

RST-5003 Control Module User Manual

Web Enabled Series

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Introduction

Thank you for purchasing an RST-5003 Web Enabled Control Module from BinMaster. We appreciate your business! Please take a few minutes to familiarize yourself with your RST-5003 and this manual.

The RST-5003 Web Enabled Control Module offers a wide degree of integrated, flexible, remote and local control and monitoring for your system. The RST-5003 can control up to 10 BinMaster Modbus sensors--any combination of level, pressure, magnetostrictive and ultrasonic--along with one 4-20 mA sensor, and two input or output relay terminals. All readings are available for control and monitoring via TCP/IP for local or remote network access. The RST-5003 also had flexible power options: it can use either POE or an independent 12-28 VDC power source.

Reading your label

Every BinMaster controller comes with a label that includes the controller's model number, part number, and serial number. The RST-5003 label also indicates the default IP address, subnet mask, and mac address. Please ensure that the model number on your label matches your order.

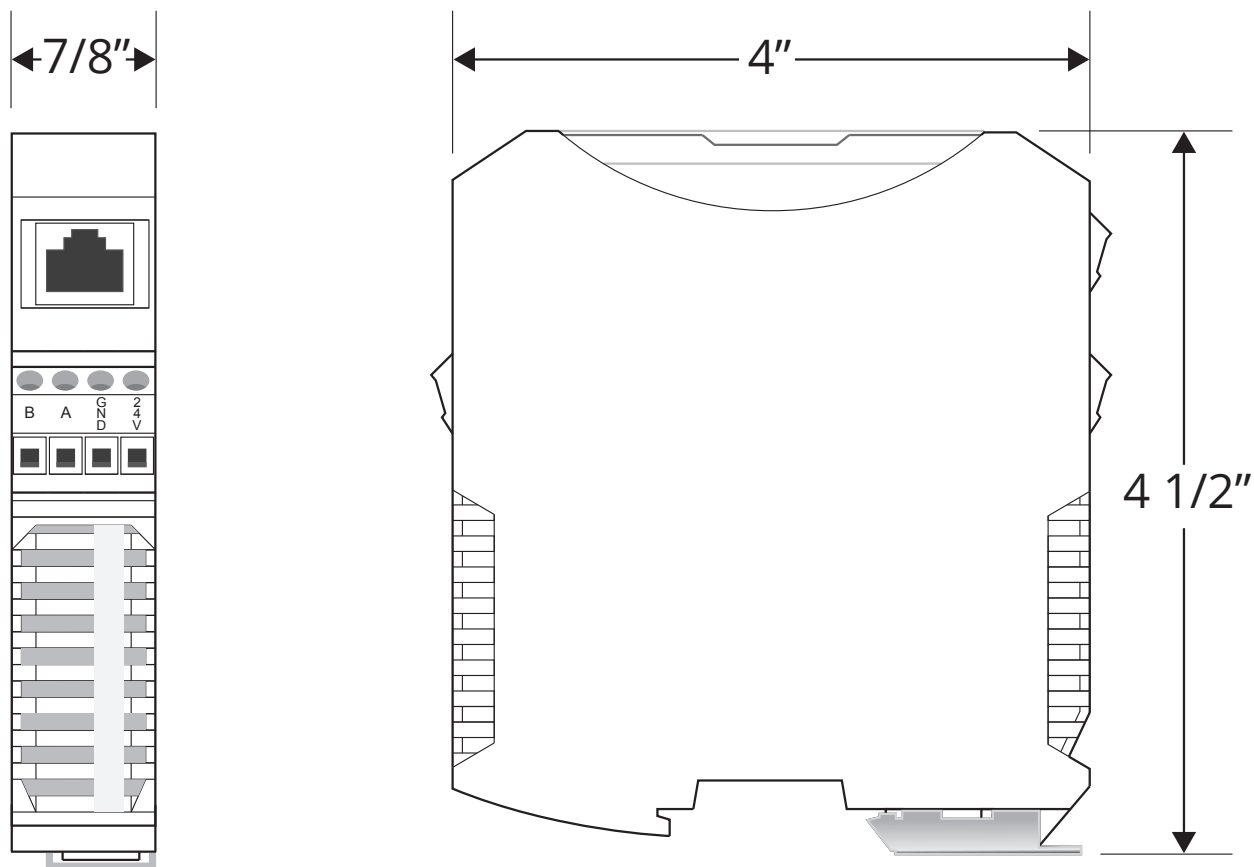
Warranty and Warranty Restrictions

BinMaster warrants this product against defects in material and workmanship for two (2) years according to the following terms;

- 1.) This warranty extends to the original purchaser only and commences on the date of original purchase.
- 2.) BinMaster's sole obligation under said warranty is to repair, or at its option replace the defective parts. The buyer shall have no other remedy. All special, incidental and consequential damages are excluded. The buyer must deliver the product under warranty prepaid to the factory. BinMaster's obligation is limited to the cost of material and labor to repair or replace, and does not include transportation expenses.
- 3.) This warranty shall be voided, in our sole judgment, by alterations of equipment except by BinMaster, or tampering with, improper installation or maintenance, accident or misuse, or act of God. This warranty expressly excludes all damage to the product resulting from careless or neglectful packaging or transportation. The warranty does not extend to repairs made necessary by normal wear.
- 4.) This warranty is in lieu of all other warranties, expressed or implied including any implied warranties or merchantability or fitness for particular purpose. No employee, agent, franchise dealer or other person is authorized to give any warranties of any nature on behalf of BinMaster.
- 5) BinMaster shall in no event be responsible for any warranty work done without first obtaining BinMaster's written consent.
- 6) Except as provided herein, BinMaster shall have no liability, loss or damage caused or alleged to be caused directly or indirectly by this equipment.
- 7) This warranty gives the buyer specific legal rights, and you may also have other rights which vary from state to state.
- 8) For service, please call 402-434-9102.

Chapter 1: Specifications and Options

- Dimensions



• Specifications

Communications

Digital Output

Ethernet TCP/IP Modbus
Ethernet TCP/IP to internal web page
Ethernet TCP/IP to external website
0-2 Isolated Solid State Relays
RS-485 Modbus
4-20 mA
0-2 Discrete Switches

Inputs

Electrical

Operational Supply Voltage (at sensor)

48 VDC via POE (requires injector or switch)
12-28 VDC

Current Draw

40 mA @ 48 VDC
130 mA Max (Isolated SSRs)

Power Rating

2.0 W Max

Accuracy

Resolution

12 bit

Environmental

Operating Temperature

-40 to 60°C (-40 to 140°F)

Materials of Construction

Housing

Polyamide

Mounting

33 mm Din-Rail

Compatible APG Modbus Senors

Ultrasonic

MNU

Magnetostrictive

MPX-E1, MPX-R1

Pressure

PT-400-L5, PT-400-L31, PT-500-L5, PT-500-L31

Controllers

DCR-1006A, MND

 NOTE: Please contact BinMaster for access to your external website.

• Model Number Configurator

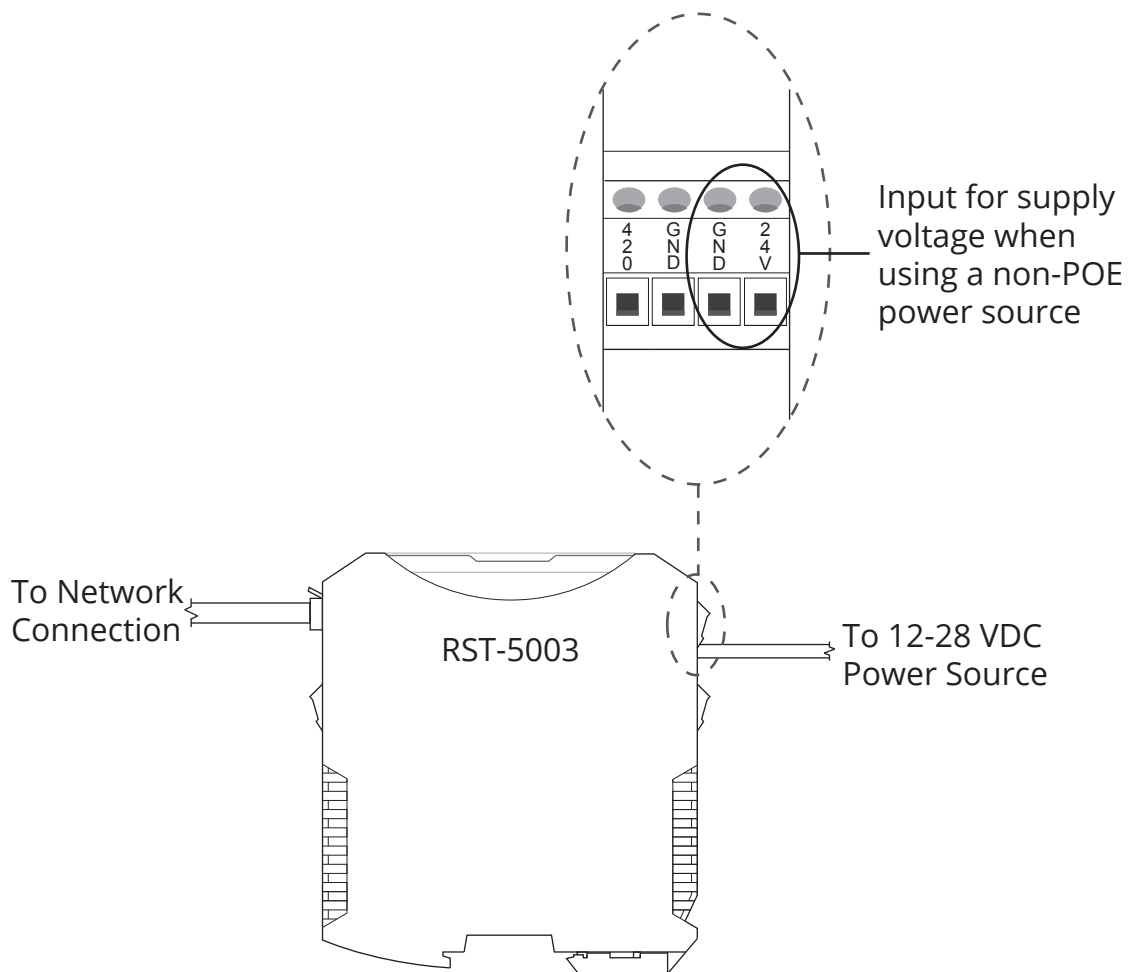
Part Number: RST - _____
A

A. Model

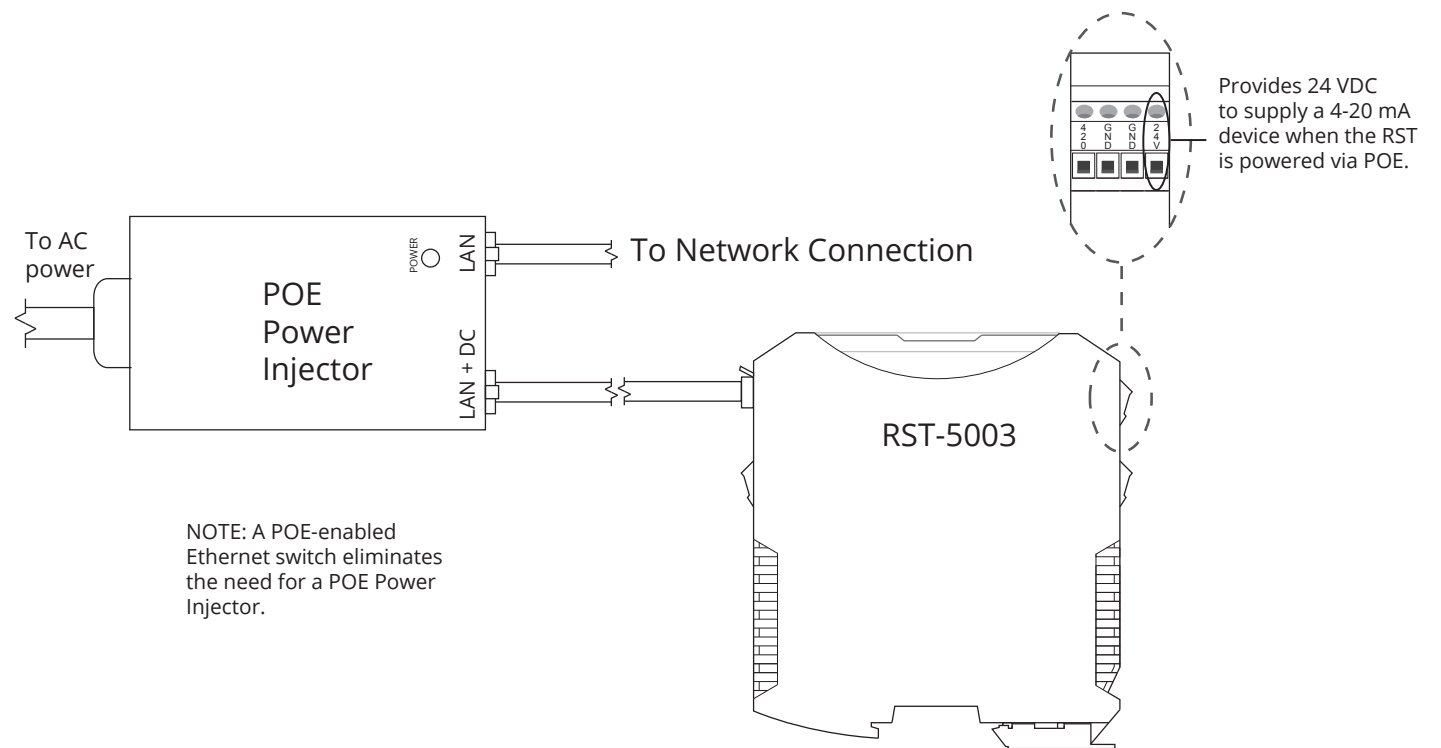
- **5003** 2 relay outputs
- **5013** 1 relay output, 1 switch input
- **5113** 2 switch inputs

• System Wiring Diagrams

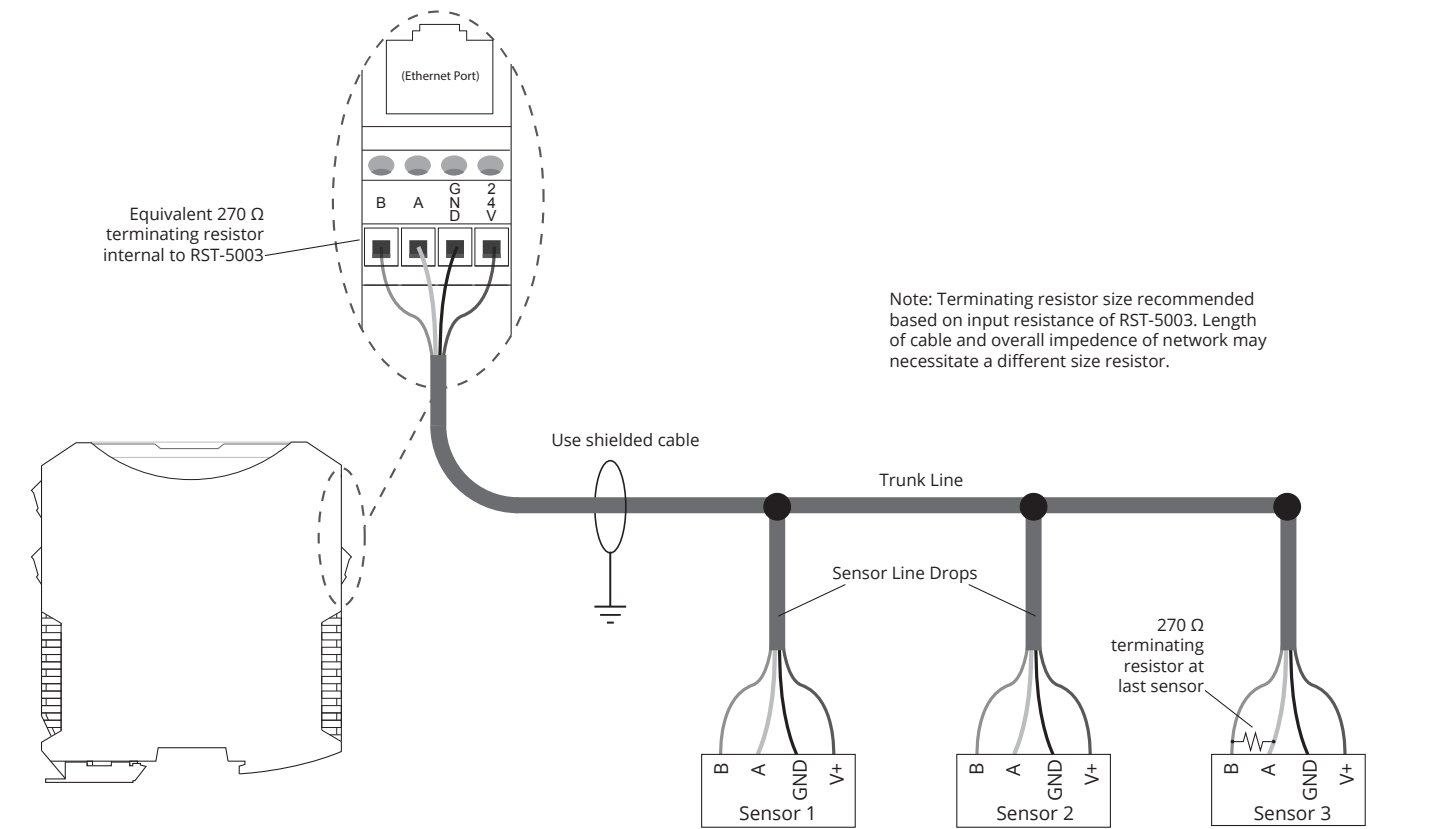
External 12-28 VDC Source Wiring



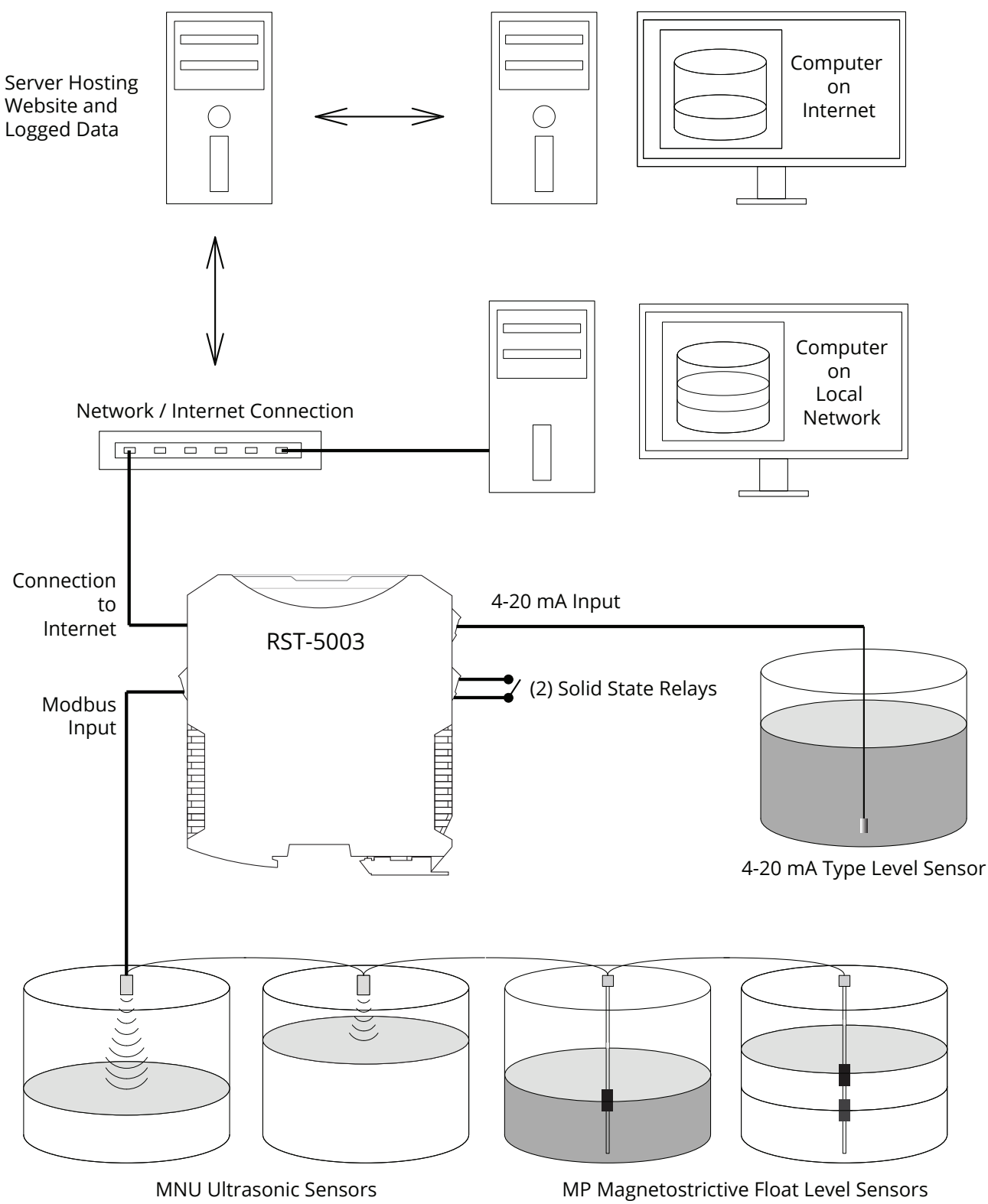
POE (Power over Ethernet) Wiring



Modbus Sensor Daisy-chain Wiring



System Overview - RST-5003 with Modbus and 4-20 mA sensors and Internet Connection



Chapter 2: Installation and Removal Procedures and Notes


• Tools Needed

- You do not need any tools to install your RST-5003. Please consult each sensor's user manual for any sensor installation notes and instructions.

 NOTE: Please visit <http://www.binmaster.com> for any BinMaster sensor user manual.


• Connection Notes

- Up to 10 Modbus sensors can be connected to the RST-5003 in any combination.
- Only one 4-20 mA sensor can be connected to the RST-5003.

 IMPORTANT: Each Modbus sensor must be connected to the network individually and assigned a unique Sensor Number before the next sensor can be added.

• Electrical Installation

- Connect any 4-20 mA sensor, relays, or switched inputs first.
- Connect RST to Ethernet/network.
- Connect independent 12-28 VDC supply if not using POE.
- Connect and set up one Modbus sensor at a time.

 IMPORTANT: Multiple Modbus sensors added to the network simultaneously are all assigned the same Modbus address/sensor number: 1. Sensors MUST be added to the network individually.

- **Software Setup**

Initial setup of the RST-5003 and individual Modbus sensors is done via an embedded web server. The page can be accessed by using either the serial number or local IP address of the RST-5003 and a web browser (Internet Explorer, Chrome, Firefox, etc).

 **NOTE:** Port 6700 must be open on your local network for the RST-5003 to connect.

Accessing RST-5003 Embedded Web Server via Serial Number

The easier way to access the embedded web server is to type rst_xxx into a web browser on a computer connected to the same local network as the RST-5003. xxx represents the numeric portion of the RST-5003's serial number. See Figures 2.1 and 2.2.



Figure 2.1

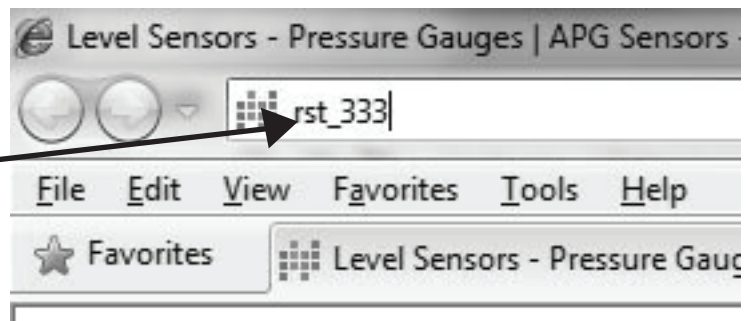


Figure 2.2

 **NOTE:** If your web browser performs a web search for "rst_xxx" instead of loading the page, type "http://rst_xxx".

Accessing RST-5003 Embedded Web Server via IP Address

Some networks will block this direct access to the RST-5003. If this is the case, you will need to use the IP address of your RST-5003 to access the embedded web server.

Ask your local network administrator for your RST-5003's IP address. Then type the RST's IP address into your browser's address bar (See Figure 2.3).

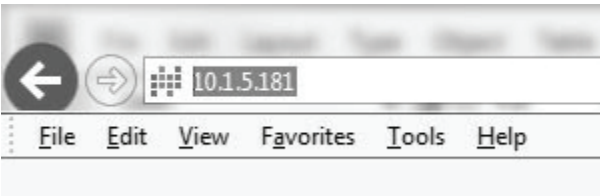


Figure 2.3

Logging on to the RST-5003 Embedded Web Server

The RST's embedded webpage should now be open, showing the Main Display page (See Figure 2.4). This page lists the sensors attached to the RST-5003 and displays each sensor's current reading. A 4-20 mA sensor will have "Analog Input" as its Sensor Number. The configured sensor number for each Modbus sensor will show as its Sensor Number. Every new Modbus sensor defaults to sensor number 1.

Sensor #	Description	Reading	Units
Analog Input		270.03	Inches
1		69.764	Inches

Refresh

Home

Figure 2.4

i IMPORTANT: Multiple Modbus sensors added to the network simultaneously are all assigned the same sensor number: 1. Sensors must be added to the network individually.

Click on Home to bring up the Menu page (See Figure 2.5). The first menu link clicked during each session will prompt a User Name and Password login for the RST-5003 (See Figure 2.6). The default User Name is **admin**, and the default Password is **password**.

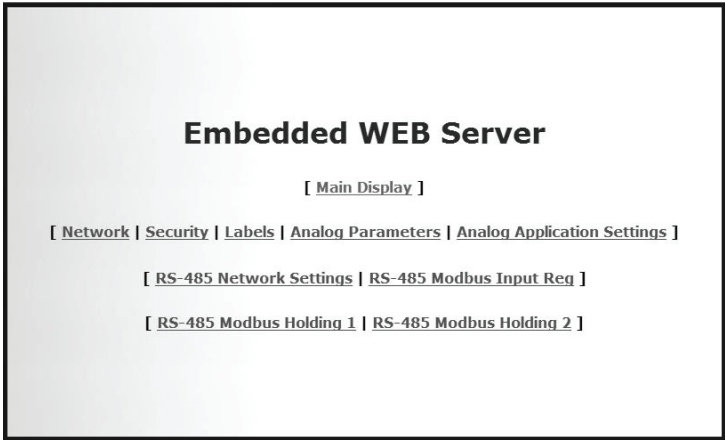


Figure 2.5



Figure 2.6

 **NOTE:** See the Security Setting Menu (Page 34) to change this user name and password.

Assigning Modbus Senor Numbers

Click on RS-485 Network Settings to bring up the RS485 Settings page. (See Figure 2.7.) See section RS-485 Network Settings for a full description of each parameter in this menu (Page 35).


RS485 Settings		
Definition	Range	Value
2400 Baud	Checked or UnChecked	<input type="checkbox"/> 2400 Baud
9600 Baud	Checked or UnChecked	<input checked="" type="checkbox"/> 9600 Baud
Numb of Sensors On Line	0 to 10	1
Sensor Number to View	1 to 10	1
New Sensor Number	0=No Change or 1 to 10	0
RS485 Sample Rate	1 to 20 Seconds	1
Change Undo Refresh Home		


Figure 2.7

Change *Numb of Sensors On Line* to reflect the total number of Modbus sensors you will be connecting. Click Change to send the new value to the RST-5003.

With *Sensor Number to View* set to 1 (for the latest sensor added to the Modbus network), set *New Sensor Number* to the highest available number. Click Change to send the new value to the RST-5003.

Repeat this process for each Modbus sensor as it is added to the network.

 **NOTE:** If you control the power to each Modbus sensor separately, powering up a new sensor after assigning a Modbus address to the previous sensor will allow you to assign an address to the new sensor without leaving the RS485 Settings Menu.

 **IMPORTANT:** None of parameters in the RS485 Settings menu automatically update. Each one must be manually configured.

• Removal Instructions

- Disconnect power to the RST-5003 first.
- Disconnect network connection.
- Disconnect any sensors, relays, and switched inputs.
- Remove the RST-5003 and store it in a dry place, at a temperature between -40° F and 180° F.

Chapter 3: Programming with Modbus TCP/IP

- **Modbus Polling via Ethernet with Modbus TCP/IP**

Using the RST-5003's IP address, and port number 502, readings can be polled from the RST-5003 for any attached sensors via RS-485 Modbus commands. Up to 14 16-bit Input Registers, beginning with register 298, can be polled with a single command. Below is a sample Modbus command illustrating the necessary syntax.

Example:

00 01 : Transaction Identifier
00 00 : Protocol Identifier
00 06 : Message Length (6 bytes to follow)
0B : The Reporting Unit Identifier [i.e., sensor number] (0B hex = 11)
04 : The Function Code (04 = read Input Registers)
01 2E : The Data Address of the first register requested. (12E hex + 1 = 303)
00 02 : The total number of registers requested. (read 2 registers, i.e. 303 to 304)

Byte order (hex values)

00 01 00 00 00 06 0B 04 01 2E 00 02

Notes:

- Reporting Unit indicates the sensor reading being polled from the RST-5003, in hex. 01 - 0A are for Modbus sensors 1 - 10 attached to the RST-5003. 0B (i.e., sensor 11) reads the interpreted values from the 4-20 mA sensor attached to the RST-5003. Unused registers (i.e., those not associated to an attached sensor) will return zeros when polled.
- Function Code 04 reads the Input Registers. No other functionality (e.g., polling from or writing to Holding Registers) is supported via Modbus TCP/IP with the RST-5003. Complete control functionality is available through the embedded web server and through your remote provided website.
- Data Address of registers, decimal to "hex minus 1" conversion:

Decimal Address	Hex minus 1	Decimal Address	Hex minus 1
299	12A	306	131
300	12B	307	132
301	12C	308	133
302	12D	309	134
303	12E	310	135
304	12F	311	136
305	130	312	137

- Total number of registers requested, up to 14, given in hex:

# of Registers	Hex equivalent	# of Registers	Hex equivalent
01	01	08	08
02	02	09	09
03	03	10	0A
04	04	11	0B
05	05	12	0C
06	06	13	0D
07	07	14	0E

• RST-5003 Generic Modbus Register List

Input Registers (0x04)

<u>Register</u>	<u>Returned Data</u>
30299	Sensor Type
30300	Distance/Level 1, Top (in mm, unsigned)
30301	Distance/Level 2, Bottom (in mm, unsigned)
30302	Sensor Temperature Reading (in °C, signed)
30303-30304	Calculated 1 (raw)
30305-30306	Calculated 2 (raw)
30307 (upper bits)	Version
30307 (lower bits)	Signal Strength
30308	Battery Voltage
30309 (upper bits)	Sensor Trip 1 Alarm
30309 (lower bits)	Sensor Trip 1 Status
30310 (upper bits)	Sensor Trip 2 Alarm
30310 (lower bits)	Sensor Trip 2 Status
30311 (upper bits)	Sensor Trip 3 Alarm
30311 (lower bits)	Sensor Trip 3 Status
30312 (upper bits)	Sensor Trip 4 Alarm
30312 (lower bits)	Sensor Trip 4 Status

This is the list of generic Input Registers for polling the RST-5003 and any connected sensors. Actual registers used vary by sensor. Please see the user manual for each sensor for a full and accurate list of registers.



NOTE: For more information about Modbus RTU, please visit www.modbus.org.

- **Modbus Programming of Individual Sensors**

The RST-5003 does NOT support full Modbus programming of attached sensors. Full control and configuration of individual sensors is supported through the RST-5003's embedded web server and through the remote provided webpage.

 NOTE: Please visit <http://www.binmaster.com> for any BinMaster sensor user manual.

Chapter 4: RST-5003 Embedded Web Server

- **Accessing the RST-5003 Embedded Web Server**

See the Software Setup section of chapter 2 (pages 7 - 9) for instructions for accessing and signing into the RST-5003 embedded web server.

- **Navigating the RST-5003 Embedded Web Server**

The RST-5003 embedded web server has two primary screens--the Main Display Page (Figure 4.1) and Menu Page (Figure 4.2)--and a screen for each of 9 submenus. The submenus can be understood in three groups:

- 4-20 mA Sensor Input Configuration Submenus
 - Analog Application Settings
 - Analog Parameters
- Modbus Sensor Configuration Registers
 - RS-485 Modbus Input Reg
 - RS-485 Modbus Holding 1
 - RS-485 Modbus Holding 2
- RST-5003 Utility Menus
 - Network
 - Security
 - Label
 - RS-485 Network Settings

The Menu Page also has a link back to the Main Display Page.

Sensor #	Description	Reading	Units
Analog Input		270.03	Inches
1		69.764	Inches

Refresh

Home

Figure 4.1

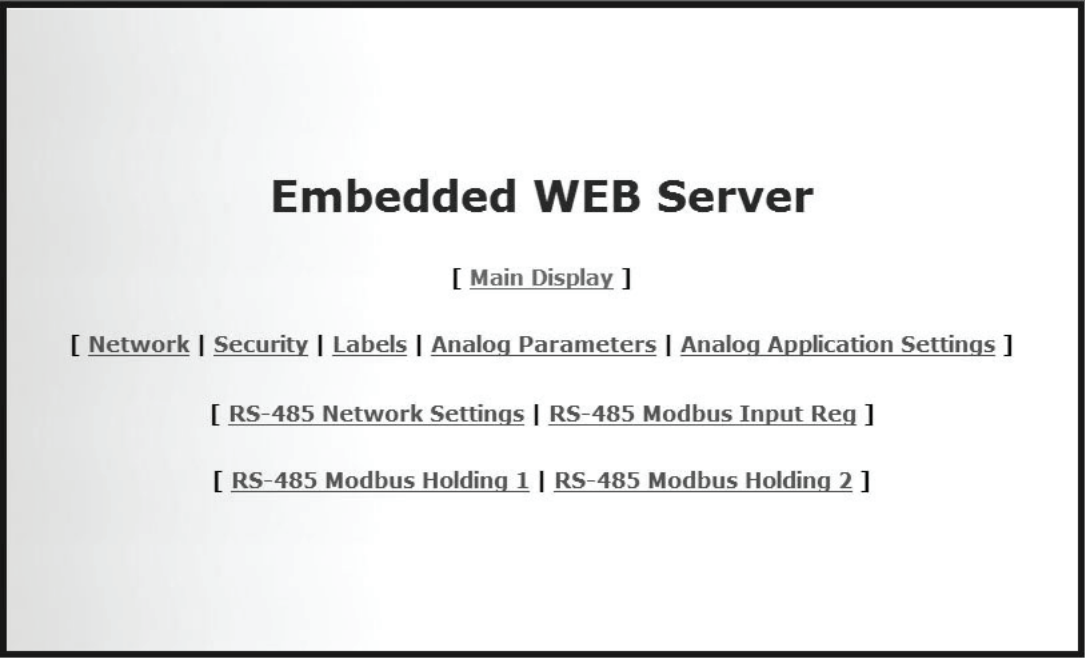


Figure 4.2

- **4-20 mA Sensor Input Configuration Submenus**

Analog Application Settings

Application Parameters		
Parameters	Information	Values
► Units	1=feet,2=inches,3=meters	2
► Decimal Place	0-3	2
► Full Distance	Not Used	0.0
► Empty Distance	Not Used	100.0
► Application Type	Value	0
► Volume Units	Not Used	1
► Tank Parameter 1	Not Used	0.0
► Tank Parameter 2	Not Used	0.0
► Tank Parameter 3	Not Used	0.0
► Tank Parameter 4	Not Used	0.0
► Tank Parameter 5	Not Used	0.0

Change
Refresh
Home

Figure 4.3

The Application Parameters menu configures the application-specific parameters applied to the calculated reading from the 4-20 mA sensor.

PARAMETER	RANGE
<i>Units</i>	1 - feet 2 - inches 3 - meters

Units is used to select the units of measurement for distance or level applications. The units will also determine the resolution of *Calculated Units*, *4ma Value*, *20ma Value*, *Window*, *Current Reading* (See Figure 4.5), and all of the Application Parameters (See Figure 4.3). The resolution is: feet 0.01, inches 0.1, and meters 0.001.

PARAMETER	RANGE
<i>Decimal Place</i>	0 - 0 1 - 0.1 2 - 0.01 3 - 0.001

Decimal Place sets the resolution of *Calc. Dist, Level, Volume* (See Figure 4.5). This resolution is also used *Trip Values* and *Trip Windows*, and the reading on Main Display Page (See Figure 4.1).

PARAMETER	RANGE
<i>Full Distance</i>	0 - Sensor Maximum

Full Distance sets the distance from the sensor *Reference Position* (See Figure 4.5) to the full level of the vessel being monitored. Not used when Application Type is set to 0 Value.

PARAMETER	RANGE
<i>Empty Distance</i>	0 - Sensor Maximum

Empty Distance sets the distance from the sensor *Reference Position* (See Figure 4.5) to the empty level of the vessel being monitored. Not used when Application Type is set to 0 Value.

PARAMETER	RANGE
<i>Application Type</i>	0 = Value (Distance) 1 = Level 2 = Volume of Standing Cylindrical Tank with or without Hemispherical Bottom 3 = Volume of Standing Cylindrical Tank with or without Conical Bottom 4 = Volume of Standing Rectangular Tank with or without Chute Bottom 5 = Volume of Horizontal Cylindrical Tank with or without Spherical Ends 6 = Volume of Spherical Tank 7 = Pounds (Linear Scaling) 8 = User Defined Units 9 = Volume of Vertical Oval Tank 10 = Volume of Horizontal Oval Tank

Application Type is used to choose the parameter configuration to convert the distance/value of *Calculated Units* into *Calc. Dist, Level, Volume*. After selecting an Application Type and pressing "Change," the Application Parameters menu updates to reflect the parameters of the chosen application (Compare Figure 4.3 and Figure 4.4).

See *Tank Parameters* for an explanation of each *Application Type* and its associated parameters.

Application Parameters		
Parameters	Information	Values
► Units	1=feet,2=inches,3=meters	2
► Decimal Place	0-3	2
► Full Distance	0.0-100,000.0 Inches	0.0
► Empty Distance	0.0-100,000.0 Inches	100.0
► Application Type	StandCylTank CBottom	3
► Volume Units	Feet^3	1
► Tank Parameter 1	Tank Diameter Inches	0.0
► Tank Parameter 2	Cone Diameter (at bottom of cone) Inches	0.0
► Tank Parameter 3	Cone Length Inches	0.0
► Tank Parameter 4	Not Used	0.0
► Tank Parameter 5	Not Used	0.0

Figure 4.4

PARAMETER	RANGE
<i>Volume Units</i>	1 = Feet ³ 2 = Million Feet ³ 3 = Gallons 4 = Meters ³ 5 = Liters 6 = Inches ³ 7 = Barrels

Volume Units selects the units of measure for *Calc. Dist,Level,Volume* when a volumetric application is selected. The settings is not used when the Application Type is set to 0, 1, 7, or 8.

Tank Parameters

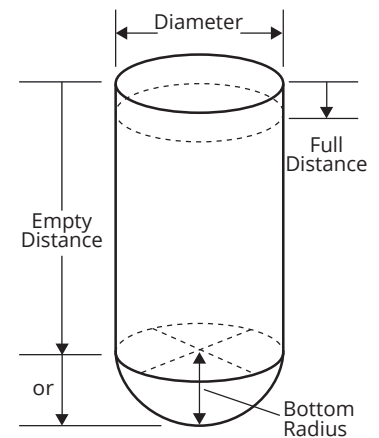
Application Type	Tank Parameter	Function
0 - Value (Distance)	Parameter 1	Not Used
	Parameter 2	Not Used
	Parameter 3	Not Used
	Parameter 4	Not Used
	Parameter 5	Not Used

Value (Distance) calculates *Calc. Dist, Level, Volume* using only the *4ma Value* and *20ma Value* settings. The result is a linear value or distance measurement.

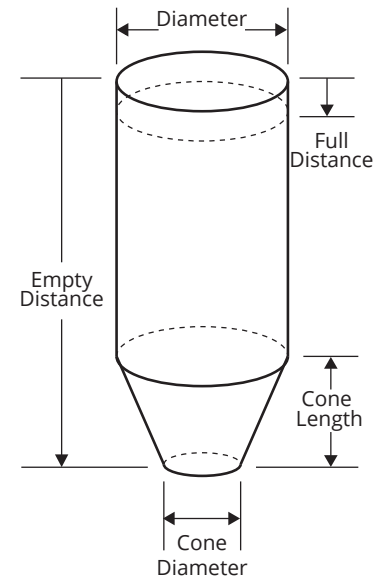
Application Type	Tank Parameter	Function
1 - Level	Parameter 1	Not Used
	Parameter 2	Not Used
	Parameter 3	Not Used
	Parameter 4	Not Used
	Parameter 5	Not Used

Level calculates *Calc. Dist, Level, Volume* using only the *4ma Value* and *20ma Value* settings, just as *Value (Distance)* does. The difference is that *Level* allows for the definition of *Full Distance* and *Empty Distance*, which then creates a display for percentage of level on the remote website.

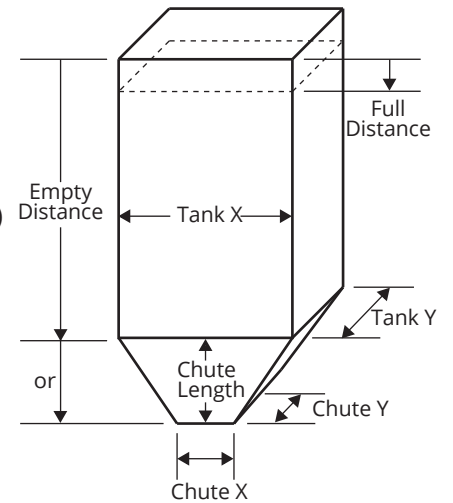
Application Type	Tank Parameter	Function
2 - Standing Cylindrical Tank with Hemispherical Bottom	Parameter 1	Tank Diameter
	Parameter 2	Bottom Radius
	Parameter 3	Not Used
	Parameter 4	Not Used
	Parameter 5	Not Used



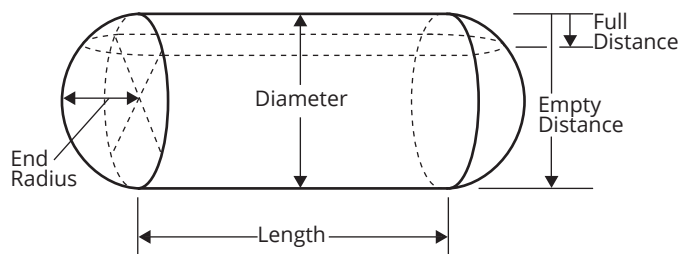
Application Type	Tank Parameter	Function
3 - Standing Cylindrical	Parameter 1	Tank Diameter
Tank with	Parameter 2	Bottom Radius
Conical	Parameter 3	Cone Length (Height)
Bottom	Parameter 4	Not Used
	Parameter 5	Not Used



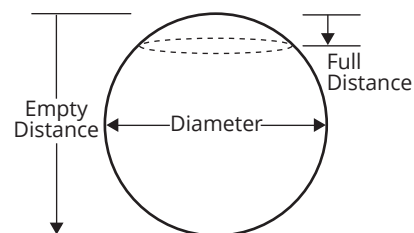
Application Type	Tank Parameter	Function
4 - Standing Rectangular	Parameter 1	Tank X Dimension
Tank with	Parameter 2	Tank Y Dimension
Chute	Parameter 3	Chute X Dimension
	Parameter 4	Chute Y Dimension
	Parameter 5	Chute Length (Height)



Application Type	Tank Parameter	Function
5 - Horizontal Cylindrical Tank with Spherical Ends	Parameter 1	Tank Length
	Parameter 2	Tank Diameter
	Parameter 3	Radius of Ends
	Parameter 4	Not Used
	Parameter 5	Not Used



Application Type	Tank Parameter	Function
6 - Spherical Tank	Parameter 1	Tank Diameter
	Parameter 2	Not Used
	Parameter 3	Not Used
	Parameter 4	Not Used
	Parameter 5	Not Used



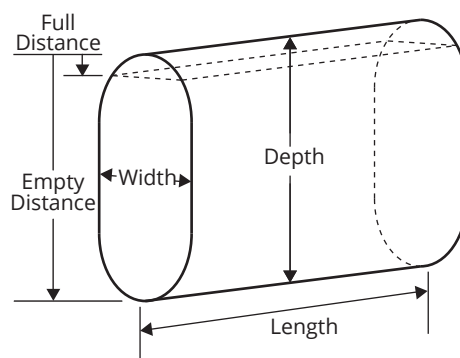
Application Type	Tank Parameter	Function
7 - Pounds (Linear Scaling)	Parameter 1	Multiplier
	Parameter 2	Unit Definition (label)
	Parameter 3	Not Used
	Parameter 4	Not Used
	Parameter 5	Not Used

Pounds allows for a multiplier (*Parameter 1*) to be applied to the *Calculated Units*, creating a linear scalar as the output to *Calc. Dist,Level,Volume*. Such a multiplier could convert the distance or level measurement of a tank with simple geometry into a measurement of weight.

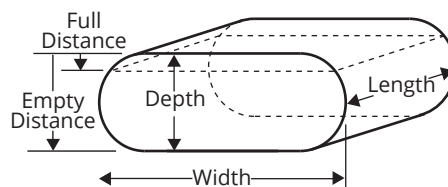
Application Type	Tank Parameter	Function
8 - User Defined Units	Parameter 1	Not Used
	Parameter 2	Unit Definition (label)
	Parameter 3	Not Used
	Parameter 4	Not Used
	Parameter 5	Not Used

User Defined Units allows the user to set custom units for the output to *Calc. Dist, Level, Volume*. The label for the custom units is stored in *Parameter 2*, and is applied to the the *4ma Value* and *20ma Value* settings, which are used to calculate the value.

Application Type	Tank Parameter	Function
9 - Vertical Oval Tank	Parameter 1	Tank Length
	Parameter 2	Tank Depth
	Parameter 3	Tank Width
	Parameter 4	Not Used
	Parameter 5	Not Used



Application Type	Tank Parameter	Function
10 - Horizontal Oval Tank	Parameter 1	Tank Length
	Parameter 2	Tank Depth
	Parameter 3	Tank Width
	Parameter 4	Not Used
	Parameter 5	Not Used



Analog Parameters

Analog Parameters						
Parameters	Information	Values		Parameters	Information	Values
▶ Reference Position	Not Used	0		▶ Trip1 Value	0-10,000.00	10.00
▶ 4ma Value	0.0-100,000.0 Inches	0.0		▶ Trip1 Window	0-10,000.00	10.00
▶ 20ma Value	0.0-100,000.0 Inches	1000.0	Change	▶ Trip1 Type Input	(18,28,30) 28=Alarm on OFF Trip Input	28
▶ 4ma Calibration	0 to 4095	825		▶ Trip2 Value	0-10,000.00	10.00
▶ 20ma Calibration	0 to 4095	4095		▶ Trip2 Window	0-10,000.00	10.00
▶ Average	1 to 32	20	Undo	▶ Trip2 Type Input	(18,28,30) 28=Alarm on OFF Trip Input	28
▶ Window	0.0-100,000.0 Inches	20.0				
▶ Out of Range Samples	0 to 250	20		▶ Retry Time	30 to 180 Seconds	30
▶ Sample Rate	1 to 15 Hertz	10				
				▶ Remote Call in Time	1 to 86400 Seconds	600
				▶ Remote Bytes	8 or 240	8
▶ Calculated Units	0.0-100,000.0 Inches	270.0				
▶ Calc Dist,Level,Volume	Inches	270.03	Refresh	▶ Current Reading	4.00 to 20.00 milliamps	8.32
▶ Trip1 Status	Green=ON Red=OFF	Trip1 ON	Home	▶ Trip2 Status	Green=ON Red=OFF	Trip2 ON

Figure 4.5

PARAMETER	RANGE
<i>Reference Position</i>	1 = Top 0 = Bottom 0 = Not Used

Reference Position defines the zero-reference point of the sensor in relation to the vessel being monitored. Ultrasonic sensors measure from the top down and submersible pressure transducers measure from the bottom up. MPX magnetostrictive sensors and non-submersible pressure sensors do not use a top or bottom reference point. *Reference Position* is not used when *Application Type* is set to 0 Value (See Figure 4.3).

i IMPORTANT: Parameter values stored on the RST-5003 will not update until the "Change" button is clicked.

PARAMETER	RANGE
<i>4ma Value</i>	0 - Sensor Max Distance

4ma Value assigns the RST-5003 distance output corresponding to the output of 4 mA from the sensor.

PARAMETER	RANGE
<i>20ma Value</i>	0 - Sensor Max Distance

20ma Value assigns RST-5003 distance output corresponding to the output of 20 mA from the sensor.

NOTE: For ultrasonic sensors only:
 For Distance configuration (i.e., to interpret a greater mA output as a target surface further from sensor), set the *4ma Value* to be less than the *20ma Value*.
 For Fill configuration (i.e., to interpret a greater mA output as a target surface closer to sensor), set the *4ma Value* to be greater than the *20ma Value*. See Figure 4.6.

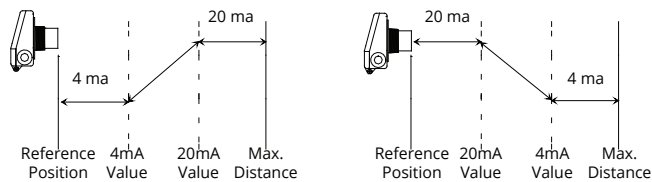


Figure 4.6

PARAMETER	RANGE
<i>4ma Calibration</i>	0 - 4095 Default: 825

4ma Calibration fine tunes the amount of recieved signal interpreted by the RST-5003 as the 4 mA signal.

PARAMETER	RANGE
<i>20ma Calibration</i>	0 - 4095 Default: 4095

20ma Calibration fine tunes the amount of recieved signal interpreted by the RST-5003 as the 20 mA signal.

PARAMETER	RANGE
<i>Average</i>	1-32

Average sets the number of qualified samples to average for the displayed reading. Qualified samples are placed in a first-in, first-out buffer, the contents of which are averaged for *Calculated Units*. The larger the number of qualified samples being averaged, the smoother the output reading will be, and the slower the reading will be to react to quick changes.

PARAMETER	RANGE
<i>Window</i>	0 - Sensor Maximum

Window determines the corresponding physical range for qualified samples, based on the current *Calculated Units*. Samples beyond the +/- *Window* range of the current *Calculated Units* will not qualify unless the average moves. Samples outside the extents of the *Window* are written to the *Out of Range Samples* buffer. (See Figure 4.7.)

PARAMETER	RANGE
<i>Out of Range Samples</i>	0-250

Out of Range Samples sets the number of consecutive samples outside the *Window* necessary to automatically adjust the current *Calculated Units* and move the *Window*.

PARAMETER	RANGE
<i>Sample Rate</i>	1 - 15 Hz

Sample Rate is the number of samples of the sensor output taken by the RST-5003 every second.

Example:
Window = 6 Inches
Out of Range Samples = 10

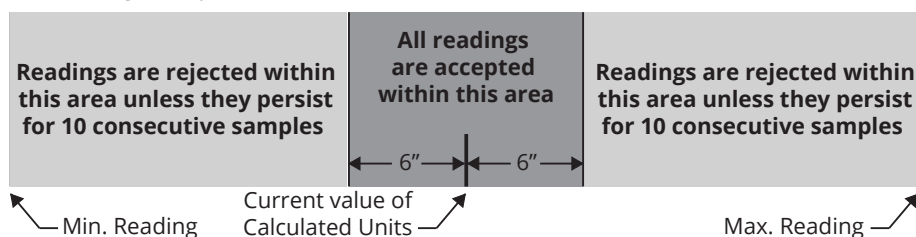


Figure 4.7

Analog Calculated Displays

► Calculated Units	0.0-100,000.0 Inches	270.0
► Calc Dist,Level,Volume	Inches	270.03

Figure 4.8

DISPLAY	RANGE
<i>Calculated Units</i>	Determined by <i>Units</i>

Calculated Units displays the "raw" reading--converted from the *Current Reading* (See Figure 4.15) from the sensor, based on the *4ma Value* and *20ma Value* settings--using the decimal places determined by the *Units* (See Figure 4.3). *Calculated Units* functions as the midpoint for *Window*.

DISPLAY	RANGE
<i>Calc. Dist,Level,Volume</i>	

Calc. Dist,Level,Volume displays the output calculated from *Calculated Units* using the Application Parameters (See Figures 4.3 and 4.4). *Calc. Dist,Level,Volume* is the evaluation basis for Trip settings (see Figures 4.9 and 4.11) and shows as the Reading on the Main Display Page (See Figure 4.1).

Analog-to-SS-Relay Trip Outputs and Settings

▶ Trip1 Value	0.00-50.00 Feet	2.50
▶ Trip1 Window	0.00-50.00 Feet	1.00
▶ Trip1 Type Output	(0 to 29) 0=Near	0
▶ Trip2 Value	0.00-50.00 Feet	3.00
▶ Trip2 Window	0.00-50.00 Feet	1.00
▶ Trip2 Type Output	(0 to 29) 0=Near	0

Figure 4.9

▶ Trip1 Status	Green=ON Red=OFF	Trip1 ON	Home	▶ Trip2 Status	Green=ON Red=OFF	Trip2 ON
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Figure 4.10

The RST-5003 and RST-5013 have output relays that can be configured to turn on or off based on the *Calc. Dist, Level, Volume* of the sensor.

Trip Type Outputs are configured with two independent digits: the first for Alarm Type (Blank, 1, or 2), and the second for Trip Condition (0-5, 7, or 9).

PARAMETER	RANGE
<i>Trip Value</i>	0 - Sensor Max Distance

Trip Value sets the value of the primary trip position, which is closest to the *Reference Position* of the sensor.

PARAMETER	RANGE
<i>Trip Window</i>	0 - Sensor Max Distance

Trip Window sets the value from the primary trip position to the secondary trip position, which is farther from the sensor's *Reference Position*.

Alarm Type
<i>Blank_</i> - No Alarm

Designates that no alarm is to be activated or deactivated on the remote provided website for the indicated Trip Condition. To initiate only the visual Trip Status indicator (See Figure 4.10) for Trip Condition 3, *Trip Type* would be set to **3**.

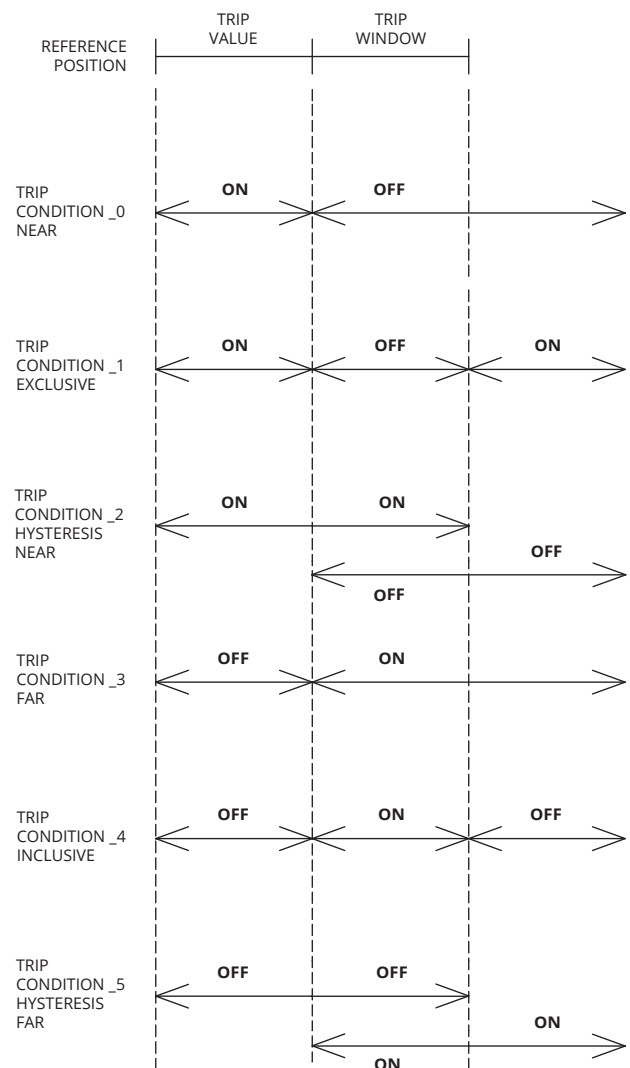


Figure 4.11

Alarm Type

1_ - Active Alarm

Designates the active trip point as a web alarm condition. To initiate web alarm whenever the Trip Condition 3 is ON, *Trip Type* would be set to **13**.

Alarm Type

2_ - Inactive Alarm

Designates an inactive trip point as a web alarm condition. To initiate a web alarm whenever the Trip Condition 3 is OFF, *Trip Type* would be set to **23**.

Trip Condition

0 - Near

Near activates the Trip whenever the *Calc. Dist,Level,Volume* is less than the *Trip Value* setting.

Trip Condition

1 - Exclusive

Exclusive activates the Trip whenever the *Calc. Dist,Level,Volume* is less than the *Trip Value* setting OR greater than the *Trip Value + Trip Window* settings.

Trip Condition

2 - Hysteresis Near

Hysteresis Near activates the Trip whenever the *Calc. Dist,Level,Volume* becomes less than than the *Trip Value* setting. The Trip remains activated until the *Calc. Dist,Level,Volume* becomes greater than the *Trip Value + Trip Window* settings. The Trip remains off until the *Calc. Dist,Level,Volume* becomes less than the *Trip Value* setting again.

Trip Condition

3 - Far

Far activates the Trip whenever the *Calc. Dist,Level,Volume* is greater than the *Trip Value* setting.

Trip Condition

4 - Inclusive

Inclusive activates the Trip whenever the *Calc. Dist,Level,Volume* is greater than the *Trip Value* setting AND less than the *Trip Value + Trip Window* settings.

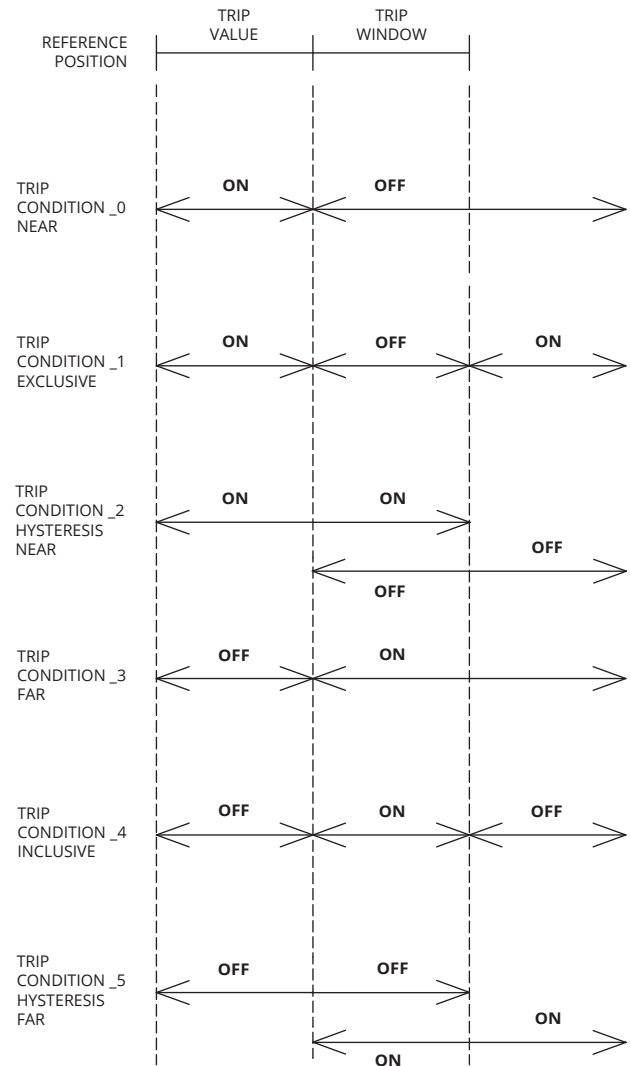


Figure 4.11

Trip Condition

5 - Hysteresis Far

Hysteresis Far activates the Trip whenever the *Calc. Dist,Level,Volume* becomes greater than the *Trip Value + Trip Window* settings. The Trip remains activated until the *Calc. Dist,Level,Volume* becomes less than the *Trip Value* setting. The Trip remains off until the *Calc. Dist,Level,Volume* becomes greater than the *Trip Value + Trip Window* settings again.

Trip Condition

6 - Disable Trip

16 - Disable Relay

26 - N/A

Disable de-activates the Trip or SS Relay output.

Trip Condition

7 - Loss of Echo

Loss of Echo activates the output when the maximum calculated reading (i.e., the greater of *4ma Value* and *20ma Value*, see Figure 4.6) is reached.

Trip Condition

8 - Timed Interval

Timed Interval activates the output for a set amount of seconds every set amount of minutes (See Figure 4.12). When Trip Type is set to 8, Trip Value and Trip Window are changed to "Interval Time (minutes)" and "On Time (seconds)".

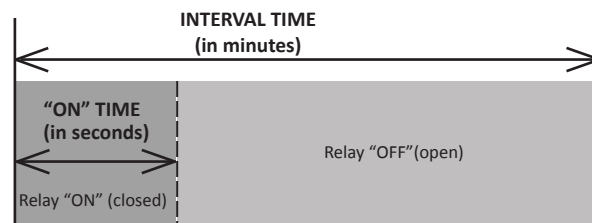


Figure 4.12

Trip Condition

9 - Abrupt Change

Abrupt Change activates the output whenever a user-defined maximum rate of level change (change in distance or level divided by elapsed time) is exceeded. *Trip Value* defines the distance and *Trip Window* defines the time.

Switched Input Alarms (RST-5013 and RST-5113 only)

► Trip1 Value	0-10,000.00	10.00
► Trip1 Window	0-10,000.00	10.00
► Trip1 Type Input	(18,28,30) 28=Alarm on OFF Trip Input	28
► Trip2 Value	0-10,000.00	10.00
► Trip2 Window	0-10,000.00	10.00
► Trip2 Type Input	(18,28,30) 28=Alarm on OFF Trip Input	28

Figure 4.13

The RST-5013 and RST-5113 have switched inputs (one and two, respectively) designed to continuously monitor the status of a simple switch or contact closure. The RST can be configured to alarm on either an open or closed input, and will immediately report to the remote provided website, regardless of the call-in interval, whenever an alarm condition is detected. The following are the three configuration options for the switched input:

Input Alarm/Trip Type

18 - Closed Input Alarm

Closed Input Alarm activates the alarm when the input switch or contact closes.

Input Alarm/Trip Type

28 - Open Input Alarm

Open Input Alarm activates the alarm when the input switch or contact opens.

Input Alarm/Trip Type

30 - On Time Check Limit Alarm

On Time Check Limit Alarm will immediately report to the remote website whenever the input remains continuously closed beyond the user specified time limit (in seconds, as set in the *Trip Value* parameter). The RST will report to the website a second time once the alarm condition clears.

i **IMPORTANT:** Inputs are NOT designed to monitor switches controlling a voltage or electrical signal. The inputs are designed to detect continuity at the closure of un-powered contacts.

External Website Communication Status

▶ Retry Time	30 to 180 Seconds	30
▶ Remote Call in Time	1 to 86400 Seconds	600
▶ Remote Bytes	8 or 240	8

Figure 4.14

The RST-5003 embedded web server includes one parameter and two status reports for communication with the remote provided website.

PARAMETER	RANGE
<i>Retry Time</i>	30 - 180 Seconds

Retry Time sets the time delay (in seconds) between attempts by the RST-5003 to contact the external website.

DISPLAY	RANGE
<i>Remote Call in Time</i>	1 - 86400 Seconds

Remote Call in Time displays the duration of the last communication between the RST-5003 and the external website.

DISPLAY	RANGE
<i>Remote Bytes</i>	8 or 240 Bytes

Remote Bytes displays the number of bytes of data sent in the last communication between the RST-5003 and the external website. 8 bytes indicates a normal, successful transmission. 240 bytes indicates an error occurred in the transmission.

Analog Sensor Current Reading

▶ Current Reading	4.00 to 20.00 milliamps	8.32
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Figure 4.15

DISPLAY	RANGE
<i>Current Reading</i>	4.00 - 20.00 milliamps

Current Reading displays the current 4-20 mA reading from the analog sensor. The RST converts this reading to a distance/value measurement based on the *4ma Value* and *20ma Value* settings (See Figure 4.6). This converted "raw" reading (*Calculated Units*) is the basis for the *Window* function, rather than the 4-20 mA reading from the sensor (See Figure 4.7).

- **Modbus Sensor Configuration Registers**

RS-485 Modbus Input Registers

Modbus Input Registers Sensor #1 Comm Good		
Address	Value	Definition
30299	6	Sensor Type
30300	1767	Distance/level 1 (Top)
30301	0	Distance/level 2 (Bottom)
30302	21	Temperature C
30303-30304	69.566	Volume 1 Data
30305-30306	0.000	Volume 2 Data
30307	3	Version Number
30307	0	Signal Strength
30308	NA	Sensor Voltage
30309	Relay Off Alarm Off	Trip 1 Status
30310	Relay Off Alarm Off	Trip 2 Status
Refresh		Home

Figure 4.16

This display-only menu shows the contents of the Input Registers for the selected Modbus sensor (See Figure 4.1). Registers used vary by sensor. Please see the user manual for each sensor for a full list of registers.

- Sensor Type Number and Sensor Model Number List:

Type Number	Model Number	Type Number	Model Number
0	LOE-2126	9	PT-400/PT-500-L31 (Level)
1	LOE-6126	10	PT-400/PT-500-L5 (Pressure)
2	LOE-3136	11	DCR-1006A
3	LOE-7126	12	LPD
4	RST-5001	13	MND
5	MPX-E1/R1 (2 floats)	14	RST-5003/4
6	MPX-E1/R1 (1 float)	15	AUS-7123
7	PG-7	16	MTM-1000
8	PG-10		

Note: This list represents sensors that interface with various BinMaster Modbus software packages. Not all interface with the RST-5003.

RS-485 Modbus Holding 1

MODBUS Holding Registers 1 Sensor #1 Comm Good			
Address	Value	Definition	Value Restrictions
40401	2	Units	1=Feet 2=Inches 3=Meters
40402	0	Application Type = Distance	0=Distance 1=Level 2-7,9-11=Volume
40403	3	Volume Units = Gallons	1-7
40404	3	Decimal Place	0-3
40405	7620	Max Distance	0 to Max Distance mm
40406	304	Full Distance	0 to Max Distance mm
40407	2500	Empty Distance	0 to Max Distance mm
40408	100	Sensitivity	0-100
40409	20	Pulses	0-20
40410	300	Blanking	0 to Max Distance mm
40411	0	Gain Control	0-4
40412	2	Averaging / Response Time	0-20
40413	150	Filter Window	0 to Max Distance mm
40414	2	Out Of Range	0-255
40415	200	Sample Rate	10-1000
40416	1.011	Multiplier (Calibration)	0-1.999
40417	-10	Offset	-32000 to 32000 mm
40418	0	Fail Safe	0-2
40419	15	Fail Safe Delay	15-9999
40420	1	Temperature Compensation	0-1
<div> <div>Change</div> <div>Undo</div> <div>Refresh</div> <div>Home</div> </div>			

Figure 4.17

This menu shows the contents of the first set of Holding Registers for the selected Modbus sensor (See Figure 4.1). The register names and value restrictions are automatically configured for the type of sensor detected (See Figure 4.16). Because register name and use varies by sensor, including a full breakdown of the registers in this manual would be counterproductive. Please see the user manual for each sensor for a full list of registers.

RS-485 Modbus Holding 2

MODBUS Holding Registers 2 Sensor #1 Comm Good			
Address	Value	Definition	Value Restrictions
40421	0	RTD Offset	-100 C to 100 C
40422	0	Float Window	1-255
40423	0	1st Float Offset	-32000 to 32000 mm
40424	0	2nd Float Offset	-32000 to 32000 mm
40425	0	Gain Offset	0-255
40426	0	0 Volt / 4ma Set Point	0 to Max Distance mm
40427	0	5 Volt / 20ma Set Point	0 to Max Distance mm
40428	0	0 Volt / 4ma Calibration	0-4095
40429	0	5 Volt / 20ma Calibration	0-4095
40430	1000	Trip 1 Value	0 to Max Distance mm
40431	100	Trip 1 Window	0 to Max Distance mm
40432	6	Trip 1 Type	0-7
40433	2000	Trip 2 Value	0 to Max Distance mm
40434	200	Trip 2 Window	0 to Max Distance mm
40435	6	Trip 2 Type	0-7
40436-40437	0	Parameter 1 Data = Not Used	0-2147483647 mm
40438-40439	0	Parameter 2 Data = Not Used	0-2147483647 mm
40440-40441	0	Parameter 3 Data = Not Used	0-2147483647 mm
40442-40443	0	Parameter 4 Data = Not Used	0-2147483647 mm
40444-40445	0	Parameter 5 Data = Not Used	0-2147483647 mm
<div> <div>Change</div> <div>Undo</div> <div>Refresh</div> <div>Home</div> </div>			

Figure 4.18

This menu shows the contents of the second set of Holding Registers for the selected Modbus sensor (See Figure 4.1). The register names and value restrictions are automatically configured for the type of sensor detected (See Figure 4.16). Because register name and use varies by sensor, including a full breakdown of the registers in this manual would be counterproductive. Please see the user manual for each sensor for a full list of registers.


- **RST-5003 Utilty Menus**

Network Settings

Network Settings	
▶ LAN IP Address	10.1.5.33
▶ Remote IP Address	174.127.124.29
▶ Subnet Mask	255.255.0.0
▶ Default Gateway	10.1.1.1
▶ Primary DNS Server	10.1.3.1
▶ Secondary DNS Server	10.1.3.2
▶ MAC Address	0.33.218.0.1.77
▶ Port Number	6700
▶ External Website Access On	<input checked="" type="checkbox"/> Checked = On
▶ DHCP Success	<input checked="" type="checkbox"/> Checked = On
▶ Alarm Filter On	<input checked="" type="checkbox"/> Checked = On
▶ Domain Name	www.levelandflow.com
▶ Domain Name IP Address	"174.127.124.29"

Figure 4.19

The Network Settings are provided for advanced users only and should not normally require changes. Each RST ships with the DHCP enabled, which means it will automatically connect to the the provided remote website and configure its own Network Settings when plugged into a port providing direct internet access.

 **NOTE:** Port 6700 must be open on your local network for the RST-5003 to connect.

 **NOTE:** Please contact BinMaster for access to your remote access (external) website.

Security Settings

Security Settings		
▶ User Name	admin	
▶ Password	*****	
▶ Retype your password	*****	
Change	Undo	Home

Figure 4.20

The Security Settings allow users to set their own user name and password for logging into the embedded webpage.

Labels

Labels			
▶ Main Table Title			
▶ Analog Input Description			
▶ Modbus Sensor 1 Description			
Change	Undo	Refresh	Home

Figure 4.21

The Labels menu allow users to create custom labels for the Main Menu and the sensors attached to the RST-5003.

Labels

▶ Main Table Title	Mini Measure System
▶ Analog Input Description	4-20 Tank 1 Level
▶ Modbus Sensor 1 Description	Ultrasonic Tank 2 Level

Change
Undo
Refresh
Home

Mini Measure System			
Sensor #	Description	Reading	Units
Analog Input	4-20 Tank 1 Level	270.03	Inches
1	Ultrasonic Tank 2 Level	69.528	Inches
Refresh		Home	

Figure 4.22

When labels are created in the Labels menu, they will be reflected on the Main Menu page (See Figure 4.22).

RS-485 Network Settings

RS485 Settings

Definition	Range	Value
2400 Baud	Checked or UnChecked	<input type="checkbox"/> 2400 Baud
9600 Baud	Checked or UnChecked	<input checked="" type="checkbox"/> 9600 Baud
Numb of Sensors On Line	0 to 10	1 <input style="width: 50px;" type="text"/>
Sensor Number to View	1 to 10	1 <input style="width: 50px;" type="text"/>
New Sensor Number	0=No Change or 1 to 10	0 <input style="width: 50px;" type="text"/>
RS485 Sample Rate	1 to 20 Seconds	1 <input style="width: 50px;" type="text"/>

Change
Undo
Refresh
Home

Figure 4.23

The RS-485 (Modbus) Settings menu controls the settings for the Modbus sensors (up to 10) attached to the RST-5003.

PARAMETER	RANGE
<i>Baud Rate Checkboxes</i>	2400 Baud 9600 Baud

Baud Rate Checkboxes are used to select the baud rate of the of the sensors connected to the RST-5003. All APG Modbus sensors communicate at 9600 Baud.

PARAMETER	RANGE
<i>Numb of Sensors On Line</i>	0 - 10

Numb of Sensors On Line sets the number Modbus sensors connected to the RST-5003. This setting is not automatically populated or updated. The user must change the setting manually. *Numb of Sensors On Line* must always be equal or greater than the number of actual sensors attached to the RST-5003.



NOTE: For best results, set Numb of Sensors On Line to the highest number of number of sensor TO BE connected. No further adjustments will be needed as those sensors are connected to the RST-5003.

PARAMETER	RANGE
<i>Sensor Number to View</i>	1 - 10

Sensor Number to View selects number of the sensor for the RST-5003 to poll for populating the Main Menu and for editing parameters in the Modbus Holding Register menus.

PARAMETER	RANGE
<i>New Sensor Number</i>	0 = No Change 1 - 10

New Sensor Number changes the sensor number assigned to the sensor selected by *Sensor Number to View*.



IMPORTANT: When "Change" is pressed to assign a new sensor number, *Sensor Number to View* DOES NOT update.

PARAMETER	RANGE
<i>RS485 Sample Rate</i>	1 - 20 Seconds

RS485 Sample Rate determines how often the RST-5003 polls the selected Modbus sensor.

Chapter 5: Maintenance

- **General Care**

Your RST-5003 series controller is very low maintenance and will need little care as long as it was installed correctly. However, you should avoid applications for which the controller was not designed, such as extreme temperatures, contact with incompatible corrosive chemicals and fumes, or other damaging environments.

- **Repair and Returns**

Should your RST-5003 require service, please contact the factory via phone or email. We will issue you a Return Material Authorization (RMA) number with instructions.

- Phone: 402-434-9102
- Email: info@binmaster.com

Please have your RST-5003 part number and serial number available. See Warranty and Warranty Restrictions for more information.

