distances of e.g. 10 % and 90 % is possible. Starting point for these distance specifications is always the sealing surface of the thread or flange. You can find specifications on the reference plane in chapter "Technical data". The actual level is calculated on the basis of these settings.

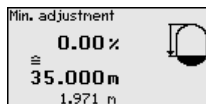
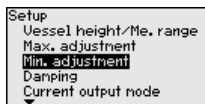
The actual product level during this adjustment is not important, because the min./max. adjustment is always carried out without changing the product level. These settings can be made ahead of time without the instrument having to be installed.

## Setup - Min. adjustment

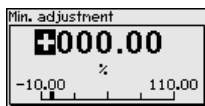
Proceed as follows:

1. Select the menu item "Setup" with **[→]** and confirm with **[OK]**. Now select with **[→]** the menu item "Min. adjustment" and confirm with **[OK]**.

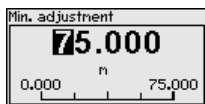




2. Edit the percentage value with **[OK]** and set the cursor to the requested position with **[>]**.



3. Set the requested percentage value with **[+]** and save with **[OK]**.  
The cursor jumps now to the distance value.

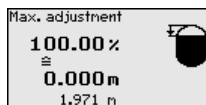
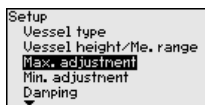


4. Enter the suitable distance value in m for empty vessel (e.g. distance from the sensor to the vessel bottom) corresponding to the percentage value.
5. Save settings with **[OK]** and move with **[ESC]** and **[>]** to the max. adjustment.

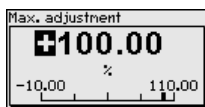
## Setup - Max. adjustment

Proceed as follows:

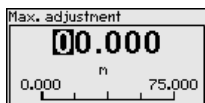
1. Select with **[>]** the menu item Max. adjustment and confirm with **[OK]**.



2. Prepare the percentage value for editing with **[OK]** and set the cursor to the requested position with **[>]**.



3. Set the requested percentage value with **[+]** and save with **[OK]**.  
The cursor jumps now to the distance value.



4. Enter the appropriate distance value in m (corresponding to the percentage value) for the full vessel. Keep in mind that the max. level must lie below the min. distance to the antenna edge.
5. Save settings with **[OK]**

## Setup - Damping

To damp process-dependent measured value fluctuations, set an integration time of 0 ... 999 s in this menu item.

Setup Display Diagnostics Additional adjustments Info	Setup Max. adjustment Min. adjustment Damping Current output mode Current output min./max. ▼	Integration time  0 s
---	--	-----------------------------

Depending on the sensor type, the factory setting is 0 s or 1 s.

### Setup - Current output, mode

In the menu item "Current output mode" you determine the output characteristics and reaction of the current output in case of failure.

Setup Display Diagnostics Additional adjustments Info	Setup Measurement loop name Medium Application Vessel type Vessel height/Me. range ▼	Current output mode Output characteristics 4 ... 20 mA Failure mode < 3.6 mA
Output characteristics ✓ 4 ... 20 mA 20 ... 4 mA	Failure mode 22.0 nA 20.5 nA No change ✓ < 3.6 mA	

The default setting is output characteristics 4 ... 20 mA, fault mode < 3.6 mA.

### Setup - Current output Min./Max.

In the menu item "Current output Min./Max.", you determine the reaction of the current output during operation.

Setup Display Diagnostics Additional adjustments Info	Setup Damping Current output mode Current output min./max. Lock adjustment ▼	Current output min./max. Min. current 3.8 mA Max. current 20.5 mA
Min. current ✓ 3.8 mA 4 mA	Max. current 20 nA ✓ 20.5 mA	

The default setting is min. current 3.8 mA and max. current 20.5 mA.

### Setup - Lock adjustment

In this menu item, the PIN is activated/deactivated permanently. Entering a 4-digit PIN protects the sensor data against unauthorized access and unintentional modifications. If the PIN is activated permanently, it can be deactivated temporarily (i.e. for approx. 60 min.) in any menu item.

Setup Display Diagnostics Additional adjustments Info	Setup Current output mode Current output min./max. Lock adjustment ----- Measurement loop name ▼	PIN  Released  Lock?
---	--	----------------------------------

Only the following functions are permitted with activated PIN:

- Select menu items and show data
- Read data from sensor into the display and adjustment module.



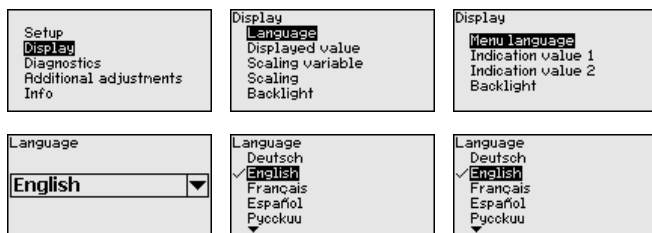
#### Caution:

When the PIN is active, adjustment via PACTware/DTM as well as other systems is also blocked.

In delivery status, the PIN is "0000".

## Display - Language

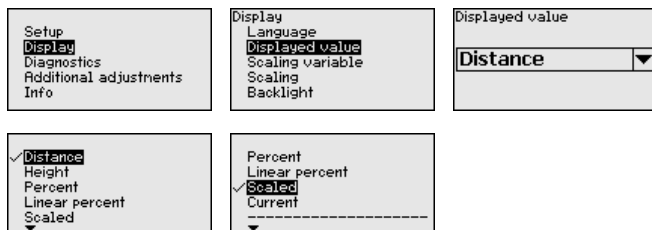
This menu item enables the setting of the requested national language.



In delivery status, the sensor is set to the ordered national language.

## Display - Indicated value

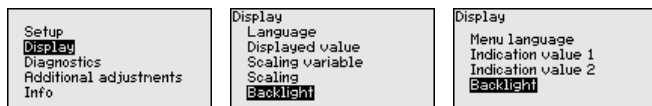
In this menu item you can define the indication of the measured value on the display.



The default setting for the indicated value is e.g. "Distance" on radar sensors.

## Display - Backlight

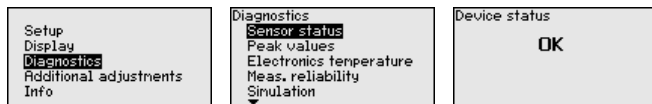
The optionally integrated background lighting can be switched on via the adjustment menu. This function depends on the level of the supply voltage, see operating instructions of the respective sensor.



In delivery status, the lighting is switched on.

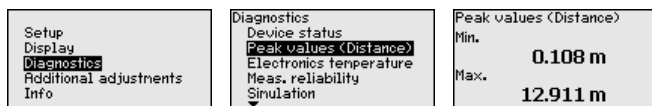
## Diagnostics - Device status

In this menu item, the device status is displayed.



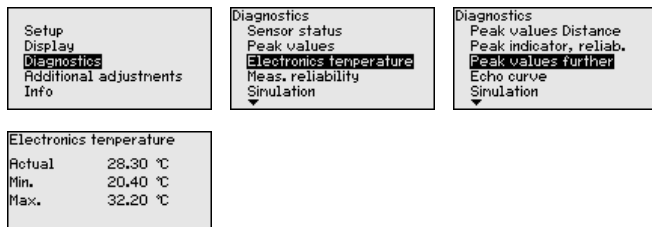
## Diagnostics - Peak values (distance)

The respective min. and max. measured distance values are saved in the sensor. The values are displayed in the menu item "Peak values".



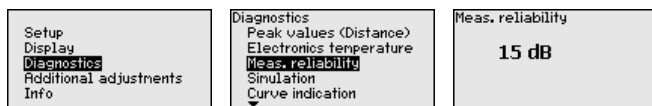
## Diagnosis - Electronics temperature

The respective min. and max. measured values of the electronics temperature are saved in the sensor. These values as well as the current temperature value are displayed in the menu item "Peak values".



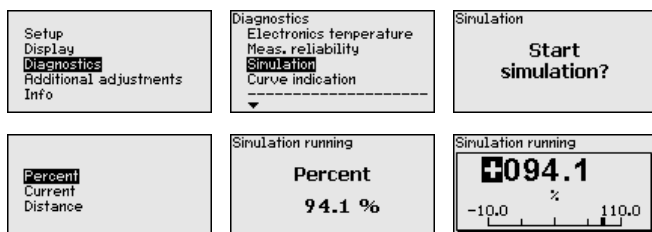
## Diagnosis - Measurement reliability

When non-contact level sensors are used, the measurement can be influenced by the respective process conditions. In this menu item, the measurement certainty of the level echo is displayed as a dB value. Measurement reliability equals signal strength minus noise. The higher the value, the more reliable the measurement. A well functioning measurement normally has a value > 10 dB.



## Diagnosis - Simulation

In this menu item you can simulate measured values via the current output. This allows the signal path to be tested, e.g. through downstream indicating instruments or the input card of the control system.



How to start the simulation:

1. Push **[OK]**
2. Select the requested simulation variable with **[>]** and confirm with **[OK]**.
3. With **[OK]** you start the simulation, first of all the actual measured value is displayed in %
4. Start the editing mode with **[OK]**
5. Set the requested numerical value with **[+]** and **[>]**.
6. Push **[OK]**



### Note:

During simulation, the simulated value is outputted as 4 ... 20 mA current value and digital HART signal.

How to interrupt the simulation:

→ Push **[ESC]**

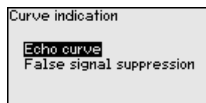
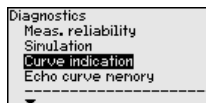
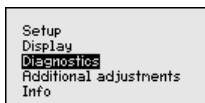


**Information:**

The simulation is automatically terminated 10 minutes after the last pressing of a key.

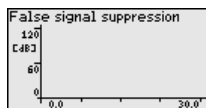
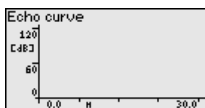
**Diagnosis - Curve indication**

The "Echo curve" shows the signal strength of the echoes over the measuring range in dB. The signal strength enables an evaluation of the quality of the measurement.



The "False signal suppression" displays the saved false echoes (see menu "Additional settings") of the empty vessel with signal strength in "dB" over the entire measuring range.

A comparison of echo curve and false signal suppression allows a more detailed statement about measurement reliability.



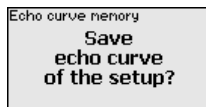
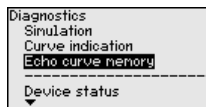
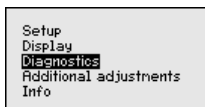
The selected curve is continuously updated. A submenu with zoom functions is opened with the **[OK]** key:

- "X-Zoom": Zoom function for the meas. distance
- "Y-Zoom": 1, 2, 5 and 10x signal magnification in "dB"
- "Unzoom": Reset the presentation to the nominal measuring range without magnification

**Diagnostics - Echo curve memory**

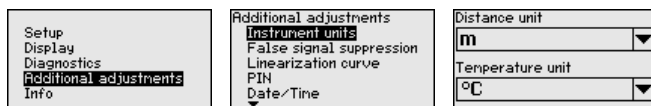
The function "Echo curve memory" makes it possible to save the echo curve at the time of setup. This is generally recommended, and it is absolutely necessary if you want to use the Asset Management functions. If possible, the curve should be saved with a low level in the vessel.

With the adjustment software PACTware and a PC, a high resolution echo curve can be displayed and used to recognize signal changes during operation. In addition, the echo curve of setup can be displayed in the echo curve window and compared with the current echo curve.



**Additional adjustments - Instrument units**

In this menu item you select the measured variable of the system and the temperature unit.



### Additional settings - False signal suppression

The following circumstances cause interfering reflections and can influence the measurement:

- High mounting sockets
- Vessel internals such as struts
- Agitators
- Buildup or welded joints on vessel walls



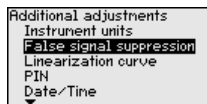
#### Note:

A false signal suppression detects, marks and saves these false signals to ensure that they are ignored in the level measurement.

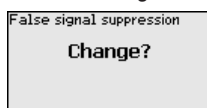
This should be done with the lowest possible level so that all potential interfering reflections can be detected.

Proceed as follows:

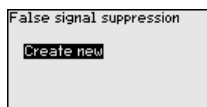
1. Select with **[>]** the menu item "False signal suppression" and confirm with **[OK]**.



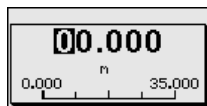
2. Confirm again with **[OK]**.



3. Confirm again with **[OK]**.



4. Confirm again with **[OK]** and enter the actual distance from the sensor to the product surface.



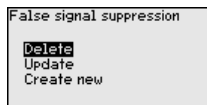
5. All interfering signals in this range are detected by the sensor and stored after being confirmed with **[OK]**.



#### Note:

Check the distance to the product surface, because if an incorrect (too large) value is entered, the existing level will be saved as a false signal. The level would then no longer be detectable in this area.

If a false signal suppression has already been saved in the sensor, the following menu window appears when selecting "*False signal suppression*":



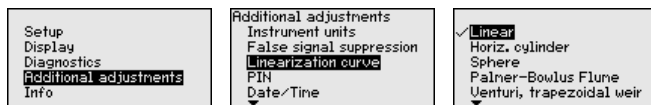
**Delete:** An already created false signal suppression will be completely deleted. This is useful if the saved false signal suppression no longer matches the metrological conditions in the vessel.

**Extend:** is used to extend an already created false signal suppression. This is useful if a false signal suppression was carried out with too high a level and not all false signals could be detected. When selecting "*Extend*", the distance to the product surface of the created false signal suppression is displayed. This value can now be changed and the false signal suppression can be extended to this range.

### Additional settings - Linearization

A linearization is necessary for all vessels in which the vessel volume does not increase linearly with the level - e.g. a horizontal cylindrical or spherical tank - and the indication or output of the volume is required. Corresponding linearization curves are preprogrammed for these vessels. They represent the correlation between the level percentage and vessel volume.

By activating the appropriate curve, the volume percentage of the vessel is displayed correctly. If the volume should not be displayed in percent but e.g. in l or kg, a scaling can be also set in the menu item "*Display*".



Enter the requested parameters via the appropriate keys, save your settings and jump to the next menu item with the **[ESC]** and **[>]** key.



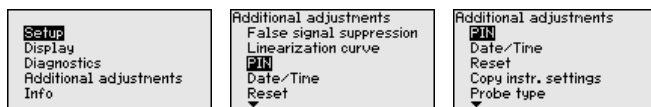
### Caution:

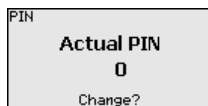
Note the following if instruments with appropriate approval are used as part of an overfill protection system according to WHG:

If a linearisation curve is selected, the measuring signal is no longer necessarily linear to the filling height. This must be considered by the user especially when setting the switching point on the limit signal transmitter.

### Additional settings - PIN

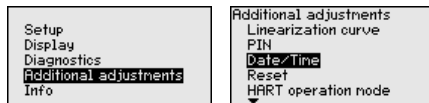
Entering a 4-digit PIN protects the sensor data against unauthorized access and unintentional modification. In this menu item, the PIN is displayed or edited and changed. However, this menu item is only available if adjustment is enabled in the menu "*Setup*".





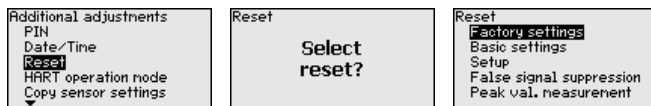
In delivery status, the PIN is "0000".

**Additional settings - Date/Time** In this menu item, the internal clock of the sensor is set.



**Additional settings - Reset**

After a reset, certain parameter adjustments made by the user are reset.



The following reset functions are available:

**Delivery status:** Restores the parameter settings at the time of shipment from the factory, incl. order-specific settings. Any stored false signal suppression or user-programmed linearisation curve, as well as the measured value memory, are deleted.

**Basic settings:** Restores the parameter settings, incl. special parameters, to the default values of the respective instrument. Any stored false signal suppression or user-programmed linearisation curve, as well as the measured value memory, are deleted.

**Setup:** Restores the parameter settings made in the menu item Setup to the default values of the respective instrument. False signal suppression, user-programmed linearisation curve, measured value memory and event memory remain untouched. The linearisation is set to linear.

**False signal suppression:** Deletes a previously created false signal suppression. The false signal suppression created at the factory remains active.

**Peak values, measured value:** Resets the measured min. and max. distances to the current measured value.

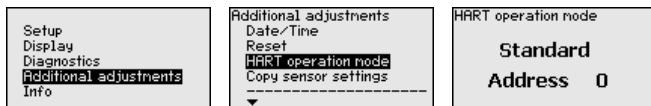
The following table shows the default values of the instrument. Depending on the instrument version, not all menu items are available or some may be differently assigned:



Menu	Menu item	Default value
Setup	Measurement loop name	Sensor
	Medium	Liquid/Water Bulk solids/Crushed stones, gravel
	Application	Storage tank Silo
	Vessel form	Vessel bottom, dished form Vessel top, dished form
	Vessel height/Measuring range	Recommended measuring range, see "Technical data" in the supplement
	Min. adjustment	Recommended measuring range, see "Technical data" in the supplement
	Max. adjustment	0,000 m(d)
	Damping	0.0 s
	Current output mode	4 ... 20 mA, < 3.6 mA
	Current output, min./max.	Min. current 3.8 mA, max. current 20.5 mA
	Lock adjustment	Released
Display	Language	Like order
	Displayed value	Distance
	Display unit	m
	Scaling size	Volume l
	Scaling	0.00 lin %, 0 l 100.00 lin %, 100 l
	Backlight	Switched on
Additional settings	Distance unit	m
	Temperature unit	°C
	Probe length	Length of standpipe ex factory
	Linearisation curve	Linear
	HART mode	Standard Address 0

### Additional settings - HART mode

The sensor offers the HART modes standard and Multidrop. In this menu item you specify the HART mode and enter the address for Multidrop.



The mode "standard" with the fixed address 0 means outputting the measured value as a 4 ... 20 mA signal.

In Multidrop mode, up to 63 sensors can be operated on one two-wire cable. An address between 1 and 63 must be assigned to each sensor.<sup>2)</sup>

The default setting is standard with address 0.

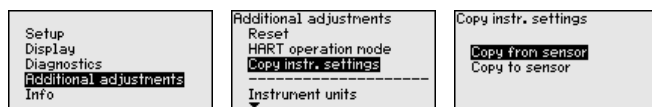
### Additional settings - Copy instrument settings

The instrument settings are copied with this function. The following functions are available:

- Store data from sensor in the display and adjustment module.
- Store data from display and adjustment module in the sensor

The following data or settings for adjustment of the display and adjustment module are saved:

- All data of the menu "Setup" and "Display"
- In the menu "Additional settings" the items "Distance unit, temperature unit and linearization"
- The values of the user-programmable linearisation curve



The copied data are permanently saved in an EEPROM memory in the display and adjustment module and remain there even in case of power failure. From there, they can be written into one or more sensors or kept as backup for a possible sensor exchange.

The type and the volume of the copied data depend on the respective sensor.

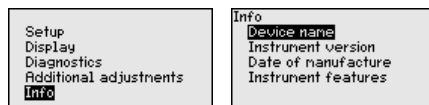


#### Note:

Before the data are stored in the sensor, a check is carried out to determine if the data fit the sensor. If the data do not fit, a fault signal is triggered or the function is blocked. When data are being written into the sensor, the display shows which instrument type the data originate from and which TAG-no. this sensor had.

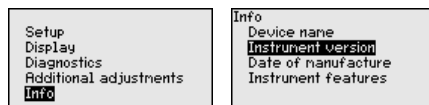
### Info - Instrument name

In this menu, you read out the instrument name and the instrument serial number:



### Info - Instrument version

In this menu item, the hardware and software version of the sensor is displayed.



<sup>2)</sup> The 4 ... 20 mA signal of the sensor is switched off. The sensor uses a constant current of 4 mA. The measuring signal is transmitted exclusively as a digital HART signal.

**Info - Date of manufacture** In this menu item, the date of factory calibration of the sensor as well as the date of the last change of sensor parameters are displayed via the display and adjustment module or via the PC.

Setup Display Diagnostics Additional adjustments <b>Info</b>	Info Device name Instrument version <b>Date of manufacture</b> Instrument features	Factory calibration date <b>3. Aug 2012</b> Last change <b>29. Nov 2012</b>
--	--	--

**Instrument features** In this menu item, the features of the sensor such as approval, process fitting, seal, measuring range, electronics, housing and others are displayed.

Setup Display Diagnostics Additional adjustments <b>Info</b>	Info Device name Instrument version Date of manufacture <b>Instrument features</b>	Instrument features <b>Display now?</b>
--	--	--

## 6.5 Saving the parameterisation data

**Backup on paper** We recommended writing down the adjustment data, e.g. in this operating instructions manual, and archiving them afterwards. They are thus available for multiple use or service purposes.

**Backup in the display and adjustment module** If the instrument is equipped with a display and adjustment module, the data in the sensor can be saved in the display and adjustment module. The procedure is described in menu item "*Copy device settings*" in the menu "*Additional settings*". The data remain there permanently even if the sensor power supply fails.

The following data or settings for adjustment of the display and adjustment module are saved:

- All data of the menu "*Setup*" and "*Display*"
- The items "*Sensor-specific units, temperature unit and linearisation*" in the menu "*Additional settings*".
- The values of the user-programmable linearisation curve

The function can also be used to transfer settings from one instrument to another instrument of the same type. If it is necessary to exchange a sensor, the display and adjustment module is inserted into the replacement instrument and the data are likewise written into the sensor via the menu item "*Copy device settings*".

## 7 Setup with PACTware

### 7.1 Connect the PC

Via the interface adapter directly on the sensor



Fig. 34: Connection of the PC directly to the sensor via the interface adapter

- 1 USB cable to the PC
- 2 Interface adapter VEGACONNECT
- 3 Sensor

### Connection via HART

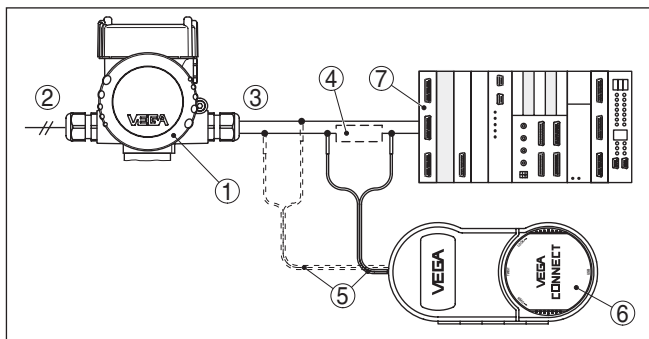


Fig. 35: Connecting the PC via HART to the signal cable

- 1 VEGAPULS 62
- 2 Voltage supply
- 3 4 ... 20 mA signal output
- 4 HART resistance approx. 250  $\Omega$  (optional depending on processing)
- 5 Connection cable with 2 mm pins and terminals
- 6 VEGACONNECT
- 7 Processing system/PLC

Necessary components:

- VEGAPULS 62

- PC with PACTware and suitable VEGA DTM
- VEGACONNECT
- HART resistance approx. 250  $\Omega$
- Processing system/PLC


**Note:**

With power supply units with integrated HART resistance (internal resistance approx. 250  $\Omega$ ), an additional external resistance is not necessary. This applies, e.g. to the VEGA instruments VEGATRENN 149A, VEGAMET 381 and VEGAMET 391). Commercially available Ex separators are also usually equipped with sufficient current limitation resistance. In such cases, VEGACONNECT can be connected parallel to the 4 ... 20 mA cable.

**Prerequisites**

## 7.2 Parameter adjustment

For parameter adjustment of the instrument via a Windows PC, the configuration software PACTware and a suitable instrument driver (DTM) according to FDT standard are required. The latest PACTware version as well as all available DTMs are compiled in a DTM Collection. The DTMs can also be integrated into other frame applications according to FDT standard.


**Note:**

To ensure that all instrument functions are supported, you should always use the latest DTM Collection. Furthermore, not all described functions are included in older firmware versions. You can download the latest instrument software from our homepage. A description of the update procedure is also available in the Internet.

Further setup steps are described in the operating instructions manual "*DTM Collection/PACTware*" attached to each DTM Collection and which can also be downloaded from the Internet. Detailed descriptions are available in the online help of PACTware and the DTMs.

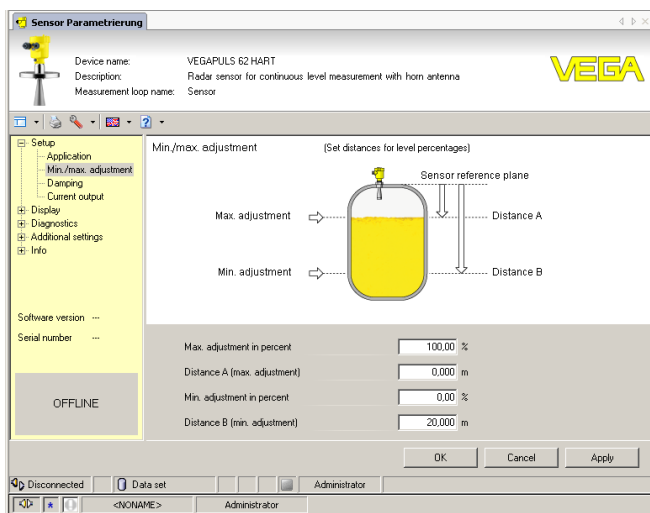


Fig. 36: Example of a DTM view

## Standard/Full version

All device DTMs are available as a free-of-charge standard version and as a full version that must be purchased. In the standard version, all functions for complete setup are already included. An assistant for simple project configuration simplifies the adjustment considerably. Saving/printing the project as well as import/export functions are also part of the standard version.

In the full version there is also an extended print function for complete project documentation as well as a save function for measured value and echo curves. In addition, there is a tank calculation program as well as a multiviewer for display and analysis of the saved measured value and echo curves.

The standard version is available as a download under [www.vega.com/downloads](http://www.vega.com/downloads) and "Software". The full version is available on CD from the agency serving you.

## 7.3 Saving the parameterisation data

We recommend documenting or saving the parameterisation data via PACTware. That way the data are available for multiple use or service purposes.

## 8 Set up with other systems

### 8.1 DD adjustment programs

Device descriptions as Enhanced Device Description (EDD) are available for DD adjustment programs such as, for example, AMS™ and PDM.

The files can be downloaded at [www.vega.com/downloads](http://www.vega.com/downloads) under "Software".

### 8.2 Field Communicator 375, 475

Device descriptions for the instrument are available as EDD for parameterisation with Field Communicator 375 or 475.

Integrating the EDD into the Field Communicator 375 or 475 requires the "Easy Upgrade Utility" software, which is available from the manufacturer. This software is updated via the Internet and new EDDs are automatically accepted into the device catalogue of this software after they are released by the manufacturer. They can then be transferred to a Field Communicator.

## 9 Diagnosis, asset management and service

### 9.1 Maintenance

If the instrument is used correctly, no maintenance is required in normal operation.

### 9.2 Measured value and event memory

The instrument has several memories available for diagnostic purposes. The data remain there even in case of voltage interruption.

#### Measured value memory

Up to 100,000 measured values can be stored in the sensor in a ring memory. Each entry contains date/time as well as the respective measured value. Storable values are for example:

- Distance
- Filling height
- Percentage value
- Lin. percent
- Scaled
- Current value
- Meas. certainty
- Electronics temperature

When the instrument is shipped, the measured value memory is active and stores distance, measurement certainty and electronics temperature every 3 minutes.

The requested values and recording conditions are set via a PC with PACTware/DTM or the control system with EDD. Data are thus read out and also reset.

#### Event memory

Up to 500 events are automatically stored with a time stamp in the sensor (non-deletable). Each entry contains date/time, event type, event description and value. Event types are for example:

- Modification of a parameter
- Switch-on and switch-off times
- Status messages (according to NE 107)
- Error messages (according to NE 107)

The data are read out via a PC with PACTware/DTM or the control system with EDD.

#### Echo curve memory

The echo curves are stored with date and time and the corresponding echo data. The memory is divided into two sections:

**Echo curve of the setup:** This is used as reference echo curve for the measurement conditions during setup. Changes in the measurement conditions during operation or buildup on the sensor can thus be recognized. The echo curve of the setup is stored via:

- PC with PACTware/DTM
- Control system with EDD
- Display and adjustment module



**Further echo curves:** Up to 10 echo curves can be stored in a ring buffer in this memory section. Additional echo curves are stored via:

- PC with PACTware/DTM
- Control system with EDD

### 9.3 Asset Management function

The instrument features self-monitoring and diagnostics according to NE 107 and VDI/VDE 2650. In addition to the status messages in the following tables, detailed error messages are available under menu item "Diagnostics" via the display and adjustment module, PACTware/DTM and EDD.

#### Status messages

The status messages are divided into the following categories:

- Failure
- Function check
- Out of specification
- Maintenance requirement

and explained by pictographs:

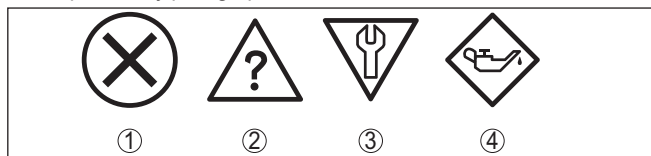


Fig. 37: Pictographs of the status messages

- 1 Failure - red
- 2 Out of specification - yellow
- 3 Function check - orange
- 4 Maintenance - blue

**Failure:** Due to a malfunction in the instrument, a fault message is outputted.

This status message is always active. It cannot be deactivated by the user.

**Function check:** The instrument is being worked on, the measured value is temporarily invalid (for example during simulation).

This status message is inactive by default. It can be activated by the user via PACTware/DTM or EDD.

**Out of specification:** The measured value is unreliable because an instrument specification was exceeded (e.g. electronics temperature).

This status message is inactive by default. It can be activated by the user via PACTware/DTM or EDD.

**Maintenance:** Due to external influences, the instrument function is limited. The measurement is affected, but the measured value is still valid. Plan in maintenance for the instrument because a failure is expected in the near future (e.g. due to buildup).

This status message is inactive by default. It can be activated by the user via PACTware/DTM or EDD.

**Failure**

The following table shows the error codes in the status message "Failure" and gives information on the reason and rectification. Keep in mind that some information is only valid for four-wire instruments.

Code Text message	Reason	Rectification	DevSpec State in CMD 48
F013 no measured value available	<ul style="list-style-type: none"> <li>● Sensor does not detect an echo during operation</li> <li>● Antenna system dirty or defective</li> </ul>	<ul style="list-style-type: none"> <li>● Check or correct installation and/or parameter settings</li> <li>● Clean or exchange process component or antenna</li> </ul>	Bit 0 of Byte 0 ... 5
F017 Adjustment span too small	<ul style="list-style-type: none"> <li>● Adjustment not within specification</li> </ul>	<ul style="list-style-type: none"> <li>● Change adjustment according to the limit values (difference between min. and max. <math>\geq 10</math> mm)</li> </ul>	Bit 1 of Byte 0 ... 5
F025 Error in the linearization table	<ul style="list-style-type: none"> <li>● Index markers are not continuously rising, for example illogical value pairs</li> </ul>	<ul style="list-style-type: none"> <li>● Check linearisation table</li> <li>● Delete table/Create new</li> </ul>	Bit 2 of Byte 0 ... 5
F036 No operable software	<ul style="list-style-type: none"> <li>● Failed or interrupted software update</li> </ul>	<ul style="list-style-type: none"> <li>● Repeat software update</li> <li>● Check electronics version</li> <li>● Exchanging the electronics</li> <li>● Send instrument for repair</li> </ul>	Bit 3 of Byte 0 ... 5
F040 Error in the electronics	<ul style="list-style-type: none"> <li>● Hardware defect</li> </ul>	<ul style="list-style-type: none"> <li>● Exchanging the electronics</li> <li>● Send instrument for repair</li> </ul>	Bit 4 of Byte 0 ... 5
F080 General software error	<ul style="list-style-type: none"> <li>● General software error</li> </ul>	<ul style="list-style-type: none"> <li>● Disconnect operating voltage briefly</li> </ul>	Bit 5 of Byte 0 ... 5
F105 Determine measured value	<ul style="list-style-type: none"> <li>● The instrument is still in the start phase, the measured value could not yet be determined</li> </ul>	<ul style="list-style-type: none"> <li>● Wait for the end of the switch-on phase</li> <li>● Duration up to approx. 3 minutes depending on the version and parameter settings</li> </ul>	Bit 6 of Byte 0 ... 5
F113 Communication error	<ul style="list-style-type: none"> <li>● EMC interference</li> <li>● Transmission error during external communication with 4-wire power supply unit</li> </ul>	<ul style="list-style-type: none"> <li>● Remove EMC influences</li> <li>● Exchange 4-wire power supply unit or electronics</li> </ul>	Bit 12 of Byte 0 ... 5
F125 Impermissible electronics temperature	<ul style="list-style-type: none"> <li>● Temperature of the electronics in the non-specified range</li> </ul>	<ul style="list-style-type: none"> <li>● Check ambient temperature</li> <li>● Insulate electronics</li> <li>● Use instrument with higher temperature range</li> </ul>	Bit 7 of Byte 0 ... 5
F260 Error in the calibration	<ul style="list-style-type: none"> <li>● Error in the calibration carried out in the factory</li> <li>● Error in the EEPROM</li> </ul>	<ul style="list-style-type: none"> <li>● Exchanging the electronics</li> <li>● Send instrument for repair</li> </ul>	Bit 8 of Byte 0 ... 5
F261 Error in the instrument settings	<ul style="list-style-type: none"> <li>● Error during setup</li> <li>● False signal suppression faulty</li> <li>● Error when carrying out a reset</li> </ul>	<ul style="list-style-type: none"> <li>● Repeat setup</li> <li>● Carry out a reset</li> </ul>	Bit 9 of Byte 0 ... 5
F264 Installation/Setup error	<ul style="list-style-type: none"> <li>● Adjustment not within the vessel height/measuring range</li> <li>● Max. measuring range of the instrument not sufficient</li> </ul>	<ul style="list-style-type: none"> <li>● Check or correct installation and/or parameter settings</li> <li>● Use an instrument with bigger measuring range</li> </ul>	Bit 10 of Byte 0 ... 5

Code Text message	Reason	Rectification	DevSpec State in CMD 48
F265 Measurement function disturbed	<ul style="list-style-type: none"> <li>● Sensor no longer carries out a measurement</li> <li>● Operating voltage too low</li> </ul>	<ul style="list-style-type: none"> <li>● Check operating voltage</li> <li>● Carry out a reset</li> <li>● Disconnect operating voltage briefly</li> </ul>	Bit 11 of Byte 0 ... 5

### Function check

The following table shows the error codes and text messages in the status message "*Function check*" and provides information on causes as well as corrective measures.

Code Text message	Reason	Rectification	DevSpec State in CMD 48
C700 Simulation active	<ul style="list-style-type: none"> <li>● A simulation is active</li> </ul>	<ul style="list-style-type: none"> <li>● Finish simulation</li> <li>● Wait for the automatic end after 60 mins.</li> </ul>	"Simulation Active" in "Standardized Status 0"

### Out of specification

The following table shows the error codes and text messages in the status message "*Out of specification*" and provides information on causes as well as corrective measures.

Code Text message	Reason	Rectification	DevSpec State in CMD 48
S600 Impermissible electronics temperature	<ul style="list-style-type: none"> <li>● Temperature of the electronics in the non-specified range</li> </ul>	<ul style="list-style-type: none"> <li>● Check ambient temperature</li> <li>● Insulate electronics</li> <li>● Use instrument with higher temperature range</li> </ul>	Bit 5 of Byte 14 ... 24
S601 Overfilling	<ul style="list-style-type: none"> <li>● Danger of vessel overfilling</li> </ul>	<ul style="list-style-type: none"> <li>● Make sure that there is no further filling</li> <li>● Check level in the vessel</li> </ul>	Bit 6 of Byte 14 ... 24

### Maintenance

The following table shows the error codes and text messages in the status message "*Maintenance*" and provides information on causes as well as corrective measures.

Code Text message	Reason	Rectification	DevSpec State in CMD 48
M500 Error during the reset "delivery status"	<ul style="list-style-type: none"> <li>● The data could not be restored during the reset to delivery status</li> </ul>	<ul style="list-style-type: none"> <li>● Repeat reset</li> <li>● Load XML file with sensor data into the sensor</li> </ul>	Bit 0 of Byte 14 ... 24
M501 Error in the non-active linearisation table	<ul style="list-style-type: none"> <li>● Hardware error EEPROM</li> </ul>	<ul style="list-style-type: none"> <li>● Exchanging the electronics</li> <li>● Send instrument for repair</li> </ul>	Bit 1 of Byte 14 ... 24
M502 Error in the diagnostics memory	<ul style="list-style-type: none"> <li>● Hardware error EEPROM</li> </ul>	<ul style="list-style-type: none"> <li>● Exchanging the electronics</li> <li>● Send instrument for repair</li> </ul>	Bit 2 of Byte 14 ... 24

Code Text message	Reason	Rectification	DevSpec State in CMD 48
M503 Measurement reliability too low	<ul style="list-style-type: none"> <li>● The echo/noise ratio is too small for reliable measurement</li> </ul>	<ul style="list-style-type: none"> <li>● Check installation and process conditions</li> <li>● Clean the antenna</li> <li>● Change polarisation direction</li> <li>● Use instrument with higher sensitivity</li> </ul>	Bit 3 of Byte 14 ... 24
M504 Error at a device interface	<ul style="list-style-type: none"> <li>● Hardware defect</li> </ul>	<ul style="list-style-type: none"> <li>● Check connections</li> <li>● Exchanging the electronics</li> <li>● Send instrument for repair</li> </ul>	Bit 4 of Byte 14 ... 24
M505 No echo available	<ul style="list-style-type: none"> <li>● Level echo can no longer be detected</li> </ul>	<ul style="list-style-type: none"> <li>● Clean the antenna</li> <li>● Use a more suitable antenna/sensor</li> <li>● Remove possible false echoes</li> <li>● Optimize sensor position and orientation</li> </ul>	Bit 7 of Byte 14 ... 24

## 9.4 Rectify faults

### Reaction when malfunction occurs

The operator of the system is responsible for taking suitable measures to rectify faults.

### Procedure for fault rectification

The first measures are:

- Evaluation of fault messages via the adjustment device
- Checking the output signal
- Treatment of measurement errors

Further comprehensive diagnostics options are available with a PC with PACTware and the suitable DTM. In many cases, the reasons can be determined in this way and faults rectified.

### Check the 4 ... 20 mA signal

Connect a multimeter in the suitable measuring range according to the wiring plan. The following table describes possible errors in the current signal and helps to eliminate them:

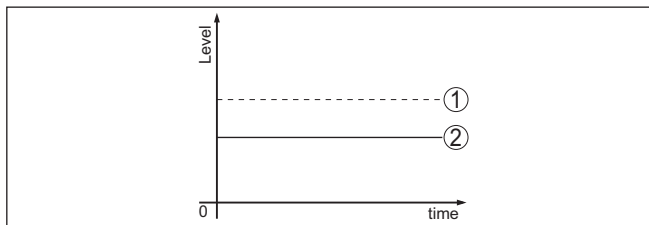
Error	Reason	Rectification
4 ... 20 mA signal not stable	<ul style="list-style-type: none"> <li>● Fluctuations of the measured variable</li> </ul>	<ul style="list-style-type: none"> <li>● Set damping appropriate to the instrument via the display and adjustment module or PACTware/DTM</li> </ul>
4 ... 20 mA signal missing	<ul style="list-style-type: none"> <li>● Electrical connection faulty</li> </ul>	<ul style="list-style-type: none"> <li>● Check connection according to chapter "Connection steps" and if necessary, correct according to chapter "Wiring plan"</li> </ul>
	<ul style="list-style-type: none"> <li>● Voltage supply missing</li> </ul>	<ul style="list-style-type: none"> <li>● Check cables for breaks; repair if necessary</li> </ul>
	<ul style="list-style-type: none"> <li>● Operating voltage too low or load resistance too high</li> </ul>	<ul style="list-style-type: none"> <li>● Check, adapt if necessary</li> </ul>
Current signal greater than 22 mA or less than 3.6 mA	<ul style="list-style-type: none"> <li>● Electronics module in the sensor defective</li> </ul>	<ul style="list-style-type: none"> <li>● Exchange the instrument or send it in for repair</li> </ul>

## Treatment of measurement errors with liquids

The below tables show typical examples of application-related measurement errors with liquids. The measurement errors are differentiated according to the following:

- Constant level
- Filling
- Emptying

The images in column "Error pattern" show the real level as a broken line and the level displayed by the sensor as a continuous line.



- 1 Real level  
2 Level displayed by the sensor




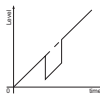

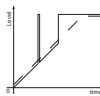
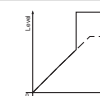
### Notes:

- Wherever the sensor displays a constant value, the reason could also be the fault setting of the current output to "Hold value"
- If the level indication is too low, the reason could be a line resistance that is too high




## Measurement error with constant level

Fault description	Error pattern	Reason	Rectification
1. Measured value shows a too low or too high level		• Min./max. adjustment not correct	• Adapt min./max. adjustment
		• Incorrect linearisation curve	• Adapt linearisation curve
		• Installation in a bypass tube or standpipe, hence running time error (small measurement error close to 100 %/large error close to 0 %)	• Check parameter "Application" with respect to vessel form, adapt if necessary (bypass, standpipe, diameter)
2. Measured value jumps towards 0 %		• Multiple echo (vessel top, product surface) with amplitude higher than the level echo	• Check parameter "Application", especially vessel top, type of medium, dished bottom, high dielectric constant, and adapt if necessary
3. Measured value jumps towards 100 %		• Due to the process, the amplitude of the level echo sinks	• Carry out a false signal suppression
		• A false signal suppression was not carried out	
		• Amplitude or position of a false signal has changed (e.g. condensation, buildup); false signal suppression no longer matches actual conditions	• Determine the reason for the changed false signals, carry out false signal suppression, e.g. with condensation

## Measurement error during filling

Fault description	Error pattern	Reason	Rectification
4. Measured value remains unchanged during filling		<ul style="list-style-type: none"> <li>False signals in the close range too big or level echo too small</li> <li>Strong foam or spout generation</li> <li>Max. adjustment not correct</li> </ul>	<ul style="list-style-type: none"> <li>Eliminate false signals in the close range</li> <li>Check measurement situation: Antenna must protrude out of the socket, installations</li> <li>Remove contamination on the antenna</li> <li>In case of interferences due to installations in the close range: Change polarisation direction</li> <li>Create a new false signal suppression</li> <li>Adapt max. adjustment</li> </ul>
5. Measured value remains in the bottom section during filling		<ul style="list-style-type: none"> <li>Echo from the tank bottom larger than the level echo, for example, with products with <math>\epsilon_r &lt; 2.5</math> oil-based, solvents</li> </ul>	<ul style="list-style-type: none"> <li>Check parameters Medium, Vessel height and Floor form, adapt if necessary</li> </ul>
6. Measured value remains momentarily unchanged during filling and then jumps to the correct level		<ul style="list-style-type: none"> <li>Turbulence on the product surface, quick filling</li> </ul>	<ul style="list-style-type: none"> <li>Check parameters, change if necessary, e.g. in dosing vessel, reactor</li> </ul>
7. Measured value jumps towards 0 % during filling		<ul style="list-style-type: none"> <li>Amplitude of a multiple echo (vessel top - product surface) is larger than the level echo</li> </ul>	<ul style="list-style-type: none"> <li>Check parameter "Application", especially vessel top, type of medium, dished bottom, high dielectric constant, and adapt if necessary</li> </ul>
		<ul style="list-style-type: none"> <li>The level echo cannot be distinguished from the false signal at a false signal position (jumps to multiple echo)</li> </ul>	<ul style="list-style-type: none"> <li>In case of interferences due to installations in the close range: Change polarisation direction</li> <li>Chose a more suitable installation position</li> </ul>
8. Measured value jumps towards 100 % during filling		<ul style="list-style-type: none"> <li>Due to strong turbulence and foam generation during filling, the amplitude of the level echo sinks. Measured value jumps to false signal</li> </ul>	<ul style="list-style-type: none"> <li>Carry out a false signal suppression</li> </ul>
9. Measured value jumps sporadically to 100 % during filling		<ul style="list-style-type: none"> <li>Varying condensation or contamination on the antenna</li> </ul>	<ul style="list-style-type: none"> <li>Carry out a false signal suppression or increase false signal suppression with condensation/contamination in the close range by editing</li> </ul>
10. Measured value jumps to $\geq 100$ % or 0 m distance		<ul style="list-style-type: none"> <li>Level echo is no longer detected in the close range due to foam generation or false signals in the close range. The sensor goes into overfill protection mode. The max. level (0 m distance) as well as the status message "Overfill protection" are outputted.</li> </ul>	<ul style="list-style-type: none"> <li>Check measuring site: Antenna must protrude out of the socket</li> <li>Remove contamination on the antenna</li> <li>Use a sensor with a more suitable antenna</li> </ul>

## Measurement error during emptying

Fault description	Error pattern	Reason	Rectification
11. Measured value remains unchanged in the close range during emptying		<ul style="list-style-type: none"> <li>● False signal larger than the level echo</li> <li>● Level echo too small</li> </ul>	<ul style="list-style-type: none"> <li>● Eliminate false signal in the close range. Check: Antenna must protrude from the socket</li> <li>● Remove contamination on the antenna</li> <li>● In case of interferences due to installations in the close range: Change polarisation direction</li> <li>● After eliminating the false signals, the false signal suppression must be deleted. Carry out a new false signal suppression</li> </ul>
12. Measured value jumps towards 0 % during emptying		<ul style="list-style-type: none"> <li>● Echo from the tank bottom larger than the level echo, for example, with products with <math>\epsilon_r &lt; 2.5</math> oil-based, solvents</li> </ul>	<ul style="list-style-type: none"> <li>● Check parameters Medium type, Vessel height and Floor form, adapt if necessary</li> </ul>
13. Measured value jumps sporadically towards 100 % during emptying		<ul style="list-style-type: none"> <li>● Varying condensation or contamination on the antenna</li> </ul>	<ul style="list-style-type: none"> <li>● Carry out false signal suppression or increase false signal suppression in the close range by editing</li> <li>● With bulk solids, use radar sensor with purging air connection</li> </ul>

### Reaction after fault rectification

Depending on the reason for the fault and the measures taken, the steps described in chapter "Setup" must be carried out again or must be checked for plausibility and completeness.

### 24 hour service hotline

Should these measures not be successful, please call in urgent cases the VEGA service hotline under the phone no. **+49 1805 858550**.

The hotline is also available outside normal working hours, seven days a week around the clock.

Since we offer this service worldwide, the support is provided in English. The service itself is free of charge, the only costs involved are the normal call charges.

## 9.5 Exchanging the electronics module

If the electronics module is defective, it can be replaced by the user.



In Ex applications, only instruments and electronics modules with appropriate Ex approval may be used.

If there is no electronics module available on site, the electronics module can be ordered through the agency serving you. The electronics modules are adapted to the respective sensor and differ in signal output or voltage supply.

The new electronics module must be loaded with the default settings of the sensor. These are the options:

- In the factory
- Or on site by the user

In both cases, the serial number of the sensor is needed. The serial numbers are stated on the type label of the instrument, on the inside of the housing as well as on the delivery note.

When loading on site, the order data must first be downloaded from the Internet (see operating instructions manual "*Electronics module*").

**Caution:**

All application-specific settings must be entered again. That's why you have to carry out a fresh setup after exchanging the electronics.

If you saved the parameter settings during the first setup of the sensor, you can transfer them to the replacement electronics module. A fresh setup is then not necessary.

## 9.6 Software update

The following components are required to update the instrument software:

- Instrument
- Voltage supply
- Interface adapter VEGACONNECT
- PC with PACTware
- Current instrument software as file

You can find the current instrument software as well as detailed information on the procedure in the download area of our homepage: [www.vega.com](http://www.vega.com).

**Caution:**

Instruments with approvals can be bound to certain software versions. Therefore make sure that the approval is still effective after a software update is carried out.

You can find detailed information in the download area at [www.vega.com](http://www.vega.com).

## 9.7 How to proceed if a repair is necessary

You can find an instrument return form as well as detailed information about the procedure in the download area of our homepage: [www.vega.com](http://www.vega.com).

By doing this you help us carry out the repair quickly and without having to call back for needed information.

If a repair is necessary, please proceed as follows:

- Print and fill out one form per instrument
- Clean the instrument and pack it damage-proof
- Attach the completed form and, if need be, also a safety data sheet outside on the packaging
- Please contact the agency serving you to get the address for the return shipment. You can find the agency on our home page [www.vega.com](http://www.vega.com).



## 10 Dismount

### 10.1 Dismounting steps

**Warning:**

Before dismantling, be aware of dangerous process conditions such as e.g. pressure in the vessel or pipeline, high temperatures, corrosive or toxic products etc.

Take note of chapters "*Mounting*" and "*Connecting to power supply*" and carry out the listed steps in reverse order.

### 10.2 Disposal

The instrument consists of materials which can be recycled by specialised recycling companies. We use recyclable materials and have designed the electronics to be easily separable.

Correct disposal avoids negative effects on humans and the environment and ensures recycling of useful raw materials.

Materials: see chapter "*Technical data*"

If you have no way to dispose of the old instrument properly, please contact us concerning return and disposal.

**WEEE directive 2002/96/EG**

This instrument is not subject to the WEEE directive 2002/96/EG and the respective national laws. Pass the instrument directly on to a specialised recycling company and do not use the municipal collecting points. These may be used only for privately used products according to the WEEE directive.

## 11 Supplement

### 11.1 Technical data

#### Note for approved instruments

The technical data in the respective safety instructions are valid for approved instruments (e.g. with Ex approval). These data can differ from the data listed herein, for example regarding the process conditions or the voltage supply.

#### General data

316L corresponds to 1.4404 or 1.4435

Materials, wetted parts

- |                          |   |
|--------------------------|---|
| – Process fitting        | 316L, Alloy C22 (2.4602), Alloy 400 (2.4360)  |
| – Process seal           | On site (instruments with thread: Klingersil C-4400 is enclosed)  |
| – Antenna                | 316L, Alloy C22 (2.4602), Tantalum, 316L electropolished, stainless steel investment casting (1.4848), Alloy 400 (2.4360), 316L Safecoat coated |
| – Antenna impedance cone | PTFE, PP, PEEK, ceramic (99.7 % $Al_2O_3$ )   |
| – Seal, antenna system   | FKM (SHS FPM 70C3 GLT), FFKM (Kalrez 6375), FFKM (Kalrez 6230 - FDA), graphite (99.9 %)   |

Materials, non-wetted parts

- |   |  |
|---|--|
| – Plastic housing                               | plastic PBT (Polyester)  |
| – Aluminium die-cast housing                    | Aluminium die-casting AlSi10Mg, powder-coated (basis: Polyester) |
| – Stainless steel housing                       | 316L   |
| – Cable gland                                   | PA, stainless steel, brass                                       |
| – Sealing, cable gland                          | NBR  |
| – Blind plug, cable gland                       | PA   |
| – Seal, housing lid                             | Silicone SI 850 R, NBR silicone-free                             |
| – Inspection window in housing cover (optional) | Polycarbonate  |
| – Ground terminal                               | 316L   |

Conductive connection

Between ground terminal, process fitting and antenna

Process fittings

- |   |                              |
|---|------------------------------|
| – Pipe thread, cylindrical (ISO 228 T1) | G1½ according to DIN 3852-A  |
| – Pipe thread, conical (ASME B1.20.1)   | 1½ NPT, 2 NPT                |
| – Flanges                               | DIN from DN 25, ASME from 1" |

Weights

- |  |   |
|--|---|
| – Instrument (depending on housing, process fitting and antenna) | approx. 2 ... 17.2 kg (4.409 ... 37.92 lbs) |
| – Antenna extension  | 1.6 kg/m (1.157 lbs/ft)                     |

Length antenna extension max.

5.85 m (19.19 ft)

**Torques**

Max. torques, threaded version

- G1½ 200 Nm (147.5 lbf ft)

Max. torques, antenna system

- Mounting screws, antenna cone 2.5 Nm (1.8 lbf ft)
- Compression nut, parabolic antenna 50 Nm (36.89 lbf ft)
- Counter nut, parabolic antenna 40 Nm (29.50 lbf ft)
- Terminal screws, swivelling holder 15 Nm (11.06 lbf ft)

Max. torques for NPT cable glands and Conduit tubes

- Plastic housing 10 Nm (7.376 lbf ft)
- Aluminium/Stainless steel housing 50 Nm (36.88 lbf ft)

**Input variable**

Measured variable The measured quantity is the distance between the end of the sensor antenna and the product surface. The reference plane for the measurement is the sealing surface on the hexagon or the lower side of the flange.

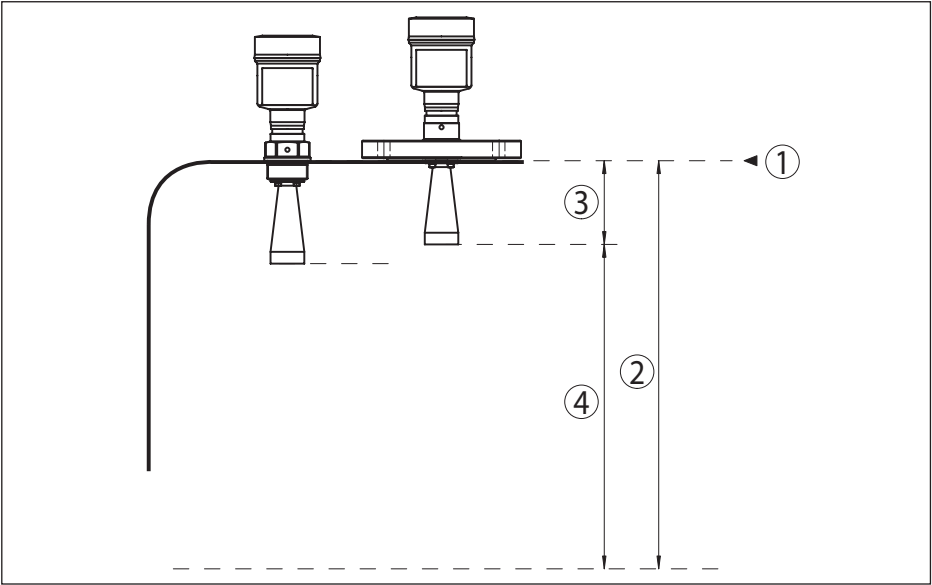


Fig. 52: Data of the input variable

- 1 Reference plane
- 2 Measured variable, max. measuring range
- 3 Antenna length
- 4 Utilisable measuring range

**Standard electronics**

Max. measuring range 35 m (114.83 ft)

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**Recommended measuring range**

- Antenna ø 40 mm (1.575 in) up to 15 m (49.21 ft)
- Antenna ø 48 mm (1.89 in) up to 20 m (65.62 ft)
- Antenna ø 75 mm (2.953 in), ø 95 mm (3.74 in), parabolic antenna up to 35 m (114.83 ft)

**Electronics with increased sensitivity**

Max. measuring range 75 m (246.1 ft)

**Recommended measuring range**

- Antenna ø 40 mm (1.575 in) up to 15 m (49.21 ft)
- Antenna ø 48 mm (1.89 in) up to 20 m (65.62 ft)
- Antenna ø 75 mm (2.953 in) up to 40 m (131.23 ft)
- Antenna ø 95 mm (3.74 in) up to 50 m (164 ft)
- Parabolic antenna up to 75 m (246.1 ft)

**Output variable**

Output signals	4 ... 20 mA/HART - active; 4 ... 20 mA/HART - passive
Range of the output signal	3.8 ... 20.5 mA/HART (default setting)
Terminal voltage passive	9 ... 30 V DC
Shortcircuit protection	Available
Potential separation	Available
Signal resolution	0.3 µA
Fault signal, current output (adjustable)	mA-value unchanged 20.5 mA, 22 mA, < 3.6 mA
Max. output current	22 mA
Starting current	≤ 3.6 mA
Load (4 ... 20 mA/HART - active)	< 500 Ω
Damping (63 % of the input variable)	0 ... 999 s, adjustable
HART output values	
– PV (Primary Value)	Distance
– SV (Secondary Value)	Percent
– TV (Third Value)	Lin. percent
– QV (Fourth Value)	Scaled
Resolution, digital	< 1 mm (0.039 in)

**Accuracy (according to DIN EN 60770-1)****Process reference conditions according to DIN EN 61298-1**

- Temperature +18 ... +30 °C (+64 ... +86 °F)
- Relative humidity 45 ... 75 %
- Air pressure 860 ... 1060 mbar/86 ... 106 kPa (12.5 ... 15.4 psig)

**Installation reference conditions**

- Min. distance to internal installations > 200 mm (7.874 in)
- Reflector Flat plate reflector

- False reflections

Deviation with liquids
- Biggest false signal, 20 dB smaller than the useful signal

See following diagrams

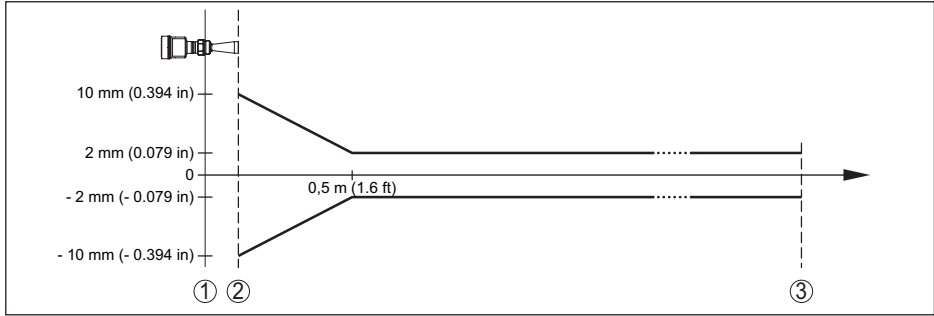


Fig. 53: Deviation under reference conditions

- 1 Reference plane
- 2 Antenna edge
- 3 Recommended measuring range

- Repeatability

Deviation with bulk solids
- $\leq \pm 1 \text{ mm}$

The values depend to a great extent on the application.  
Binding specifications are thus not possible.

**Variables influencing measurement accuracy**

**Specifications apply to the digital measured value**

- Temperature drift - Digital output

Additional deviation through electromagnetic interference acc. to EN 61326
- $\pm 3 \text{ mm}/10 \text{ K}$ , max. 10 mm

$< \pm 50 \text{ mm}$

**Specifications apply also to the current output**

- Temperature drift - Current output

Deviation in the current output due to digital/analogue conversion
- $\pm 0.03 \text{ \%}/10 \text{ K}$  relating to the 16 mA span max.  $\pm 0.3 \text{ \%}$

– Non-Ex and Ex-ia version

– Ex-d-ia version
- $< \pm 15 \text{ }\mu\text{A}$

$< \pm 40 \text{ }\mu\text{A}$
- Deviation in the current output due to strong, high-frequency electromagnetic fields acc. to EN 61326

$< \pm 150 \text{ }\mu\text{A}$

**Influence of the superimposed gas and pressure on measurement accuracy**

The propagation speed of the radar impulses in gas or vapour above the medium is reduced by high pressure. This effect depends on the type of superimposed gas or vapour and is especially large at low temperatures.

The following table shows the resulting deviation for some typical gases and vapours. The specified values refer to the distance. Positive values mean that the measured distance is too large, negative values that the measured distance is too small.

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Gas phase	Temperature	Pressure				
		1 bar (14.5 psig)	10 bar (145 psig)	50 bar (725 psig)	100 bar (1450 psig)	200 bar (2900 psig)
Air	20 °C/68 °F	0.00 %	0.22 %	1.2 %	2.4 %	4.9 %
	200 °C/392 °F	-0.01 %	0.13 %	0.74 %	1.5 %	3.0 %
	400 °C/752 °F	-0.02 %	0.08 %	0.52 %	1.1 %	2.1 %
Hydrogen	20 °C/68 °F	-0.01 %	0.10 %	0.61 %	1.2 %	2.5 %
	200 °C/392 °F	-0.02 %	0.05 %	0.37 %	0.76 %	1.6 %
	400 °C/752 °F	-0.02 %	0.03 %	0.25 %	0.53 %	1.1 %
Steam (saturated steam)	100 °C/212 °F	0.26 %	-	-	-	-
	180 °C/356 °F	0.17 %	2.1 %	-	-	-
	264 °C/507 °F	0.12 %	1.44 %	9.2 %	-	-
	366 °C/691 °F	0.07 %	1.01 %	5.7 %	13.2 %	76 %

### Characteristics and performance data

Measuring frequency K-band (26 GHz technology)

Measuring cycle time

- Standard electronics approx. 450 ms
- Electronics with increased sensitivity approx. 700 ms

Step response time<sup>3)</sup> ≤ 3 s

Beam angle<sup>4)</sup>

- Horn antenna ø 40 mm (1.575 in) 20°
- Horn antenna ø 48 mm (1.89 in) 15°
- Horn antenna ø 75 mm (2.953 in) 10°
- Horn antenna ø 95 mm (3.74 in) 8°
- Parabolic antenna 3°

Emitted HF power (depending on the parameter setting)<sup>5)</sup>

- Average spectral transmission power density -14 dBm/MHz EIRP
- Max. spectral transmission power density +43 dBm/50 MHz EIRP
- Max. power density at a distance of 1 m < 1 µW/cm<sup>2</sup>

### Ambient conditions

Ambient, storage and transport temperature -40 ... +80 °C (-40 ... +176 °F)

<sup>3)</sup> Time span after a sudden measuring distance change by max. 0.5 m in liquid applications, max 2 m with bulk solids applications, until the output signal has taken for the first time 90 % of the final value (IEC 61298-2).

<sup>4)</sup> Outside the specified beam angle, the energy level of the radar signal is 50% (-3 dB) less.

<sup>5)</sup> EIRP: Equivalent Isotropic Radiated Power.

## Process conditions

For the process conditions, please also note the specifications on the type label. The lowest value always applies.

Seal	Antenna impedance cone	Process temperature (measured on the process fitting)
FKM (SHS FPM 70C3 GLT)	PTFE	-40 ... +130 °C (-40 ... +266 °F)
	PTFE <sup>6)</sup>	-40 ... +200 °C (-40 ... +392 °F)
	PEEK <sup>7)</sup>	-40 ... +200 °C (-40 ... +392 °F)
FFKM (Kalrez 6375)	PTFE	-20 ... +130 °C (-4 ... +266 °F)
	PEEK	-20 ... +250 °C (-4 ... +482 °F)
FFKM (Kalrez 6230)	PTFE	-15 ... +130 °C (5 ... +266 °F)
	PEEK	-15 ... +250 °C (5 ... +482 °F)
Graphite	Ceramic	-196 ... +450 °C (-321 ... +842 °F)
Graphite Process fitting Alloy C22 (2.4602)	Ceramic	-196 ... +400 °C (-321 ... +752 °F)

### Vessel pressure - horn antenna

- Antenna impedance cone PTFE -1 ... 40 bar (-100 ... 4000 kPa/-14.5 ... 580 psig)
- Antenna impedance cone PEEK -1 ... 100 bar (-100 ... 10000 kPa/-14.5 ... 1450 psig)
- Antenna impedance cone ceramic -1 ... 160 bar (-100 ... 16000 kPa/-14.5 ... 2320 psig)

### Vessel pressure - parabolic antenna -1 ... 6 bar (-100 ... 6000 kPa/-14.5 ... 870 psig)

### Vessel pressure with swivelling holder -1 ... 1 bar (-100 ... 100 kPa/-14.5 ... 14.5 psig)

Vessel pressure relating to the flange nominal pressure stage see supplementary instructions manual "*Flanges according to DIN-EN-ASME-JIS*"

### Vibration resistance

- Horn antenna 4 g at 5 ... 200 Hz according to EN 60068-2-6 (vibration with resonance)
- Parabolic antenna 1 g at 5 ... 200 Hz according to EN 60068-2-6 (vibration with resonance)

### Shock resistance

- Horn antenna 100 g, 6 ms according to EN 60068-2-27 (mechanical shock)
- Parabolic antenna 25 g, 6 ms according to EN 60068-2-27 (mechanical shock)

## Data on rinsing air connection

Max. permissible pressure 6 bar (87.02 psig)

Air volume with horn antenna, depending on pressure (recommended area)

Pressure	Without reflux valve	With reflux valve
0.5 bar (7.25 psig)	3.3 m³/h	1.2 m³/h

<sup>6)</sup> Not with steam.

<sup>7)</sup> Not with steam.

Pressure	Without reflux valve	With reflux valve
0.6 bar (8.70 psig)	3.5 m³/h	1.4 m³/h
0.7 bar (10.15 psig)	3.7 m³/h	1.7 m³/h
0.8 bar (11.60 psig)	3.9 m³/h	1.8 m³/h
0.9 bar (13.05 psig)	4.0 m³/h	2.1 m³/h
1 bar (14.5 psig)	4.2 m³/h	2.2 m³/h
1.5 bar (21.76 psig)	5.0 m³/h	3.2 m³/h
2 bar (29.0 psig)	5.5 m³/h	4.5 m³/h

Air volume with parabolic antenna, depending on pressure (recommended area)

Pressure	Without reflux valve	With reflux valve
0.5 bar (7.25 psig)	3.0 m³/h	1.2 m³/h
0.6 bar (8.70 psig)	3.2 m³/h	1.4 m³/h
0.7 bar (10.15 psig)	3.4 m³/h	1.7 m³/h
0.8 bar (11.60 psig)	3.5 m³/h	1.9 m³/h
0.9 bar (13.05 psig)	3.6 m³/h	2.0 m³/h
1 bar (14.5 psig)	3.8 m³/h	2.2 m³/h
1.5 bar (21.76 psig)	4.3 m³/h	3.5 m³/h
2 bar (29.0 psig)	4.8 m³/h	4.0 m³/h

Thread

G1/8

Closure with

- Non-Ex Dust protection cover of PE
- Ex Threaded plug of 316Ti

Reflux valve - unmounted (as option with non-Ex version, included in the scope of delivery with Ex version)

- Material 316Ti
- Seal FKM (SHS FPM 70C3 GLT), FFKM (Kalrez 6375)
- for tube diameter 6 mm
- Opening pressure 0.5 bar (7.25 psig)
- Nominal pressure stage PN 250

### Electromechanical data - version IP 66/IP 67 and IP 66/IP 68; 0.2 bar

Options of the cable entry

- Cable entry M20 x 1.5, 1/2 NPT
- Cable gland M20 x 1.5; 1/2 NPT (cable ø see below table)
- Blind plug M20 x 1.5; 1/2 NPT
- Closing cap 1/2 NPT



Material cable gland	Material seal insert	Cable diameter				
		4.5 ... 8.5 mm	5 ... 9 mm	6 ... 12 mm	7 ... 12 mm	10 ... 14 mm
PA	NBR	–	●	●	–	●
Brass, nickel-plated	NBR	●	●	●	–	–
Stainless steel	NBR	–	●	●	–	●

Wire cross-section (spring-loaded terminals)

- Massive wire, stranded wire 0.2 ... 2.5 mm<sup>2</sup> (AWG 24 ... 14)
- Stranded wire with end sleeve 0.2 ... 1.5 mm<sup>2</sup> (AWG 24 ... 16)

### Display and adjustment module

Display element Display with backlight

Measured value indication

- Number of digits 5
- Size of digits W x H = 7 x 13 mm

Adjustment elements

- 4 keys *[OK], [->], [+], [ESC]*
- Switch Bluetooth On/Off

Bluetooth interface

- Standard Bluetooth smart
- Effective range 25 m (82.02 ft)

Protection rating

- unassembled IP 20
- mounted in the housing without lid IP 40

Materials

- Housing ABS
- Inspection window Polyester foil

Functional safety SIL non-reactive

### Interface to the external display and adjustment unit

Data transmission Digital (I<sup>2</sup>C-Bus)

Connection cable Four-wire

Sensor version	Configuration, connection cable			
	Cable length	Standard cable	Special cable	Screened
4 ... 20 mA/HART	50 m	●	–	–
Profibus PA, Foundation Fieldbus	25 m	–	●	●

### Integrated clock

Date format Day.Month.Year

Time format	12 h/24 h
Time zone, factory setting	CET
Max. rate deviation	10.5 min/year

---

**Additional output parameter - Electronics temperature**


---

## Output of the temperature values

– Analogue	Via the current output
– Digital	Via the digital output signal (depending on the electronics version)
Range	-40 ... +85 °C (-40 ... +185 °F)
Resolution	< 0.1 K
Accuracy	±3 K

---

**Voltage supply**


---

## Operating voltage

– Version for low voltage	9.6 ... 48 V DC, 20 ... 42 V AC, 50/60 Hz
– Version for mains voltage	90 ... 253 V AC, 50/60 Hz

Reverse voltage protection      Integrated

Max. power consumption      4 VA; 2.1 W

---

**Potential connections and electrical separating measures in the instrument**


---

Electronics	Not non-floating
Ground terminal	Galvanically connected with the metal process fitting
Galvanic separation between electronics and metal housing parts	
– Reference voltage	500 V AC

---

**Electrical protective measures**


---

Protection rating      IP 66/IP 67 (NEMA Type 4X)

## Overvoltage category (IEC 61010-1)

– Version with low voltage	The feeding power supply unit can be connected to networks of overvoltage category III.
----------------------------	---

## Overvoltage category (IEC 61010-1) - Version with mains voltage

– up to 2000 m (6562 ft) above sea level	III
– up to 5000 m (16404 ft) above sea level	III - Only with connected overvoltage protection
– up to 5000 m (16404 ft) above sea level	II

Pollution degree      3

Protection rating (IEC 61010-1)      I

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**Approvals**


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Instruments with approvals can have different technical specifications depending on the version.

For that reason the associated approval documents of these instruments have to be carefully noted. They are part of the delivery or can be downloaded under [www.vega.com](http://www.vega.com), "Instrument search (serial number)" as well as in the download area.

## 11.2 Dimensions

The following dimensional drawings represent only an extract of all possible versions. Detailed dimensional drawings can be downloaded at [www.vega.com/downloads](http://www.vega.com/downloads) under "Drawings".

### Housing

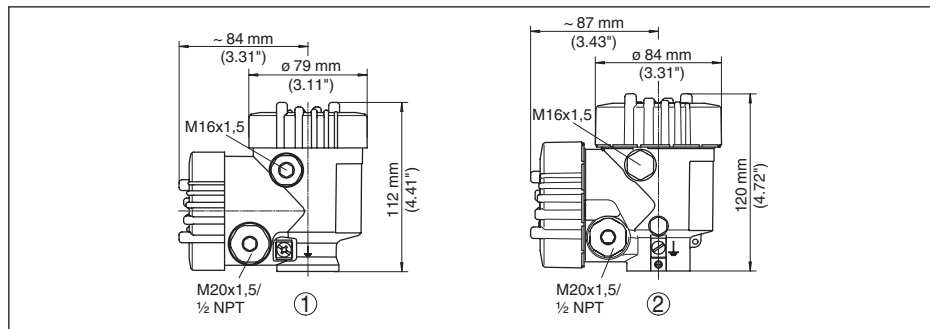


Fig. 54: Dimensions of housing - with integrated display and adjustment module the housing is 9 mm/0.35 inches higher

- 1 Plastic housing
- 2 Aluminium/Stainless steel housing

**VEGAPULS 62, horn antenna in threaded version**

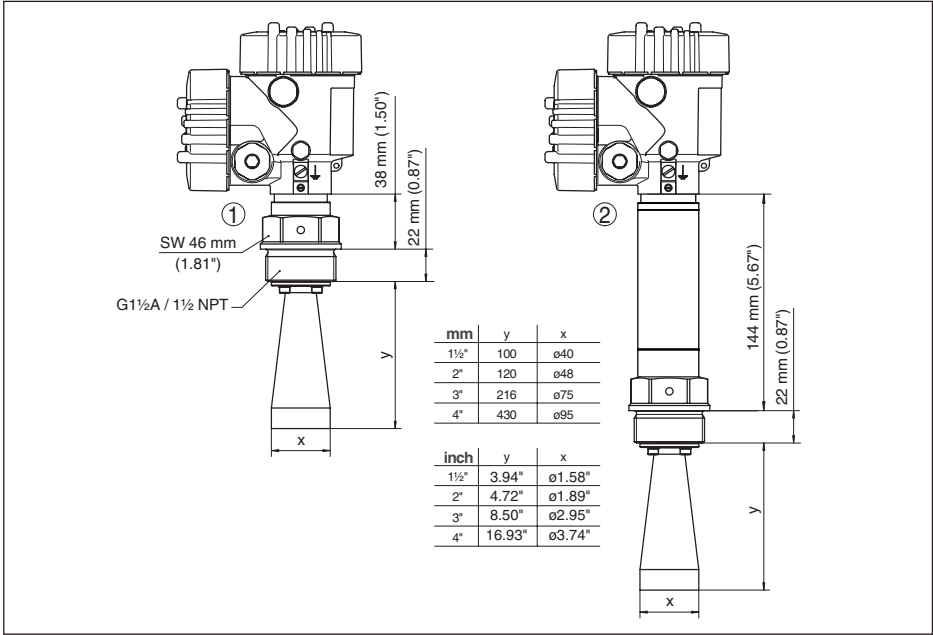


Fig. 55: VEGAPULS 62, horn antenna in threaded version

- 1 Standard
- 2 With temperature adapter up to 250 °C

**VEGAPULS 62, horn antenna in flange version**

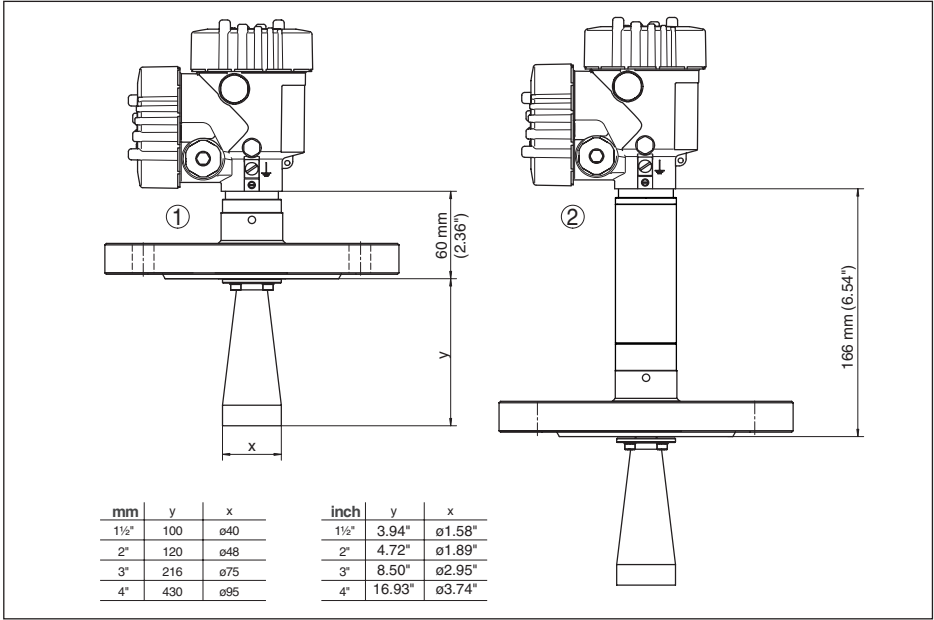


Fig. 56: VEGAPULS 62, horn antenna in flange version

- 1 Standard
- 2 With temperature adapter up to 250 °C

**VEGAPULS 62, horn antenna in flange version with purging air connection**

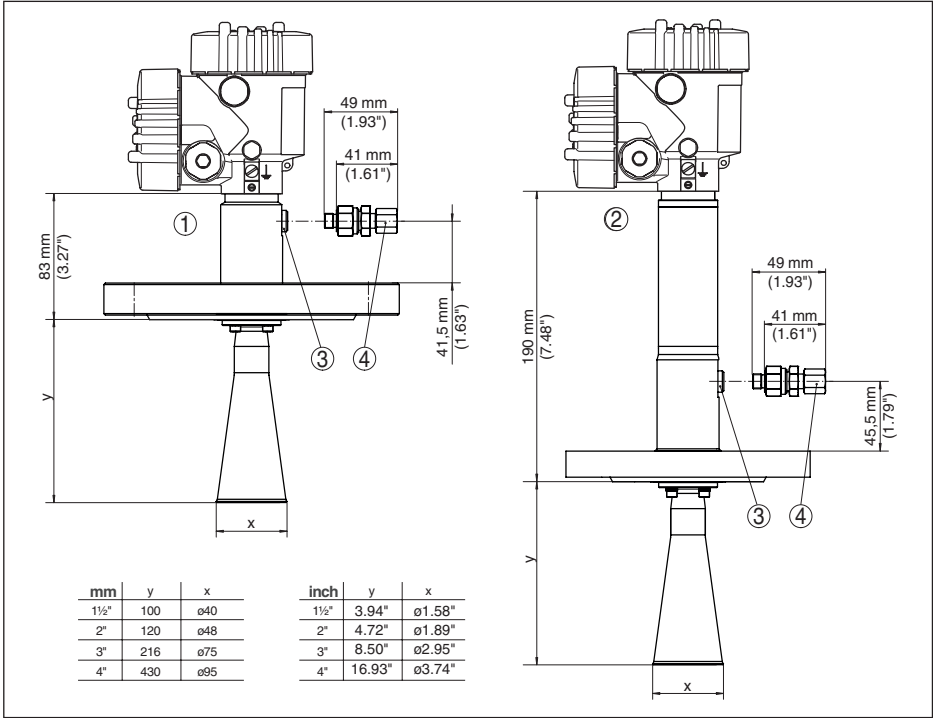
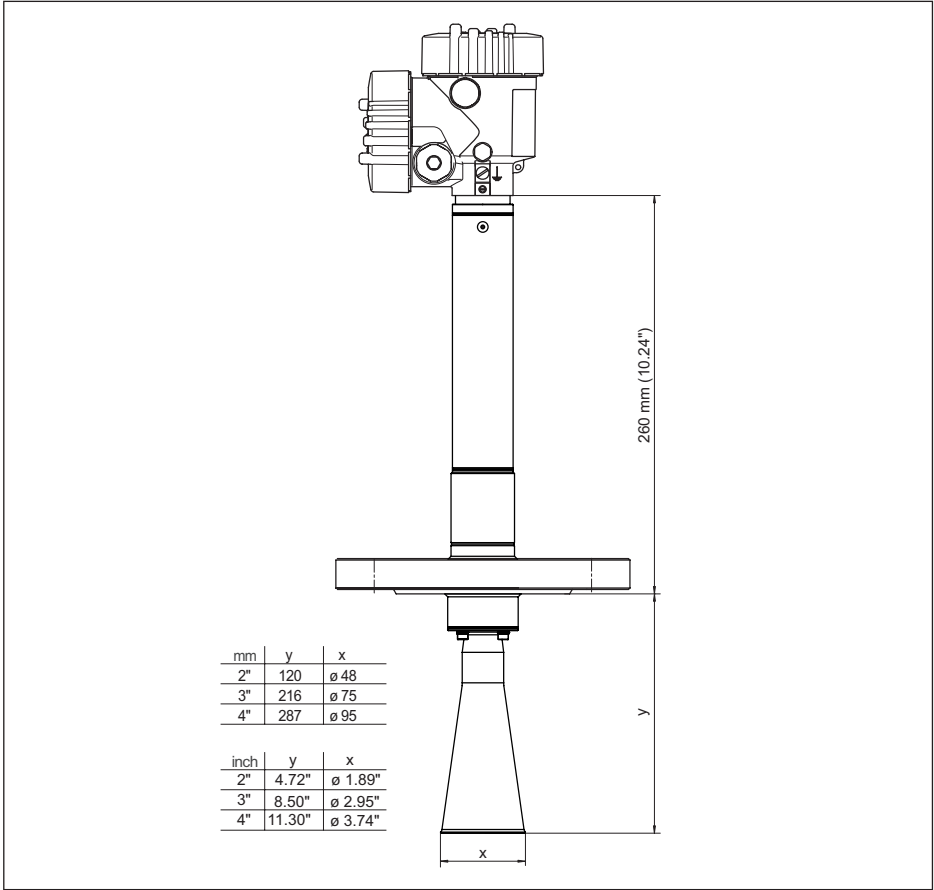


Fig. 57: VEGAPULS 62, horn antenna in flange version with purging air connection

- 1 Standard
- 2 With temperature adapter up to 250 °C
- 3 Blind plug
- 4 Reflux valve

**VEGAPULS 62, horn antenna in flange version 450 °C**



*Fig. 58: VEGAPULS 62, horn antenna in flange version with temperature adapter up to 450 °C*

**VEGAPULS 62, horn antenna and swivelling holder**

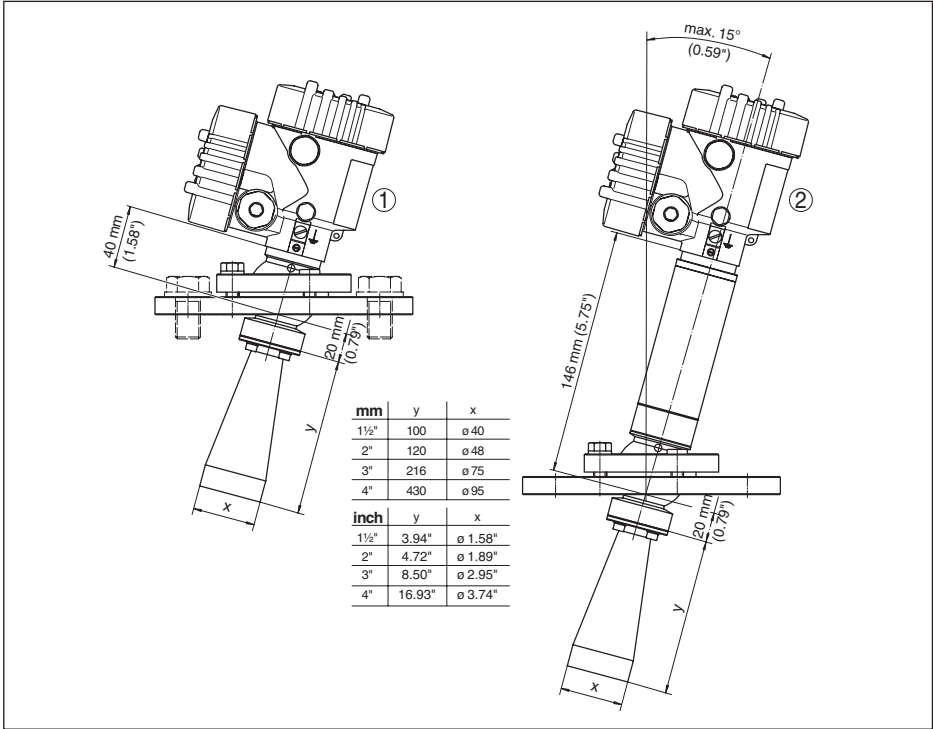


Fig. 59: VEGAPULS 62, horn antenna and swivelling holder

- 1 Standard
- 2 With temperature adapter up to 250 °C



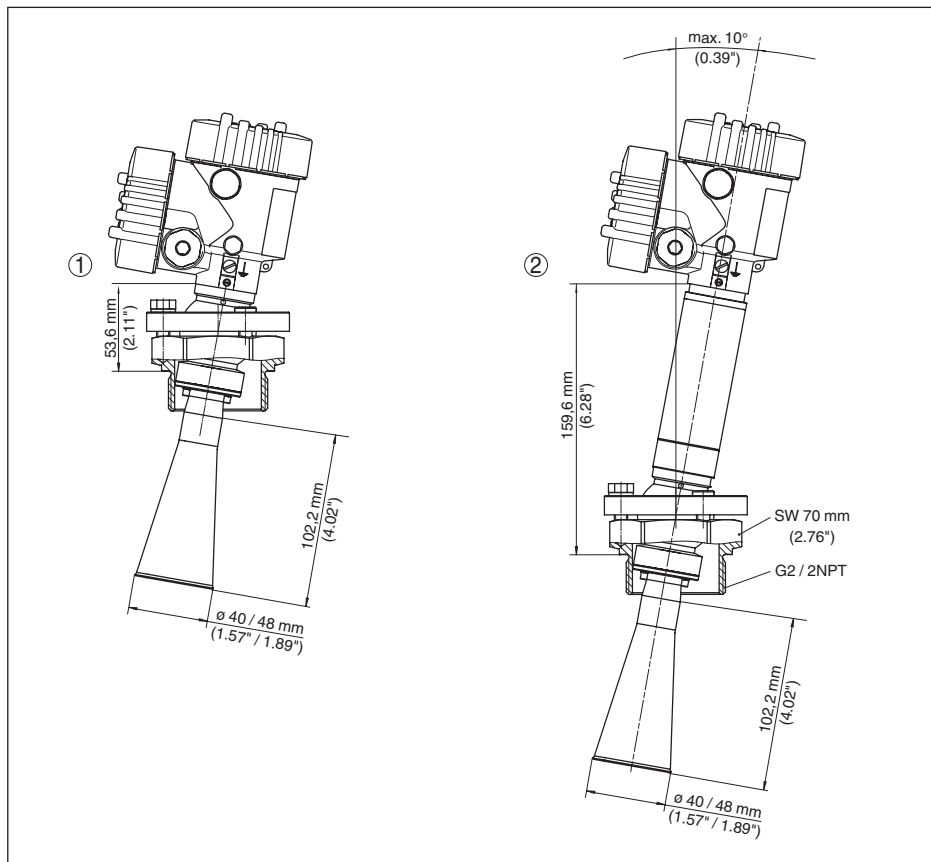
**VEGAPULS 62, horn antenna and swivelling holder, threaded fitting**


Fig. 60: VEGAPULS 62, horn antenna and swivelling holder, threaded fitting

- 1 Standard
- 2 With temperature adapter up to 250 °C

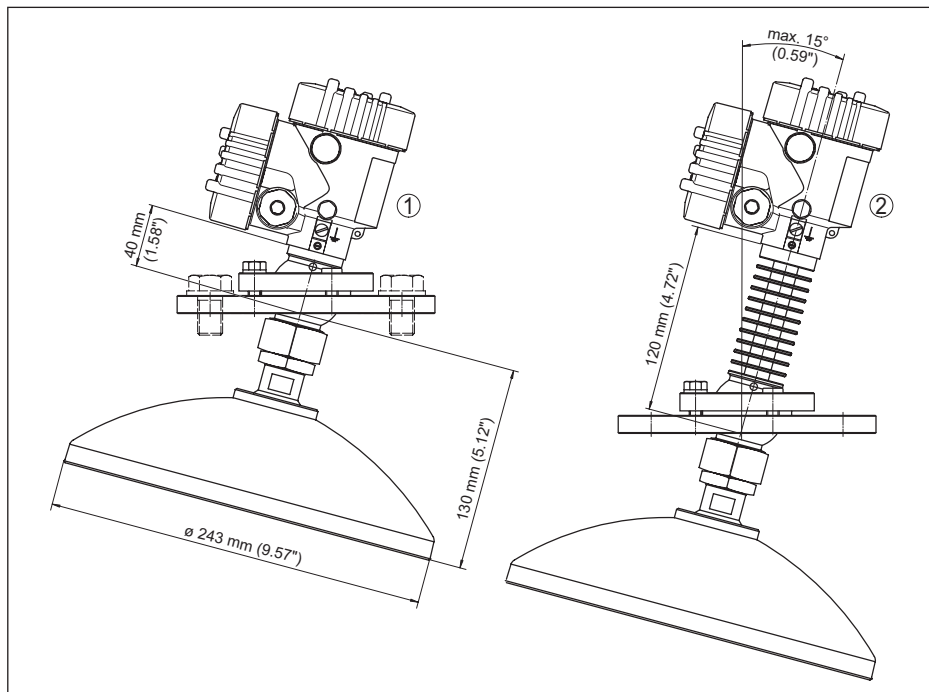
**VEGAPULS 62, parabolic antenna and swivelling holder**

Fig. 61: VEGAPULS 62, parabolic antenna and swivelling holder

- 1 Standard
- 2 With temperature adapter up to 200 °C

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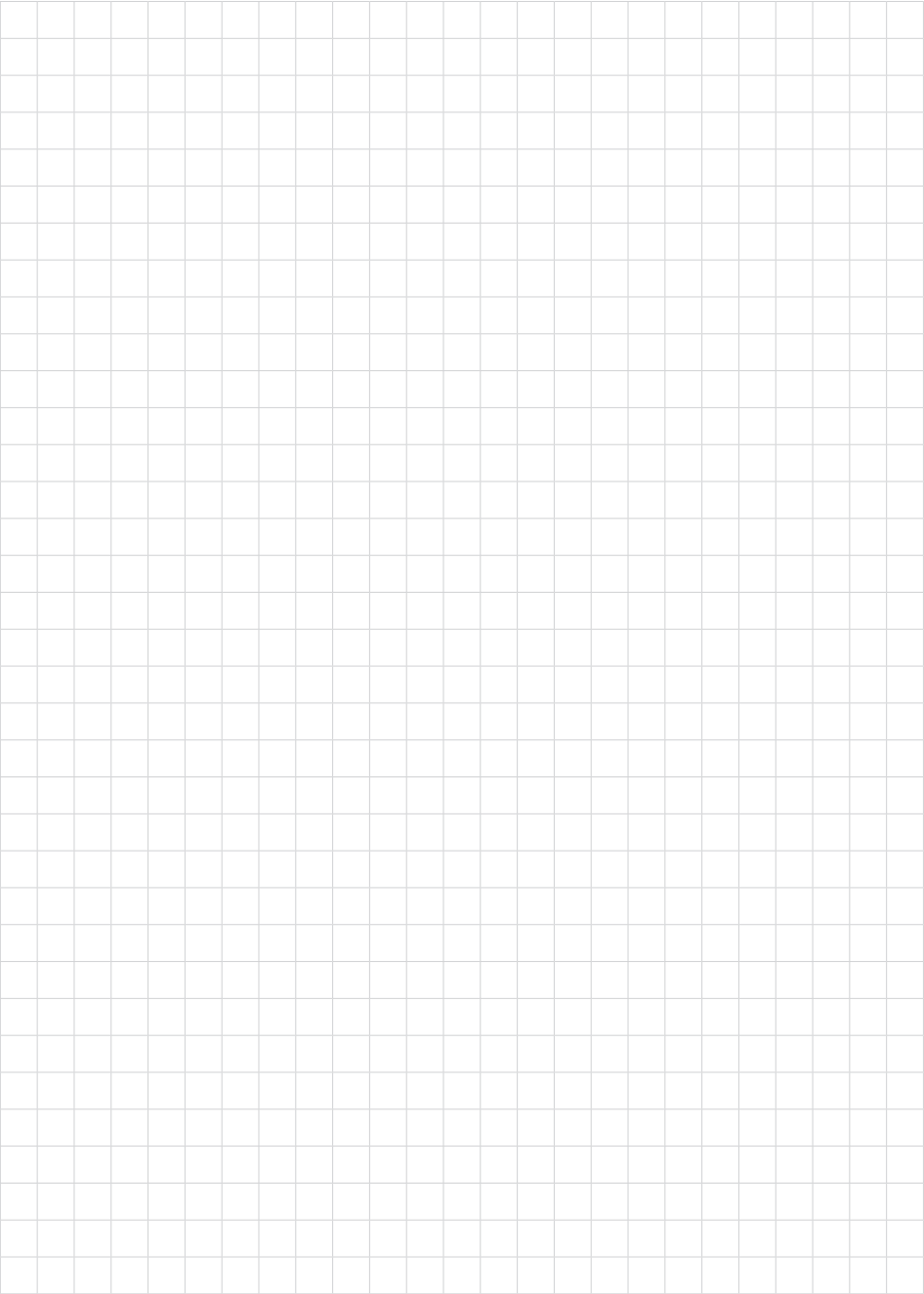
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